

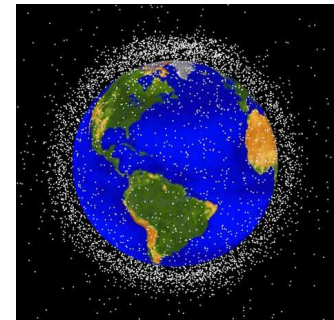


Retrospective Cost Model Refinement and State and Input Estimation for Space Weather Modeling and Prediction

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University of Michigan

Thanks to: Ankit Goel

Supported by Frederica Darema,
AFOSR DDDAS Program





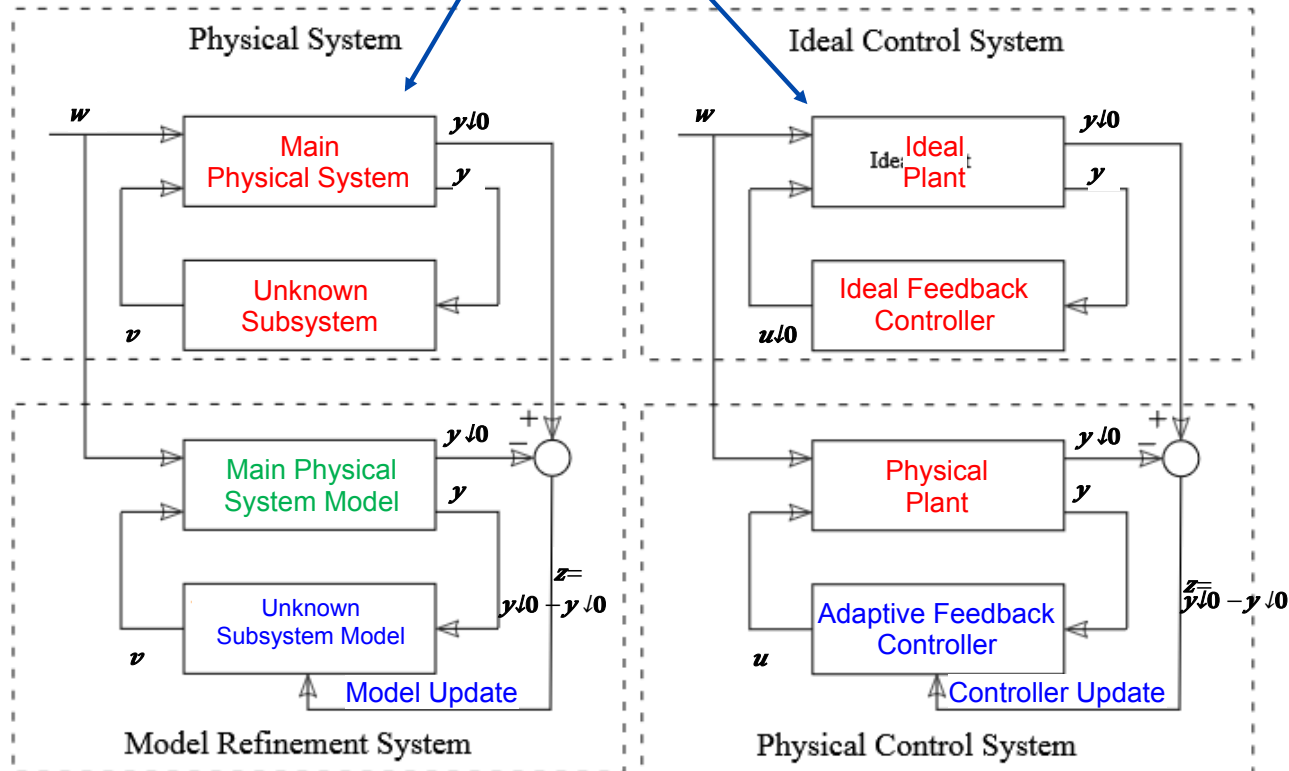
Modeling for DDDAS



- ❑ model \neq reality
- ❑ All models are wrong 😞
- ❑ Types of model errors
 - ❑ Parameter errors
 - ❑ Errors in dynamics----wrong or missing
 - ❑ Everything is uncertain to some extent
- ❑ But some models are useful! 😊
 - ❑ Some are more useful than others
- ❑ The “accuracy” of a model is meaningful only relative to its intended purpose
- ❑ Model refinement
 - ❑ Model + data = better model



Model Refinement = Adaptive Control!



