



pyIntensityFeatures

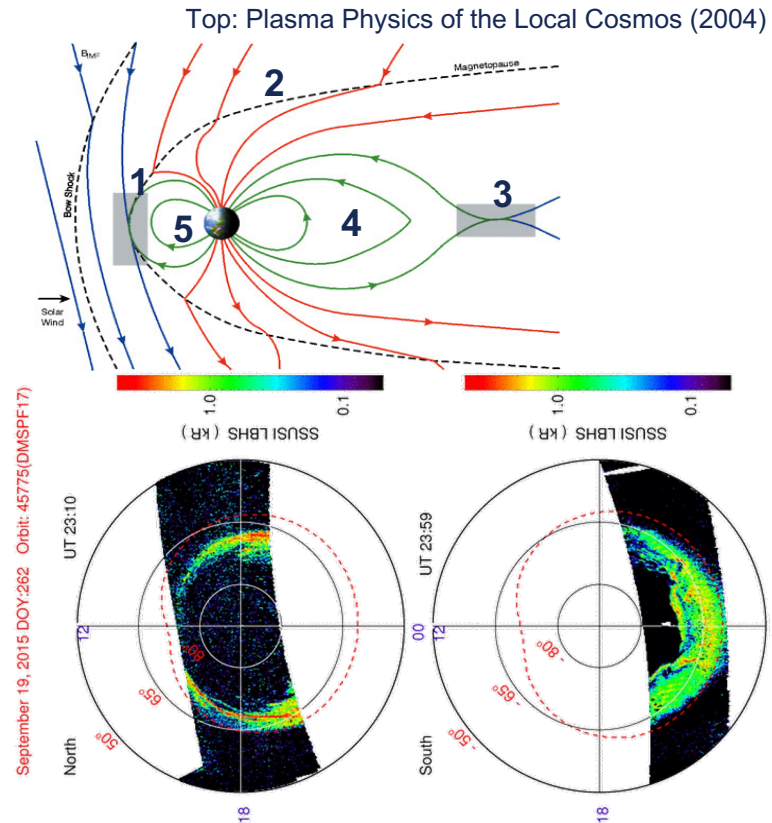
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(UMich)

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CEDAR 2026

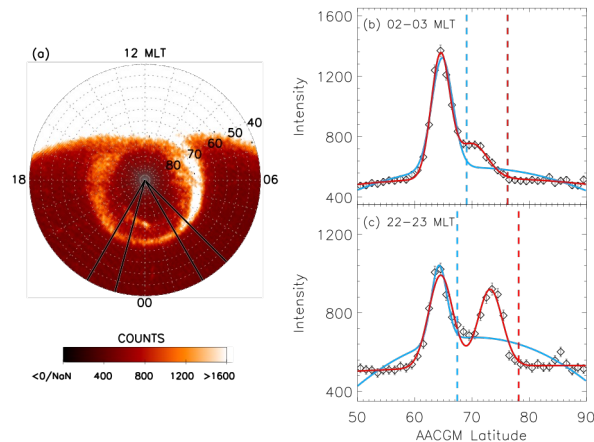
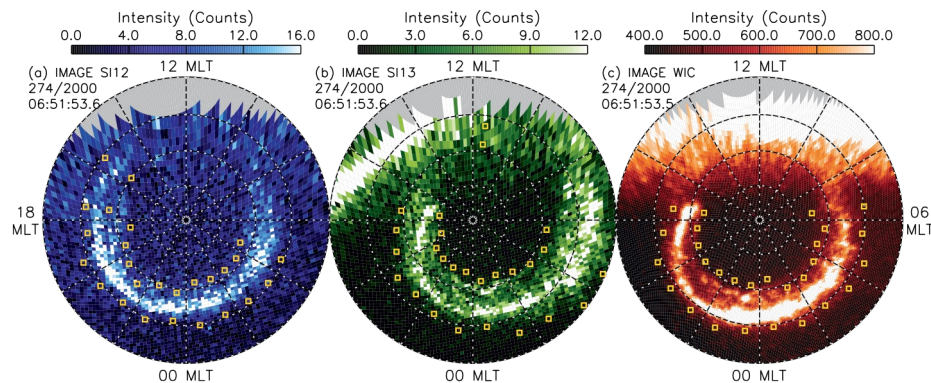
Motivation

