

Optical Tomography in CEDAR Science

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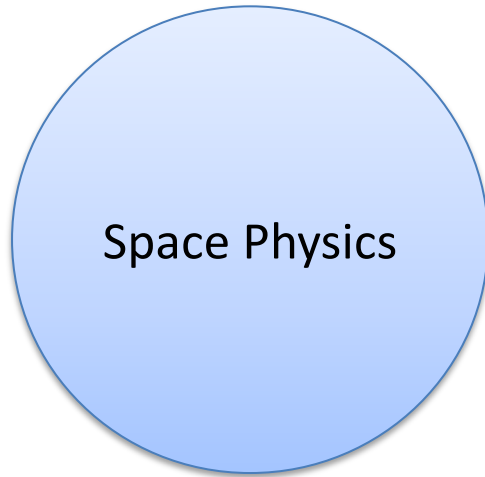


Everyone is a genius. But if you judge a fish by its ability to climb a tree, it will live its whole life believing that it is stupid.

- Albert Einstein

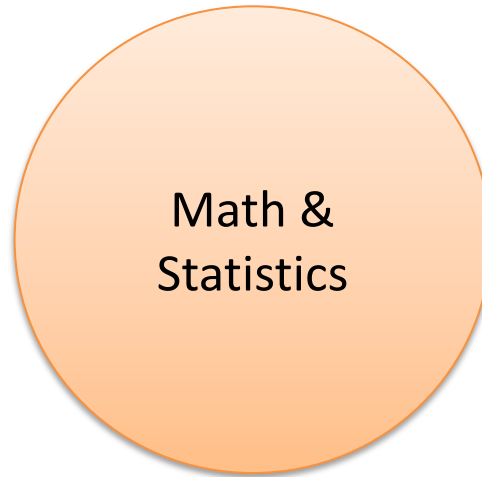
Data science: multi-disciplinary field that aims to extract knowledge from data.

- ⊙ **Optical tomography** is presented as an example of what we know as data science, multi-disciplinary field that involves, in our case, space physics, math & statistics , computer science (computational resources) and



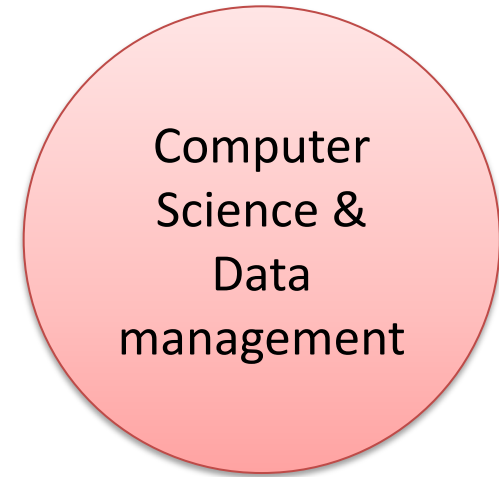
Space Physics

Exospheric Hydrogen
Solar-Terrestrial interactions
Radiative Emission models
Physical Model