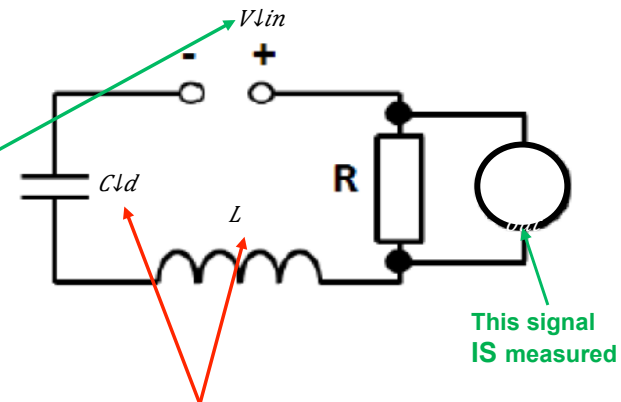


Retrospective Cost Model Refinement Circuit Experiment



Current and voltage drops
are NOT measured

- ❑ Series RLC circuit
- ❑ Driving signal is circuit voltage
- ❑ The only measurement is the voltage drop across the resistor
- ❑ The inductance and capacitance are assumed to be unknown



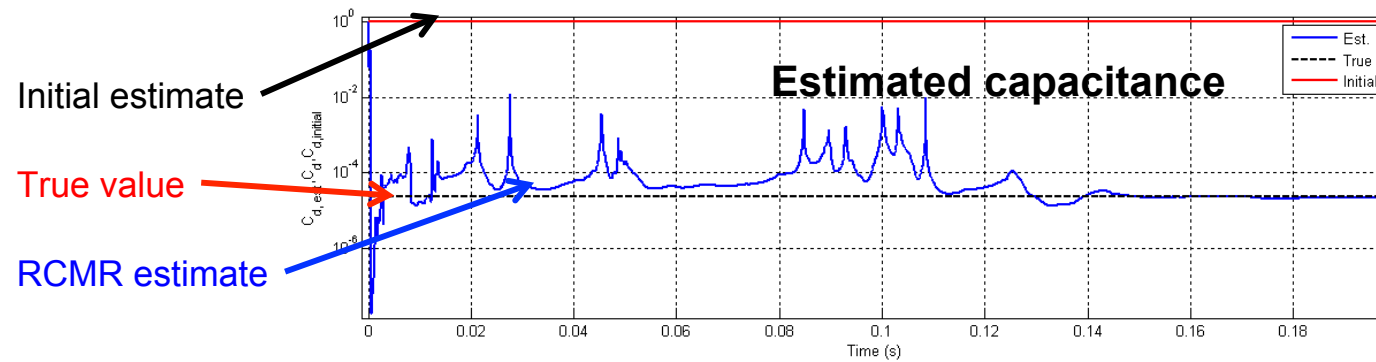
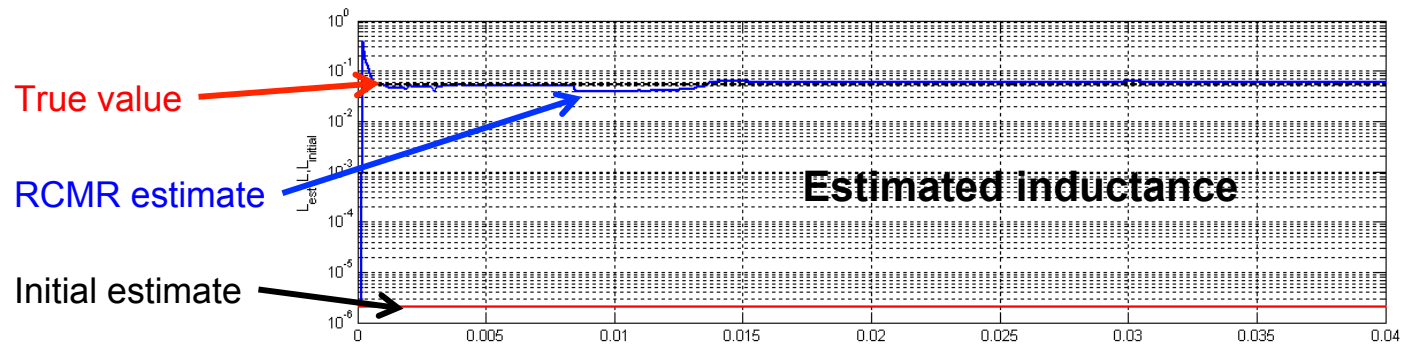
**These parameters are
unknown and inaccessible**