- High latitude M-I coupling varies based on region:
 - Open field lines in the polar cap
 - Closed field lines in the auroral oval, high L-shells
 - Closed field lines below the auroral oval, low L-shells
- Gridding relative to the polar cap (Open-Closed field line Boundary, OCB) and auroral oval (Equatorward Auroral Boundary, EAB) can improve modelling and statistical studies
- Auroral boundary detections from space-based imagers are needed to improve these efforts
- Existing boundary information may not be suitable for scientific use



Starting Point for Auroral Luminosity Boundaries

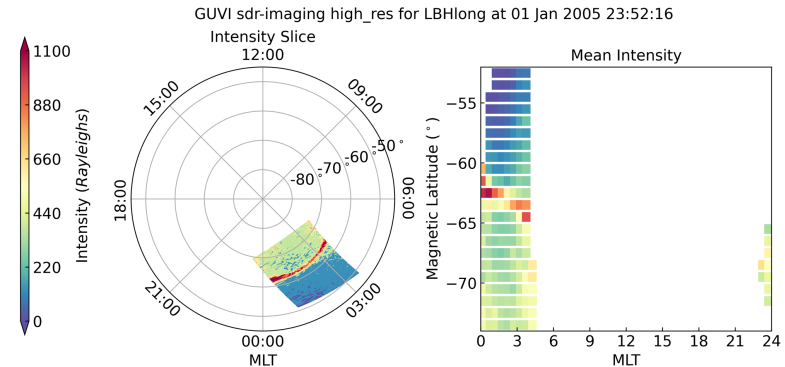
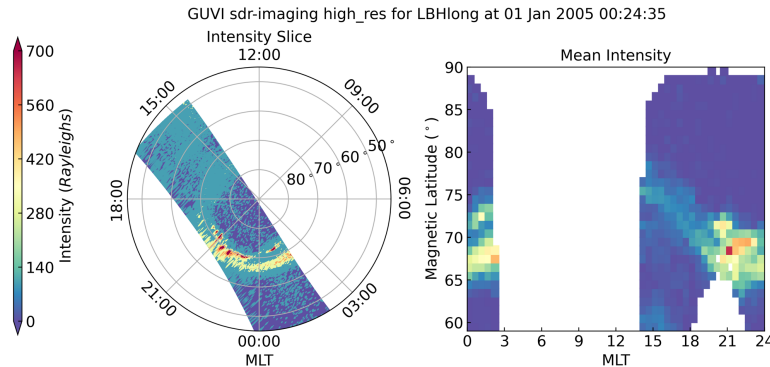
- IMAGE SI12, SI13, and WIC measured Ly- α , O, and LBH emission bands in the Northern hemisphere
- Chisham et al., 2022 found the polar and equatorward ALBs using the Longden et al., 2010 method
 - Used Newell DMSP boundaries to determine the offset between the ALB and precipitation boundaries
 - Fits to the offset boundaries agree well with the convection reversal boundary, providing confidence in the ALBs
- Used the IDL code developed by Longden as a base and generalize
 - Allow any number of multi-Gaussian fits
 - Added adaptive limits for partial-aurora scans
 - Added test for MLT consistency in boundary IDs