Math &
Statistics

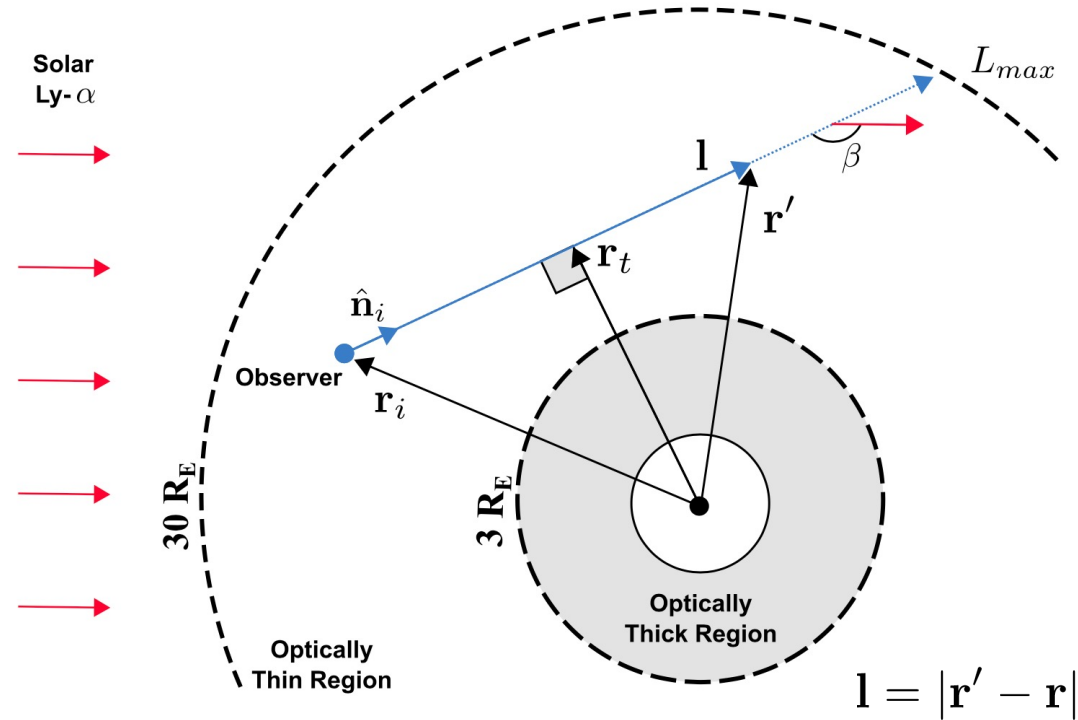
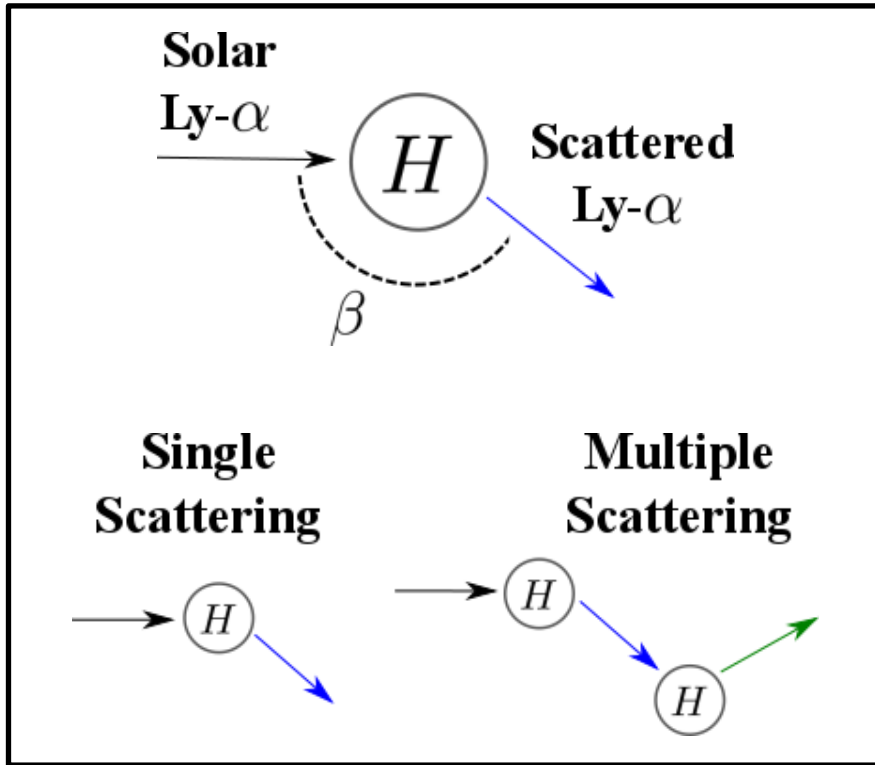
Signal Processing
Tomography
Statistical Estimation
Discrete Model



Computer
Science &
Data
management

Computational resources
Scientific Computing
Methods to reduce time/resources
Real Implementation

Hydrogen density estimation leverages the linearity of the optically thin emission model ($>3R_E$)



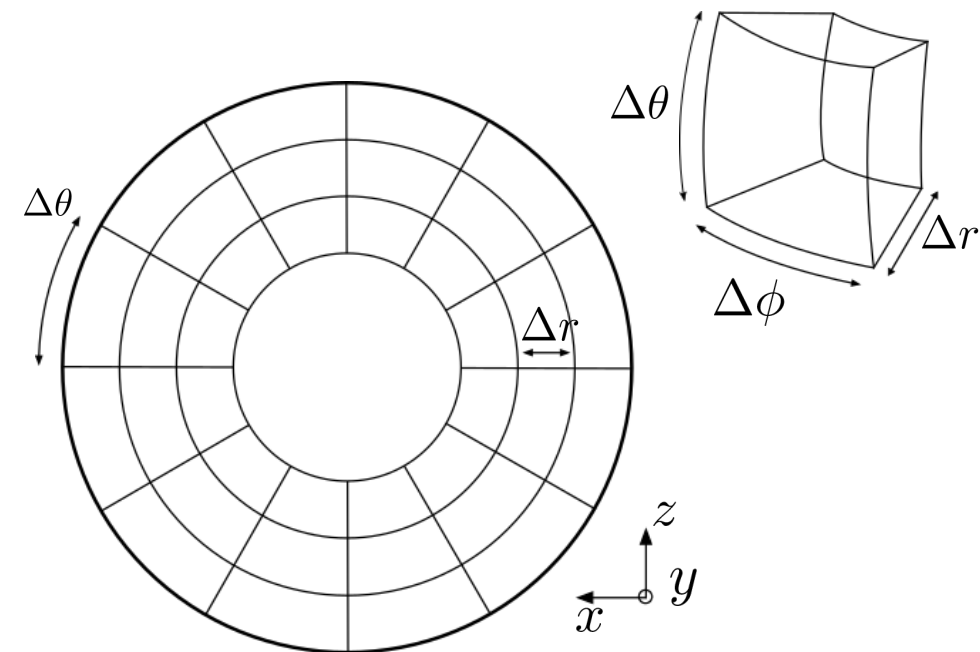
emission intensity (measured) [R] \rightarrow $I(\mathbf{r}, \hat{\mathbf{n}}, t)$ = $\frac{g^*(t)}{10^6} \int_0^{L_{max}} n_H(l) \Psi(\beta) dl + I_{IP}(\hat{\mathbf{n}}, t)$