$$Lx + Rx + x/C\omega d = V\omega in$$

$$V\omega out = Rx$$



Retrospective Cost Model Refinement Estimates of L and C

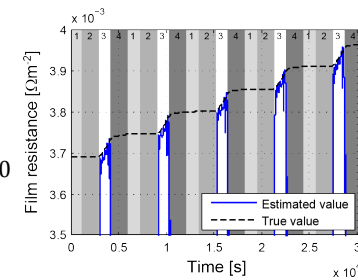
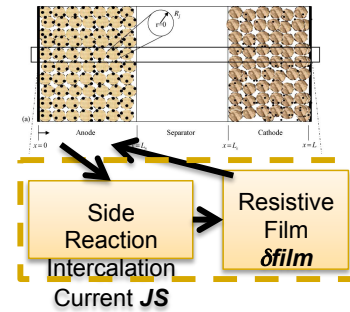
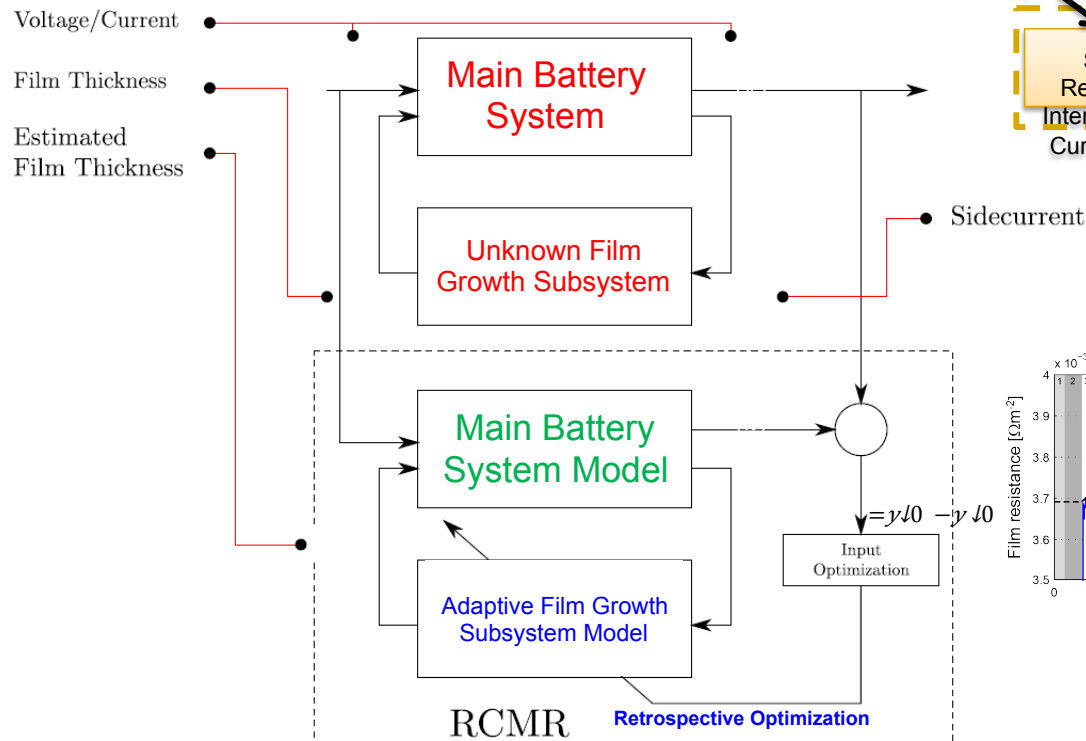