Methodology

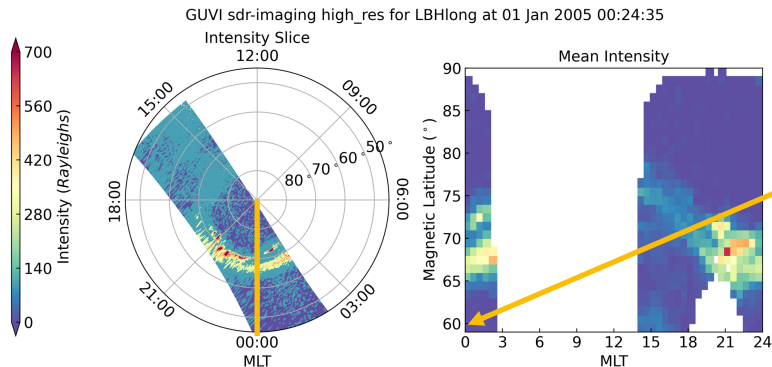
- Clean data as directed by the instrument team
- Identify a scan of intensity observations that contain the auroral oval in one hemisphere
- Separate the scan into MLT slices, for each slice:
 - Fit the intensity peaks (try multiple fits)
 - Identify the poleward and equatorward boundaries
 - Calculate boundary uncertainty
 - Evaluate the poleward and equatorward boundaries and select the best ones
- Evaluate the poleward and equatorward boundaries in each scan and remove outliers

Identify and Process a Scan



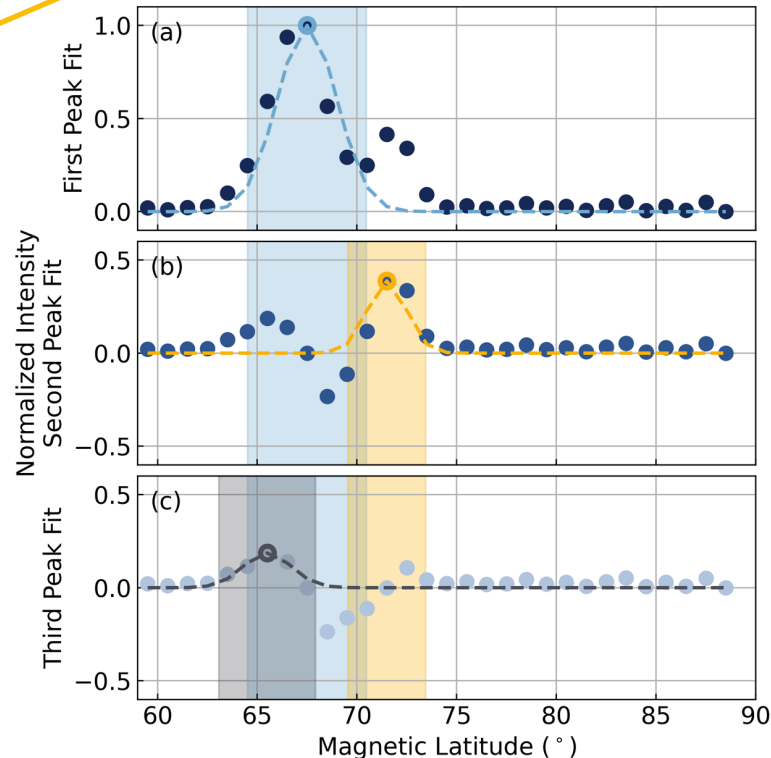
- Identify a “scan” of auroral data
 - ``pyIntensityFeatures.instruments.satellites.get_auroral_slice``
 - User provides arrays of time, latitude, longitude, and intensity data
 - Optionally specifies a start time and a mask to select clean data
 - User should provide hemisphere (assumes North) and a minimum co-latitude (assumes 45°)
 - Operates in geodetic coordinates
- Process the auroral scan to get MLT slices:
 - Create a grid in magnetic coordinates (package uses AACGMV2)
 - Get mean and standard deviation of the intensity at each magnetic latitude and local time (MLat, MLT)
 - Determine the magnetic latitude limits of the slice by finding the highest and lowest latitudes with data at all MLT