LAD/TWINS \rightarrow $I(\mathbf{r}, \hat{\mathbf{n}}, t)$
 Ly-alpha resonant scattering rate (measured) [photons.s⁻¹] \rightarrow $g^*(t)$ (SEE/TIMED)
 emitter H density (unknown) [cm⁻³] \rightarrow $n_H(l)$
 scattering phase function (known) \rightarrow $\Psi(\beta)$
 interplanetary Background (measured) [R] \rightarrow $I_{IP}(\hat{\mathbf{n}}, t)$ (SOHO/SWAN)

Discretization of the exospheric volume of interest yields an algebraic linear system.

$$I(\mathbf{r}_i, \hat{\mathbf{n}}_i) = \frac{g^*(\mathbf{r}_i)}{10^6} \int_0^{Lmax} n_H(l) \Psi(\hat{\mathbf{n}}_i) dl + I_{IP}(\hat{\mathbf{n}}_i)$$

- Step 1: Discretize region into J spherical voxels.



- Step 2: Project unknown density function onto J orthonormal basis functions.

$$n_H(r') = \sum_{j=1}^J x_j \delta_{H_j}(r'),$$

$$\delta_{H_j}(r') = \begin{cases} 1 & \text{if } r' \in V_j \\ 0 & \text{else} \end{cases}$$

- Step 3: Rewrite i^{th} measurement of intensity as a linear equation.

$$y(\mathbf{r}_i, \hat{\mathbf{n}}_i) = \sum_{j=1}^J \left[\frac{g^*(\mathbf{r}_i)}{10^6} \Psi(\hat{\mathbf{n}}_i) \int_0^{Lmax} \delta_{H_j}(l) dl \right] x_j$$

$$\mathbf{y} = L\mathbf{x}$$

$$\begin{aligned} \mathbf{y} &\in \mathbb{R}^M \\ \mathbf{x} &\in \mathbb{R}^J \\ L &\in \mathbb{R}^{M \times J} \end{aligned}$$

Solving the estimation problem requires the use of more complex techniques such as regularization

- ⊙ Observation matrix $L \in \mathbb{R}^{M \times J}$, $M \gg J$ and **is not full column rank** (Voxels with out LOS through them).

$$\hat{\mathbf{x}} = \underset{x \geq 0}{\operatorname{argmin}} \Phi(\mathbf{x})$$

- ⊙ Regularization techniques are necessary to obtain a solution.

$$\Phi(\mathbf{x}) = \underbrace{\|L\mathbf{x} - \mathbf{y}\|_2^2}_{\text{Data misfit term}} + \underbrace{\lambda RRRPE(\mathbf{x})}_{\text{Regularization term}}$$

Cost Func.

- ⊙ The selected regularization method is **Regularized Robust Positive Estimation**.

$$\lambda RRRPE(\mathbf{x}) = \underbrace{\lambda_r \|\mathbf{x}\|_{D_r}}_{\text{Radial dim.}} + \underbrace{\lambda_\phi \|\mathbf{x}\|_{D_\phi}}_{\text{Azimuthal dim.}} + \underbrace{\lambda_\theta \|\mathbf{x}\|_{D_\theta}}_{\text{Polar dim.}}$$

- ⊙ Includes prior knowledge of **physical structure of the Hydrogen density distributions** for each dimension.