Retrospective Cost Model Refinement Battery Health Monitoring



- Objective: Monitor battery health by estimating film growth at the negative electrode using charging measurements





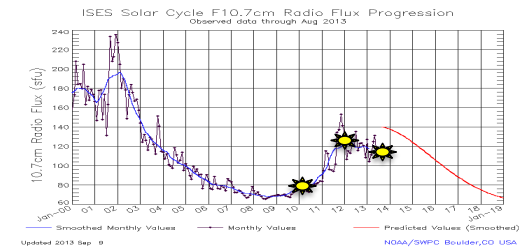
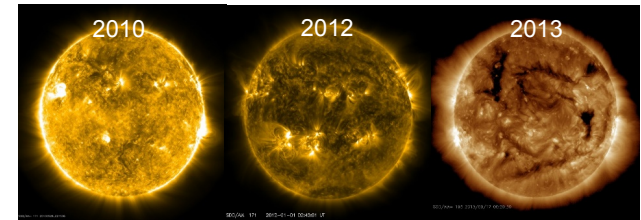
Space Weather Modeling



- Problem
 - Unknown changes to the atmospheric density degrade the accuracy of GPS and impede the ability to track space objects
- Goals
 - Use input reconstruction to estimate atmospheric drivers that determine the evolution of the ionosphere-thermosphere
 - Use model refinement to improve the accuracy of atmospheric models
 - Achieve more accurate data assimilation

Effects on Earth

- Space weather affects the terrestrial environment
- Space weather disturbances interfere with satellite and radio communications and operations
- Extreme space weather events can knock out the power grid, melt electronics, damage satellites, and disrupt polar air routes



Orbit Determination

- Orbital prediction error is principally caused by problems in estimating atmospheric drag
- Predicting atmospheric drag requires prediction of the atmospheric density and understanding ion-neutral interactions
- Measurements in the upper atmosphere are primarily space-based



Monitoring Space Weather



- ❑ Satellites
 - ❑ Solar Missions
 - ❑ Magnetospheric Missions
 - ❑ Atmospheric Missions

- ❑ Ground-Based Observatories
 - ❑ Ionospheric characteristics and disturbances
 - ❑ Atmospheric winds
 - ❑ Solar, magnetic, and current indices

- ❑ Monitoring and Data Centers
 - ❑ NOAA Space Weather Prediction Center
 - ❑ Heliophysics Events Knowledge base
 - ❑ Dominion Observatory in Penticton, British Columbia, Canada



NASA

CHAMP
CHALLENGING Mini-satellite Payload

Charge utile « gravité » :
• récepteur GPS Black-Jack
• réflecteurs laser
• accéléromètre STAR

Launched 15 July '00
Re-entered 12 Sept '10

GFZ POTSDAM DLR

2000

GRACE
Gravity Recovery and Climate Experiment

Charge utile :
• récepteurs GPS Black-Jack
• réflecteurs laser
• système dual inter-satellite en bandes K/Ka
• accéléromètres super-STAR