Process each MLT in the Scan



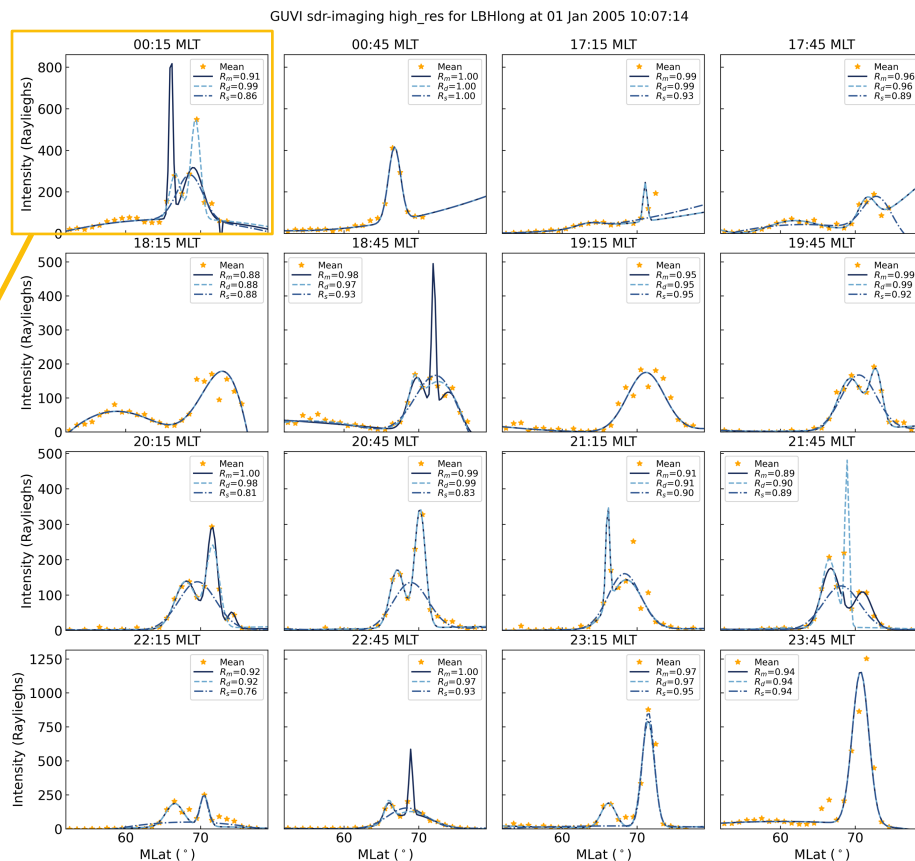
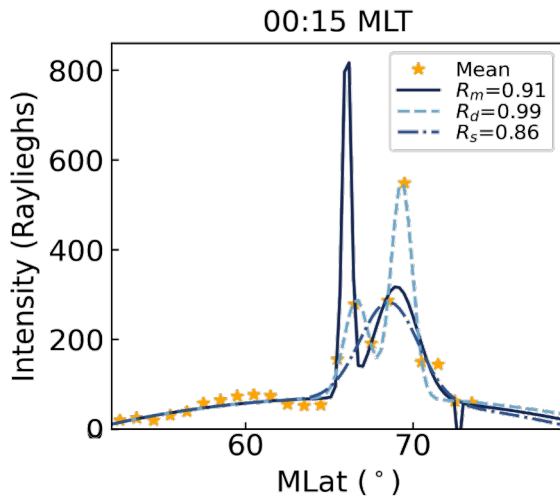
- For each MLT grid point, fit the intensity and find the poleward and equatorward boundaries
- Process:
 - Identify the maximum number of intensity peaks (up to three peaks)
 - Find peak intensity and standard deviation to initialize future fitting