$$\|\mathbf{x}\|_{D_r} = \mathbf{x}^T D_r^T D_r \mathbf{x}$$

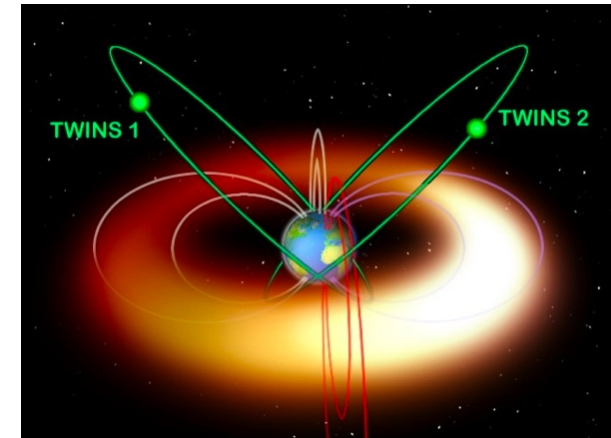
Discrete matrix form of
1st and 2nd derivatives

$$\begin{aligned} D_r &\approx \partial^2 / \partial r^2 \\ D_\phi &\approx \partial / \partial \phi \\ D_\theta &\approx \partial / \partial \theta \end{aligned}$$

Example of technique feasibility using the NASA's TWINS mission data.

Data

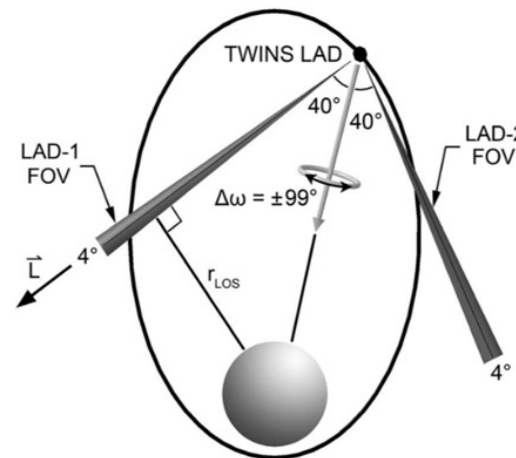
⊙ NASA's Two Wide-angle Imaging Neutral-atom Spectrometers (TWINS) mission provides the capability for **stereoscopically imaging the magnetosphere.**



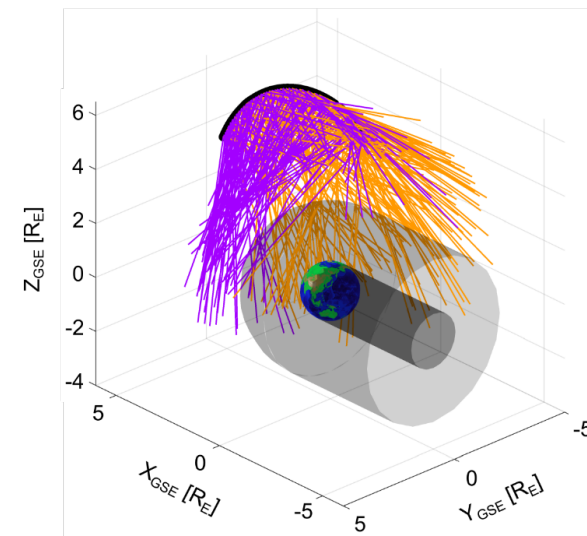
Source: TWINS SWRI website

⊙ Each TWINS1/2 has two **Lyman-alpha detectors (LAD)**, optical sensors.

⊙ The selected data in this study is from **11 June 2008**, in order to compare results with those reported by Bailey et al., [2011]



Source: [Bailey et al., 2011]

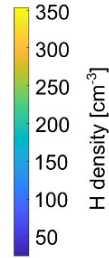
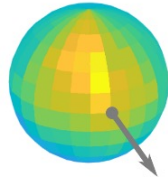
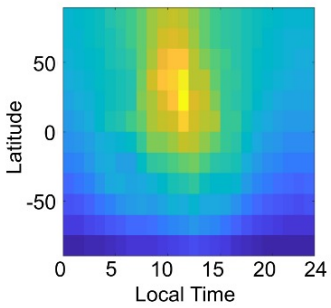


Radial shell R = 4.125 RE

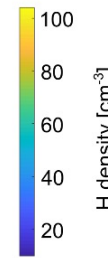
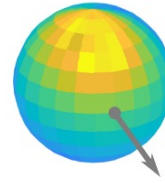
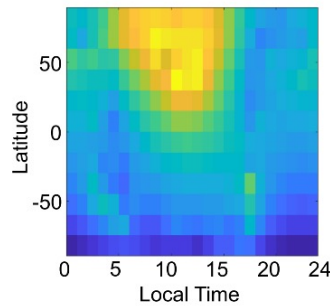
Radial shell R = 6.375 RE

Space Physics

Tomographic reconstruction

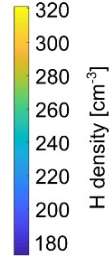
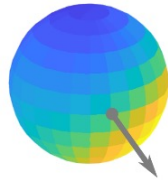
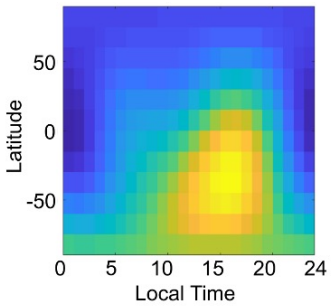