Launched 17 March '02
in decaying orbit till 2016

NASA DLR GFZ POTSDAM University of Texas at Austin Center for Space Research CSR

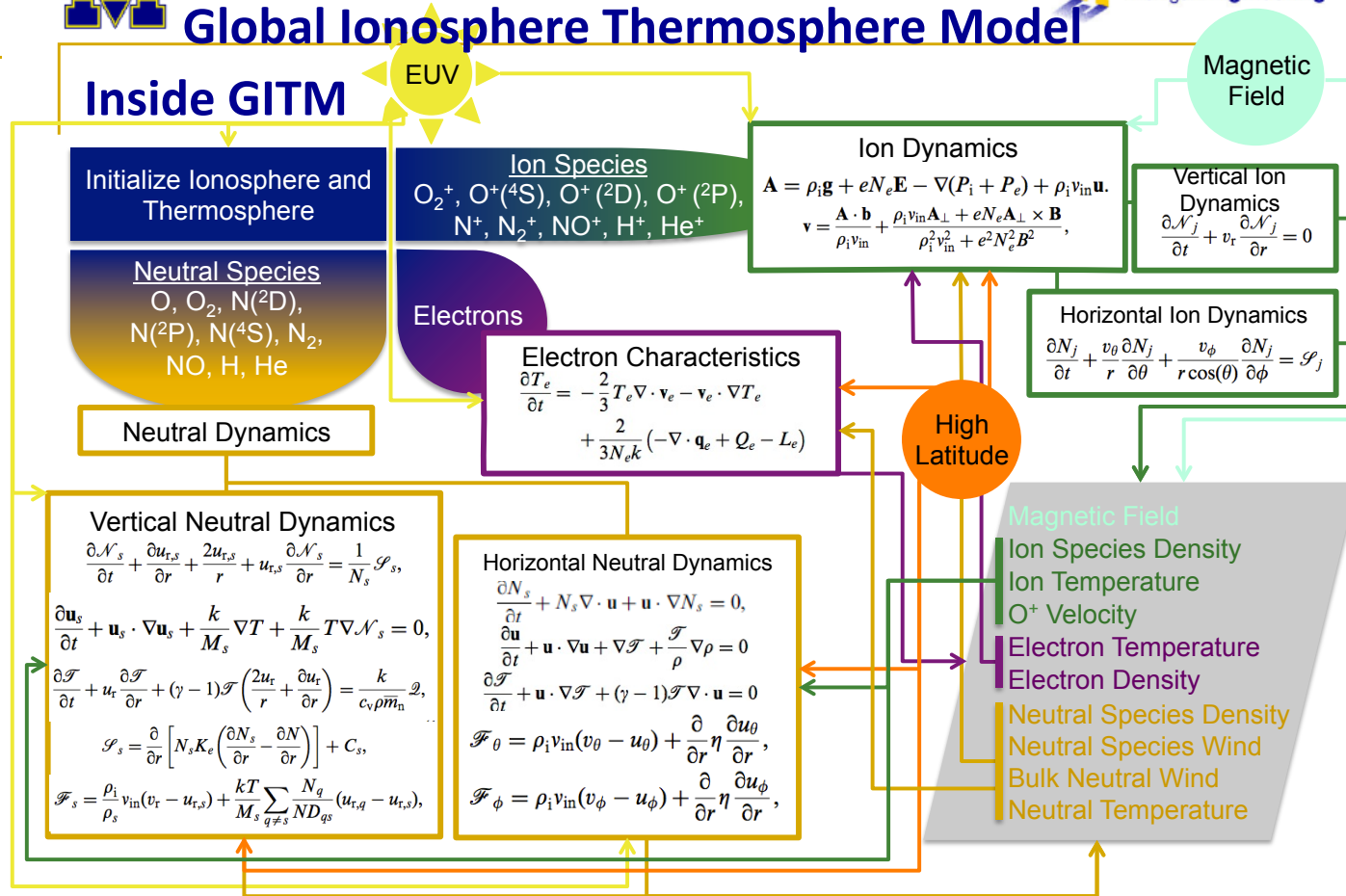
2002



GITM

Global Ionosphere Thermosphere Model

MichiganEngineering anEngineering



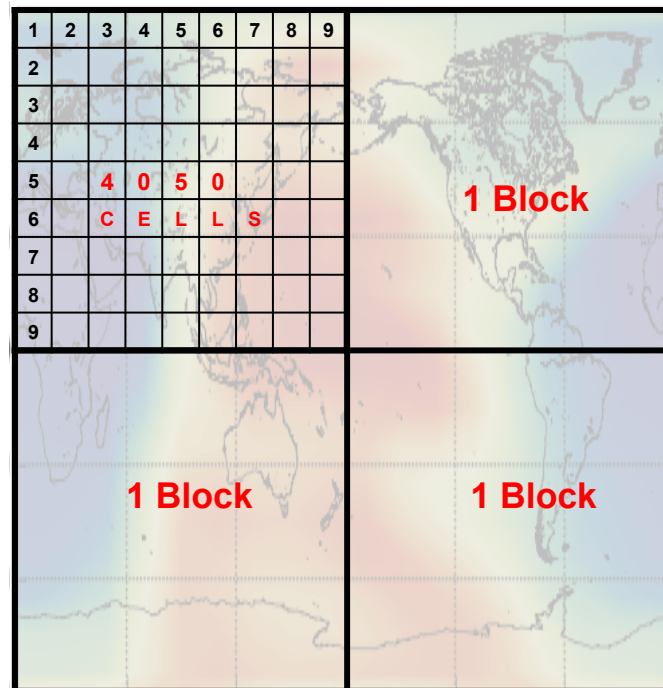


GITM Is Fully Parallelized



- ❑ Resolution is specified by the number of blocks covering the Earth
- ❑ Each block has 4050 cells
9 longs X 9 lats X 50 alts
- ❑ Each cell as 28 states
 - ❑ 7 neutrals, 8 ions, 3 temperatures, 7 neutral velocities, 3 ion velocities
 - ❑ Each block has 113,400 states
- ❑ Typical grids are (longitude blocks)x(latitude blocks):
 - ❑ 2x2 (4 processors)
Testing purposes, $10^\circ \times 20^\circ$
453,600 states
 - ❑ 8x8 (64 processors)
Low resolution physical runs, $5^\circ \times 2.5^\circ$
7,257,600 states
 - ❑ 8x12 (96 processors)