Initial Parameter Estimation Using GUVI at 01 Jan 2005 00:24:35 UT, 00:15 MLT



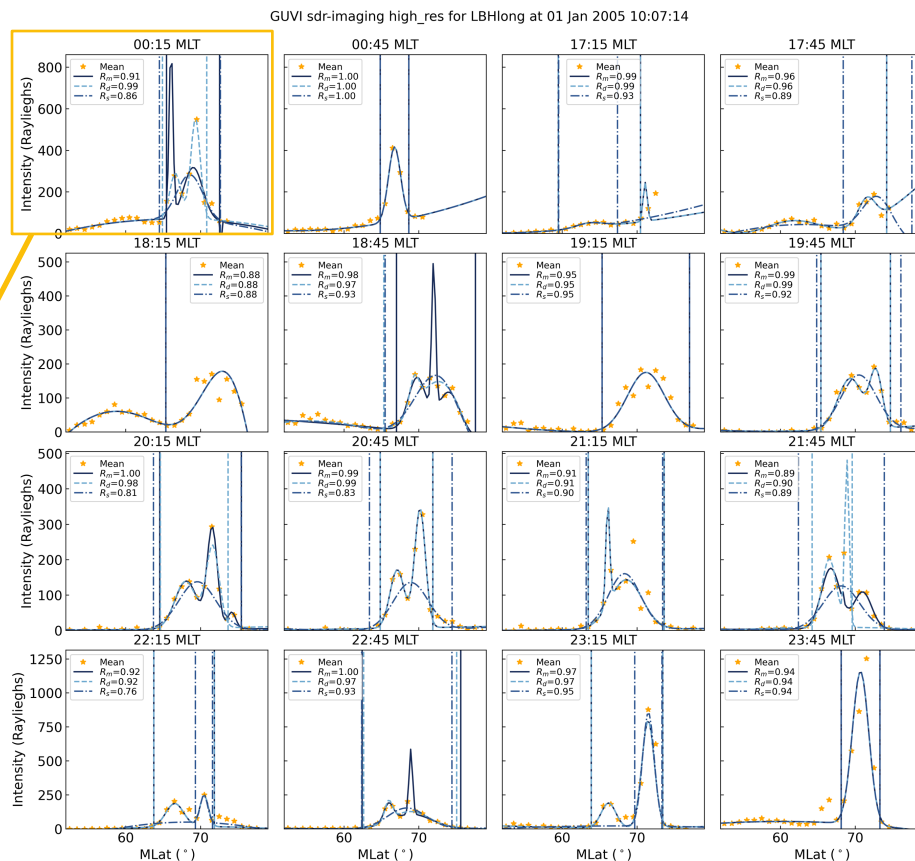
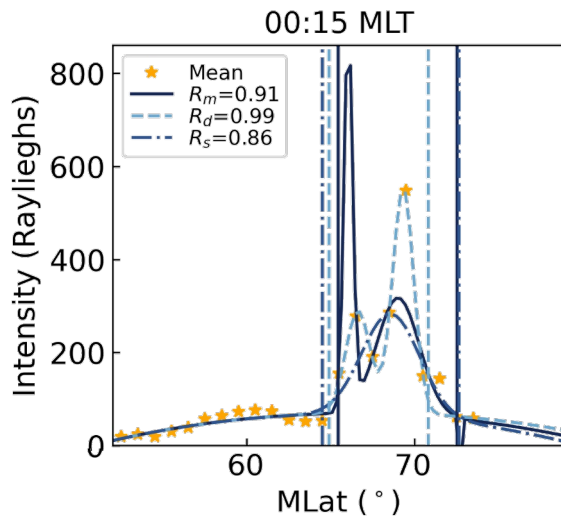
Process each MLT in the Scan

- Process (second time example):
 - Identify the maximum number of intensity peaks (up to three peaks)
 - Find peak intensity and standard deviation to initialize future fitting
 - Fit 1, 2, and 3 Gaussian peaks with a quadratic background
 - Quadratic background accounts for dayglow and noise