H density [cm⁻³]

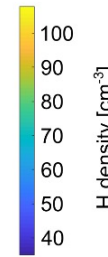
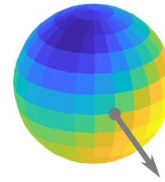
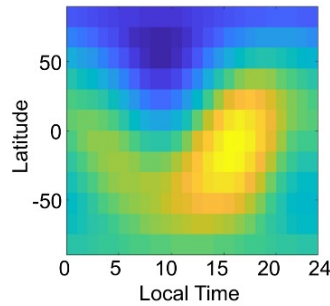


H density [cm⁻³]

Parametric fitting
[Bailey and Gruntman, 2011]

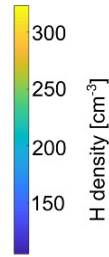
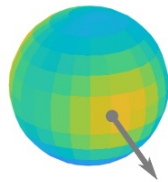
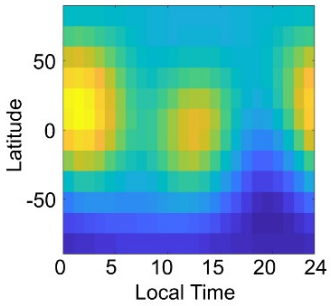


H density [cm⁻³]

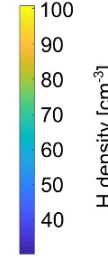
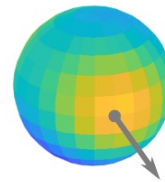
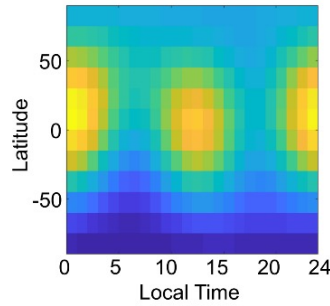


H density [cm⁻³]

Parametric fitting
[Zoennchen et al, 2015]

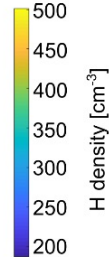
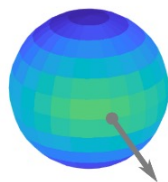
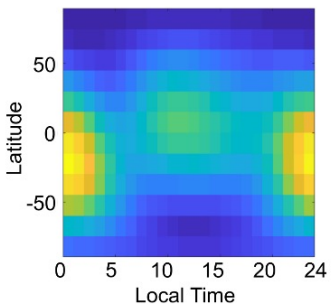


H density [cm⁻³]

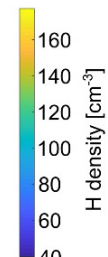
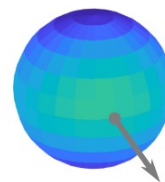
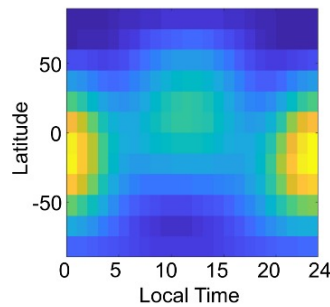


H density [cm⁻³]

Monte Carlo simulation



H density [cm⁻³]



H density [cm⁻³]

Cucho-Padin and Waldrop, (2018)
Tomographic Estimation of Exospheric Hydrogen Density Distributions, JGR Space Physics

Space-state framework approach for dynamic tomography and Kalman Filter as a solver

As exospheric H densities are prone to be dynamic during storm-time, we use the state-space model as a means for time-varying estimation:

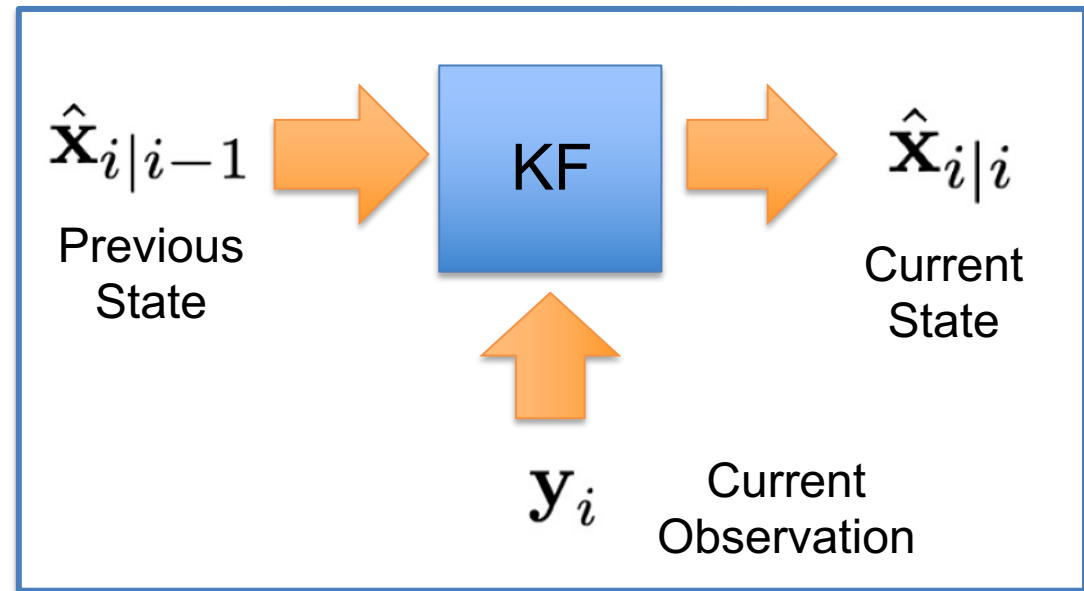
Measurement equation:

$$\mathbf{y}_i = H_i \mathbf{x}_i + \mathbf{v}_i$$

Model evolution equation:

$$\mathbf{x}_{i+1} = F_i \mathbf{x}_i + \mathbf{u}_i$$

Kalman Filter as solver



Inclusion of regularization terms

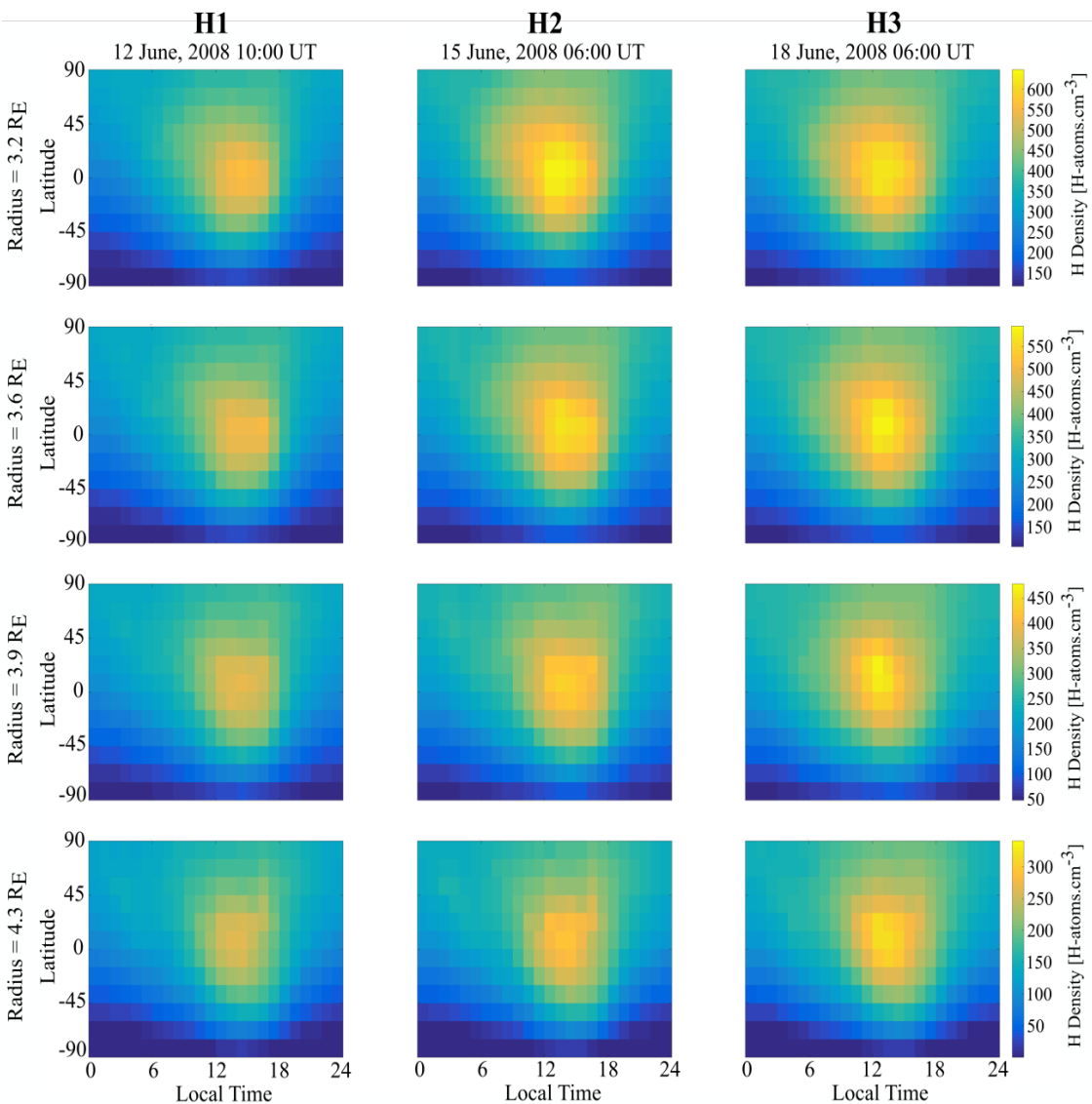
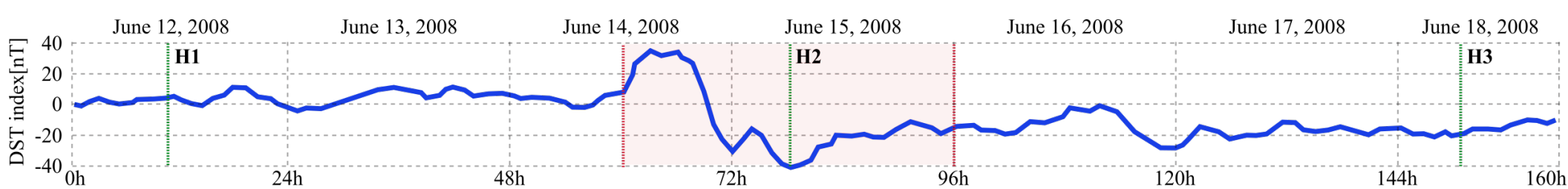
$$\begin{bmatrix} \mathbf{y}_i \\ 0 \end{bmatrix} = \begin{bmatrix} H_i \\ D_i \end{bmatrix} \mathbf{x}_i + \begin{bmatrix} \mathbf{v}_i \\ \mathbf{w}_i \end{bmatrix}$$