High resolution physical runs, $5^\circ \times 1.67^\circ$
10,886,400 states

2x2 Grid of the Earth (4 blocks)





Estimate Photoelectron Heating Efficiency



Vertical Neutral Dynamics

$$\frac{\partial \mathcal{N}_s}{\partial t} + \frac{\partial u_{r,s}}{\partial r} + \frac{2u_{r,s}}{r} + u_{r,s} \frac{\partial \mathcal{N}_s}{\partial r} = \frac{1}{N_s} \mathcal{S}_s,$$

$$\frac{\partial \mathbf{u}_s}{\partial t} + \mathbf{u}_s \cdot \nabla \mathbf{u}_s + \frac{k}{M_s} \nabla T + \frac{k}{M_s} T \nabla \mathcal{N}_s = 0,$$

$$\frac{\partial \mathcal{F}}{\partial t} + u_r \frac{\partial \mathcal{F}}{\partial r} + (\gamma - 1) \mathcal{F} \left(\frac{2u_r}{r} + \frac{\partial u_r}{\partial r} \right) = \frac{k}{c_v \rho \bar{m}_n} \mathcal{Q}$$

$$\mathcal{S}_s = \frac{\partial}{\partial r} \left[N_s K_e \left(\frac{\partial N_s}{\partial r} - \frac{\partial N}{\partial r} \right) \right] + C_s,$$