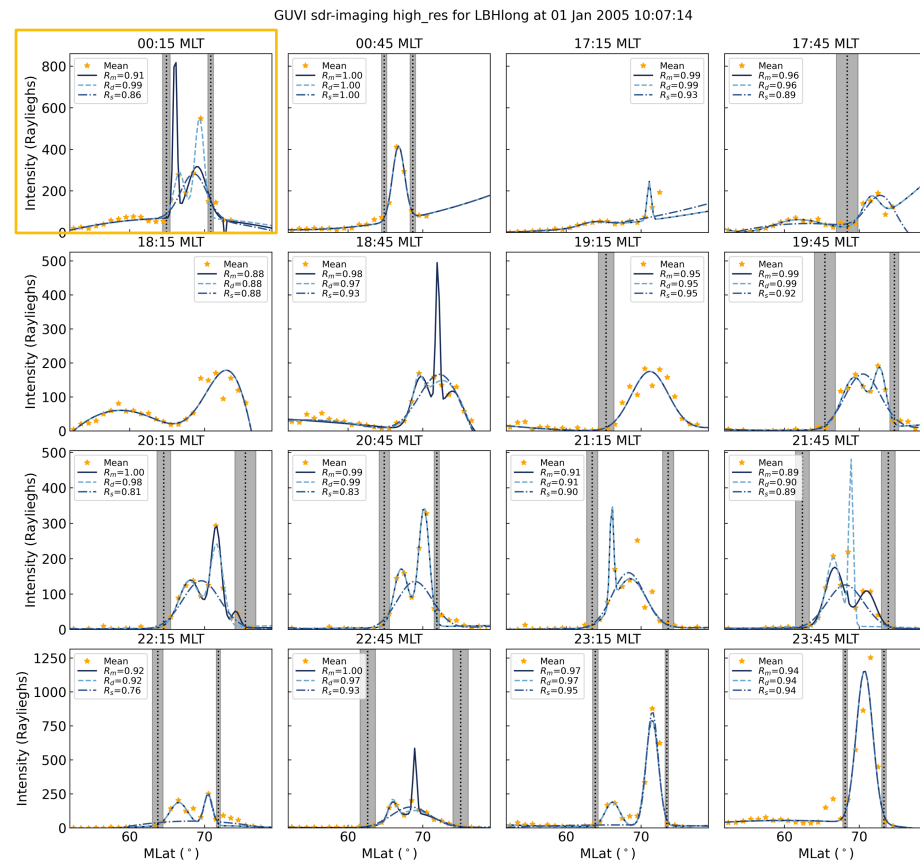
Process each MLT in the Scan

- Process (second time example):
 - Fit 1, 2, and 3 Gaussian peaks with a quadratic background
 - Find the poleward and equatorward boundaries for each fit
 - The boundary is the location 2σ from the most poleward/equatorward peak