$$\mathbf{y}'_i = H'_i \mathbf{x}_i + v'_i$$

$$R'_i \triangleq \mathbb{E}[\mathbf{v}'_i (\mathbf{v}'_i)^T] = \begin{bmatrix} R_i & 0 \\ 0 & \lambda_i^{-1} I \end{bmatrix}$$

Dynamic tomographic estimation connected to the LMMSE estimation

$$\hat{\mathbf{x}}_{i|i}^d = \underset{\mathbf{x}_i}{\operatorname{argmin}} \left\| \mathbf{y}'_i - H'_i \mathbf{x}_i \right\|_{R'_i}^2 + \left\| \mathbf{x}_i - \hat{\mathbf{x}}_{i|i-1} \right\|_{P_{i|i-1}^{-1}}^2 + \lambda_\phi \left\| D_\phi \mathbf{x}_i \right\|_2^2 + \lambda_\theta \left\| D_\theta \mathbf{x}_i \right\|_2^2 + \lambda_r \left\| D_r \mathbf{x}_i \right\|_2^2$$

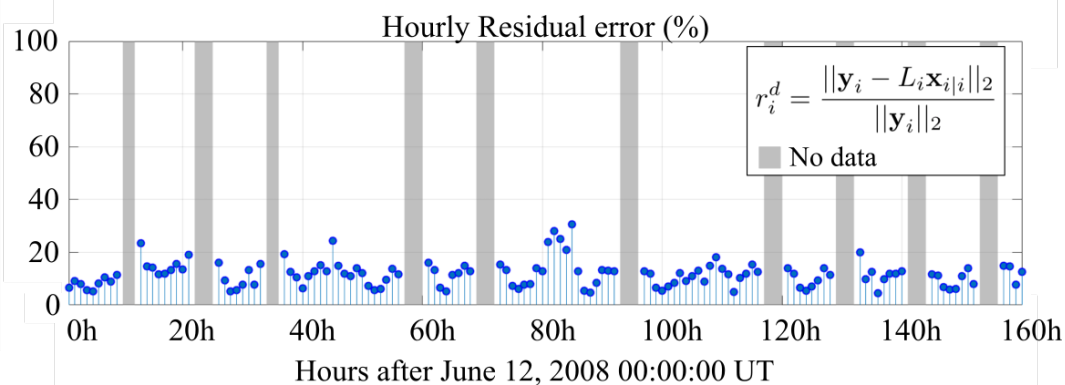
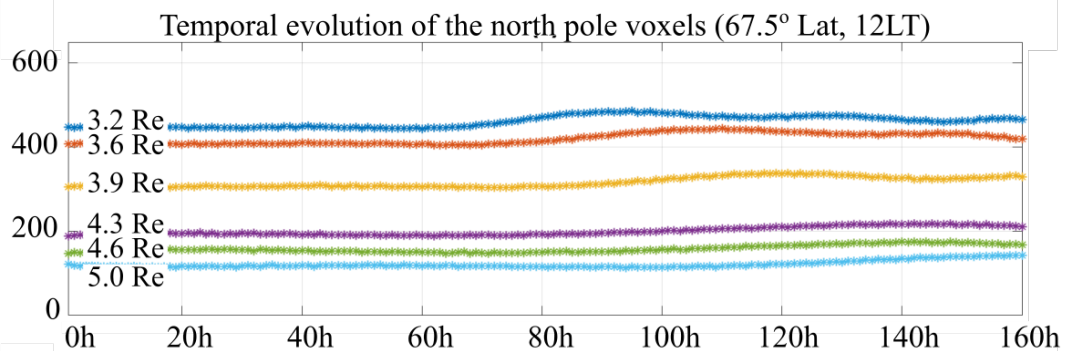
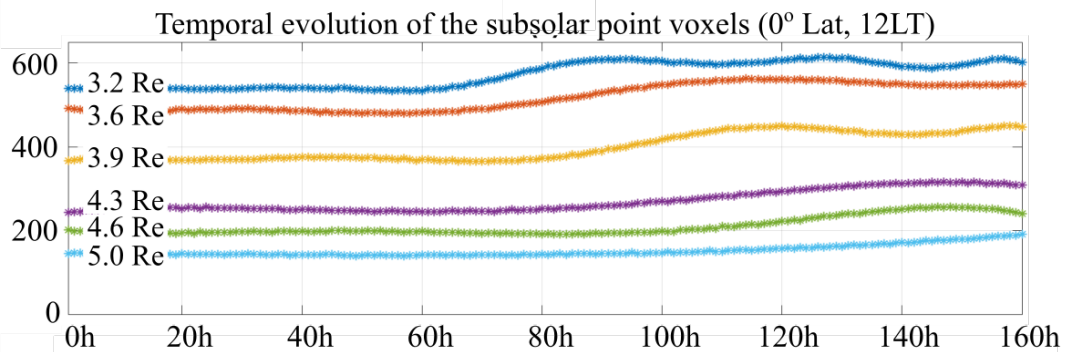
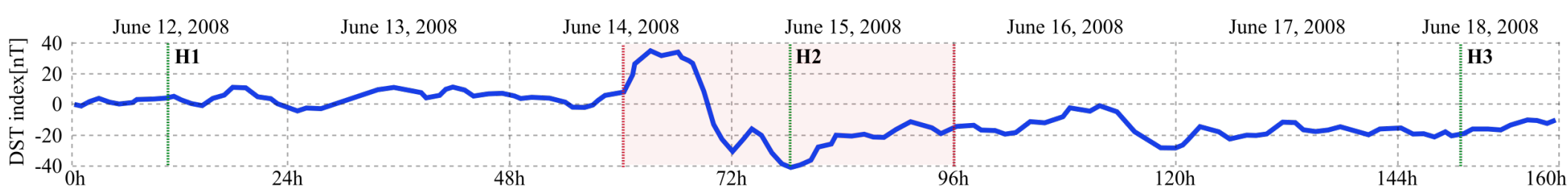


⊙ Using KF we have performed 160 dynamic reconstructions during the storm occurred on 15 June, 2008.

⊙ Hydrogen density enhancements have been seen as the storm develops. Such increments are then translated to higher altitudes with certain delay which suggests a vertical transport or upwelling.

⊙ Hydrogen densities at altitudes greater than 5Re remain constant. It suggests that the increment is related to the ballistic and escape populations.

Space Physics



⊙ Two voxel columns with the highest LOS coverage has been selected to analyze the temporal evolution of geocoronal H density.

⊙ In the subsolar point, simple calculations between 3.2Re and 3.9 Re profiles show a exospheric wind of ~60m/s.

⊙ Similar structure can be seen in those voxels near Geographic North Pole.

⊙ Hourly residual error is presented and has an average value of ~11%.

Space Physics

⊙ **Data cleaning:** TWINS data contains several values with non-physical interpretation for unknown reasons. *Possible solution:* Machine learning techniques to classify non-physical behavior in the acquired signal.

⊙ **Computational resources:** Several tools enable us to reduce the computational time. Although Kalman Filter is a sequential procedure, the internal calculations (mainly matrix-vector operations) can easily be implemented in dedicated hardware such as GPU's, or with specialized libraries such as MKL (Math Kernel Library from Intel)

⊙ **Dynamic Storage:** Using both TWINS satellites during stereoscopic events will provide a great amount of data. The increase of spatial and even temporal resolution can be performed. However, increasing the number of voxel N involve the size increment of covariance matrices N^2 . Possible solution: Ensemble Kalman Filter (EnKF). It uses L samples of a the random process that could keep the internal statistical properties (variance). With $L \ll N$, the used storage would be $[L \times N]$ instead of $[N \times N]$.

THANK YOU