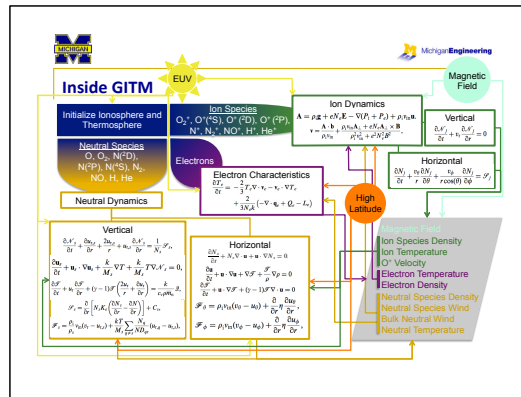
$$\mathcal{F}_s = \frac{\rho_i}{\rho_s} v_{in} (u_r - u_{r,s}) + \frac{kT}{M_s} \sum_{q \neq s} \frac{N_q}{ND_{qs}} (u_{r,q} - u_{r,s}),$$

$$\mathcal{Q} = \mathcal{Q}_{EUV} + \mathcal{Q}_{NO} + \mathcal{Q}_O + \frac{\partial}{\partial r} \left((\kappa_c + \kappa_{eddy}) \frac{\partial T}{\partial r} \right) + N_e \frac{\bar{m}_i \bar{m}_n}{\bar{m}_i + \bar{m}_n} v_{in} (\mathbf{v} - \mathbf{u})^2,$$

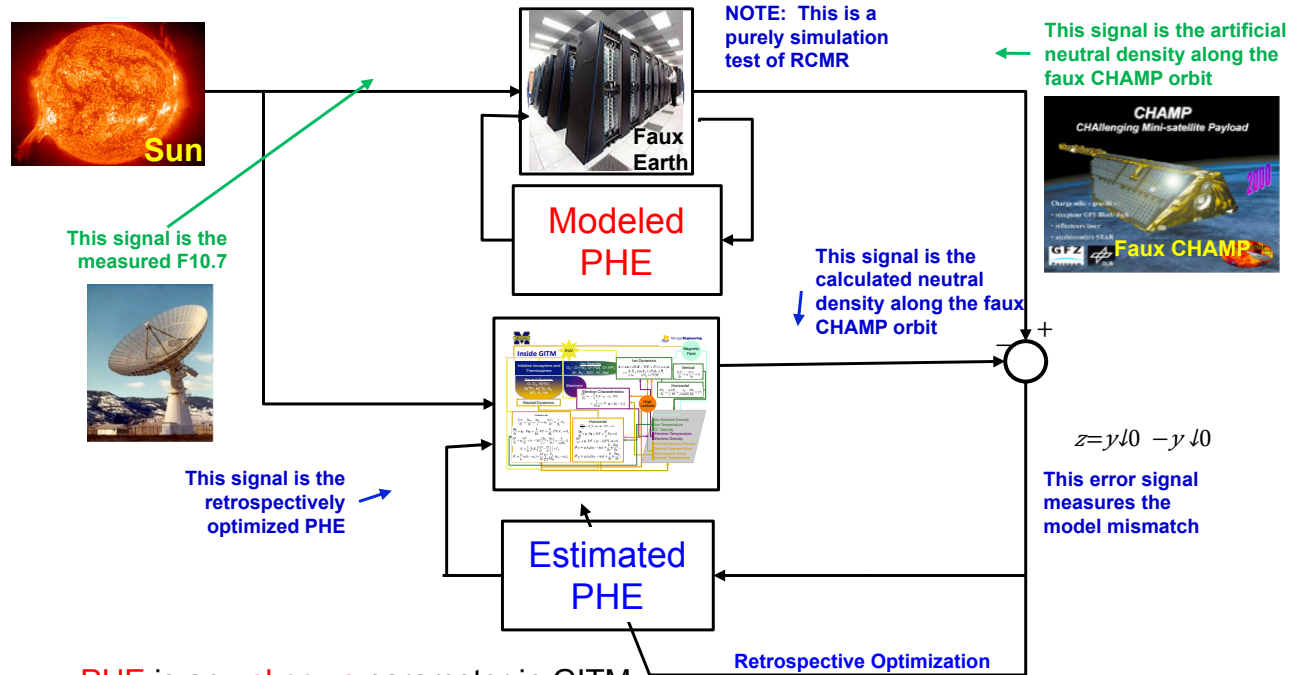
$$\mathcal{Q}_{EUV} = \epsilon_{EUV} q_{EUV} + \epsilon_{PHE} q_{PHE}$$