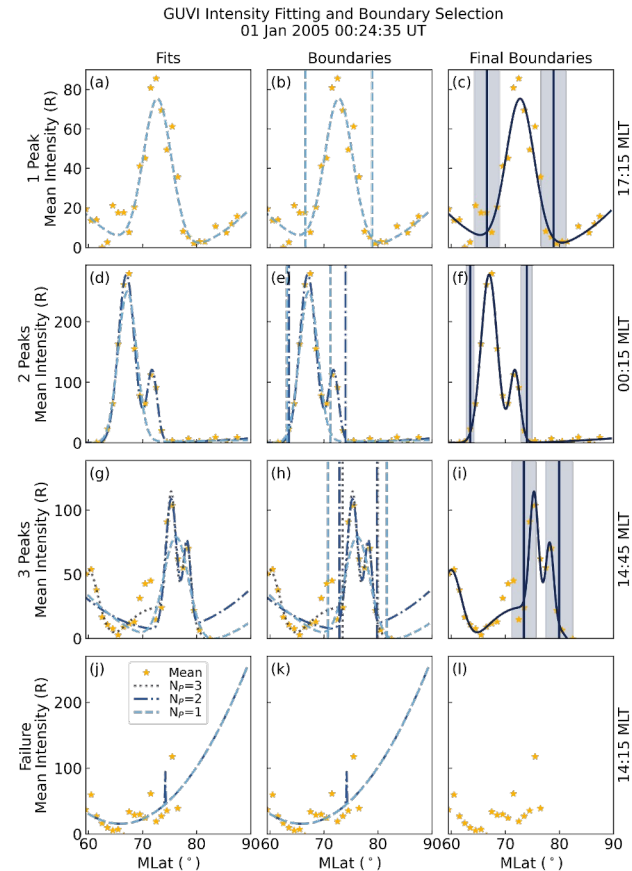
Process each MLT in the Scan

- Process (second time example):
 - Find the poleward and equatorward boundaries for each fit
 - Calculate boundary uncertainty using the uncertainties of the mean and standard deviation of the Gaussian peaks, as well as the covariance of the fitting
 - Recommend that user also accounts for the grid size in their final boundary uncertainties
 - Choose the best poleward and equatorward boundaries separately, based on their fit's Pearson correlation coefficient and the boundary uncertainty
 - Reject boundaries based on the background intensity, boundary uncertainty, location relative to a latitude limit



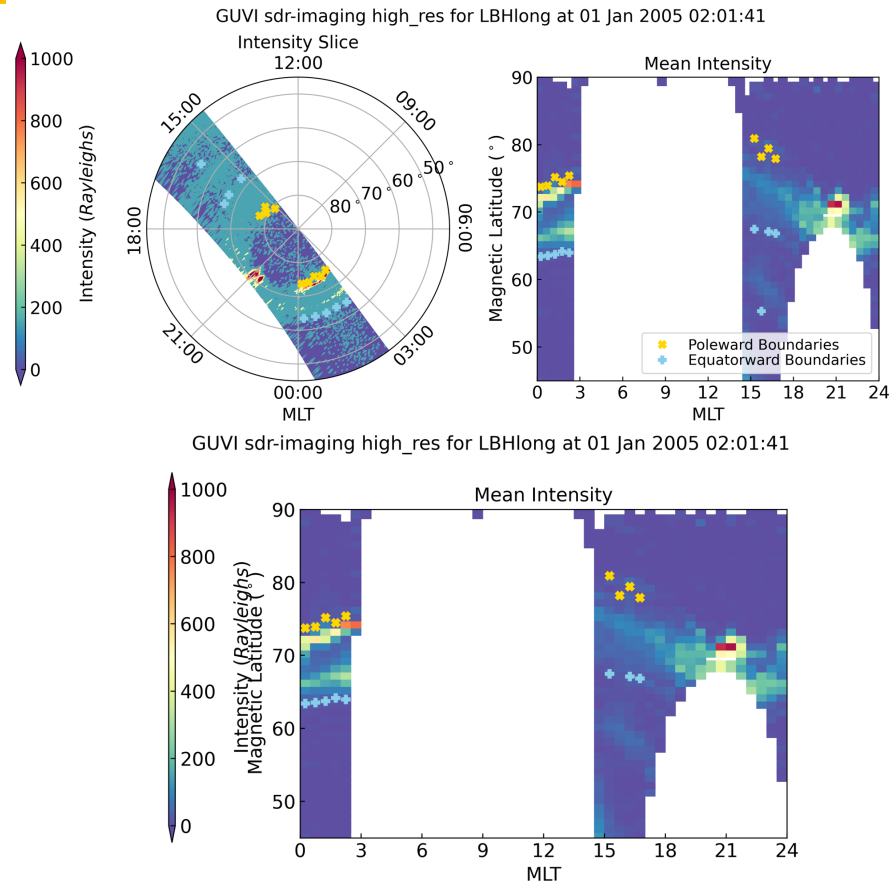
Process each MLT in the Scan

- Process (first time example):
 - Find the poleward and equatorward boundaries for each fit
 - Calculate boundary uncertainty using the uncertainties of the mean and standard deviation of the Gaussian peaks, as well as the covariance of the fitting
 - Recommend that user also accounts for the grid size in their final boundary uncertainties
 - Choose the best poleward and equatorward boundaries separately, based on their fit's Pearson correlation coefficient and the boundary uncertainty
 - Reject boundaries based on the background intensity, boundary uncertainty, location relative to a latitude limit



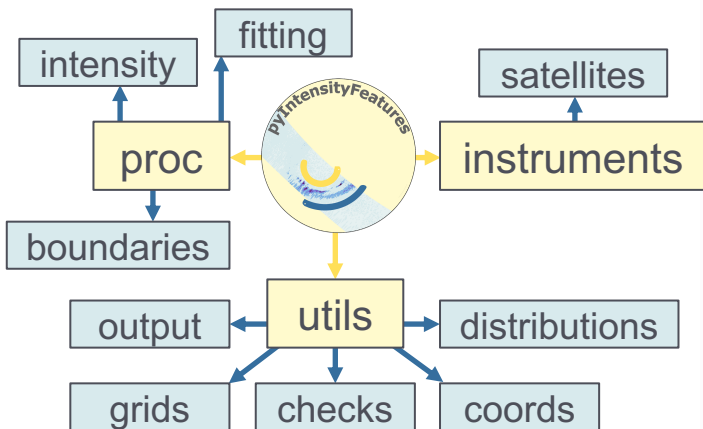
Consider all MLT in the Scan

- Process (first time example):
 - Choose the best poleward and equatorward boundaries based on their fit's Pearson correlation coefficient and the boundary uncertainty
 - Reject boundaries based on the background intensity, boundary uncertainty, location relative to a latitude limit
 - Identify outliers in 5 hr MLT bins using the Interquartile Range (IQR)
 - For full-auroral imagers, such as POLAR or IMAGE, consider using the entire MLT range



pyIntensityFeatures Usage

- Class-based user interface combines all steps needed to perform ALB identification and output data into a netCDF file
- Function access in sub-modules allows users to experiment with the best constraints for their data set



```
alb = pyIntensityFeatures.AuroralBounds({}, "time", "glat", "glon",
                                         "intensity", 110.0)
```

```
print(alb)
```

```
Auroral Boundary object
```

```
=====
```

```
Instrument Data: {}
```

```
Data Variables
```

```
=====
```

```
Time: time
```

```
Geo Lon: glat
```

```
Geo Lat: glon
```

```
Intensity: intensity
```

```
Transpose: {'glat': False, 'glon': False, 'intensity': False}
```

```
Coordinate Attributes
```

```
=====
```

```
Hemisphere: 1
```

```
Altitude: 110.00 km
```

```
Optional coords: {'hemisphere': 1}
```

```
Start time: None
```

```
End time: None
```

```
Instrument Functions
```

```
=====
```

```
Slicing: functools.partial(<function get_auroral_slice at 0x1391d1550>)
```

```
Cleaning: None
```

pyIntensityFeatures Future

- Ground-based observations (All-Sky Imagers) may also be worth incorporating
- Similar algorithms may be useful for identifying other intensity features in observations
 - New classes allow vetted identification algorithms to be added to the main package
 - Potential extensions include:
 - Travelling Ionospheric Disturbances (TIDs)
 - Equatorial Ionization Anomaly (EIA)
 - Equatorial Plasma Bubbles (EPBs)

Summary

- Find `pyIntensityFeatures` on GitHub
 - <https://github.com/aburrell/pyIntensityFeatures>
- Documentation available on ReadTheDocs with examples for using main class and functions
 - <https://pyintensityfeatures.readthedocs.io/en/latest/?badge=latest>
- Publication in JGR: Space Physics goes over more details of the algorithm
 - Burrell, A. G., Chisham, G., Longden, N., Fritz, B., & Zawdie, K. A. (2025). Automated identification of auroral luminosity boundaries using pyIntensityFeatures. Journal of Geophysical Research: Space Physics, 130, e2025JA034230, doi:[10.1029/2025JA034230](https://doi.org/10.1029/2025JA034230).

Acknowledgements

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