Photoelectron Heating Efficiency

is the solar extreme ultraviolet (EUV) heating
 is the photoelectron heating---the heat released by secondary photoelectrons



Estimate Photoelectron Heating Efficiency Using Artificial Data



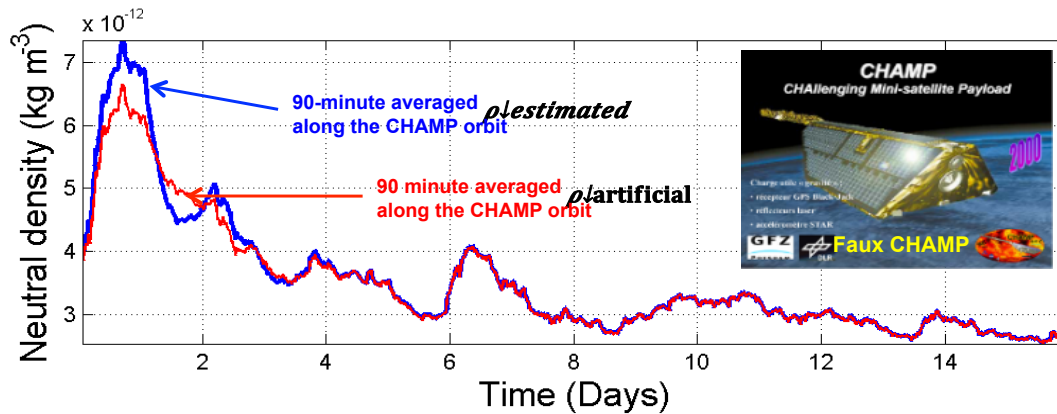
- PHE is an **unknown** parameter in GITM
- To estimate PHE, we compute neutral density along **CHAMP**'s orbit at the fixed altitude of 400 km, and RCMR uses this artificial data
- As a quality metric for the state estimates, we compare estimates of the neutral density along **GRACE**'s orbit at a constant altitude of 400 km



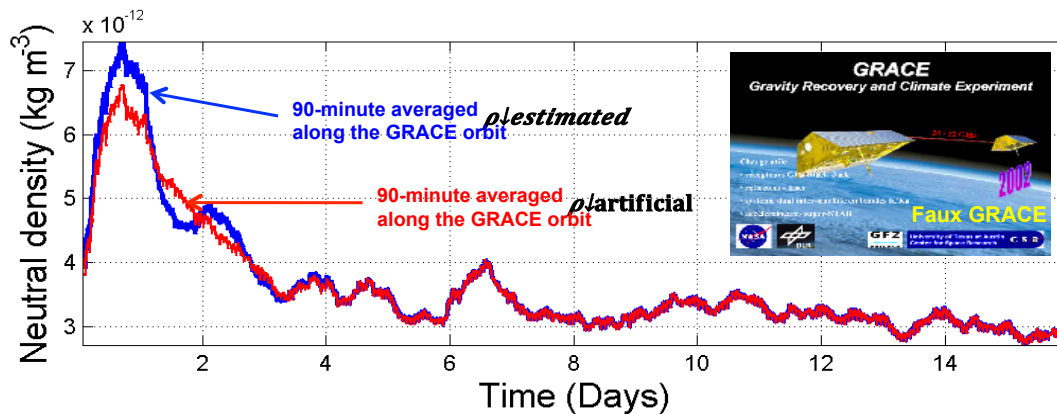
Estimate Photoelectron Heating Efficiency Using Artificial Data



- The 90-minute average of the estimated neutral density converges to the artificial neutral density along the CHAMP and GRACE orbits at 400 km altitude



Faux CHAMP neutral density **IS** assimilated



Faux GRACE neutral density is **NOT** assimilated

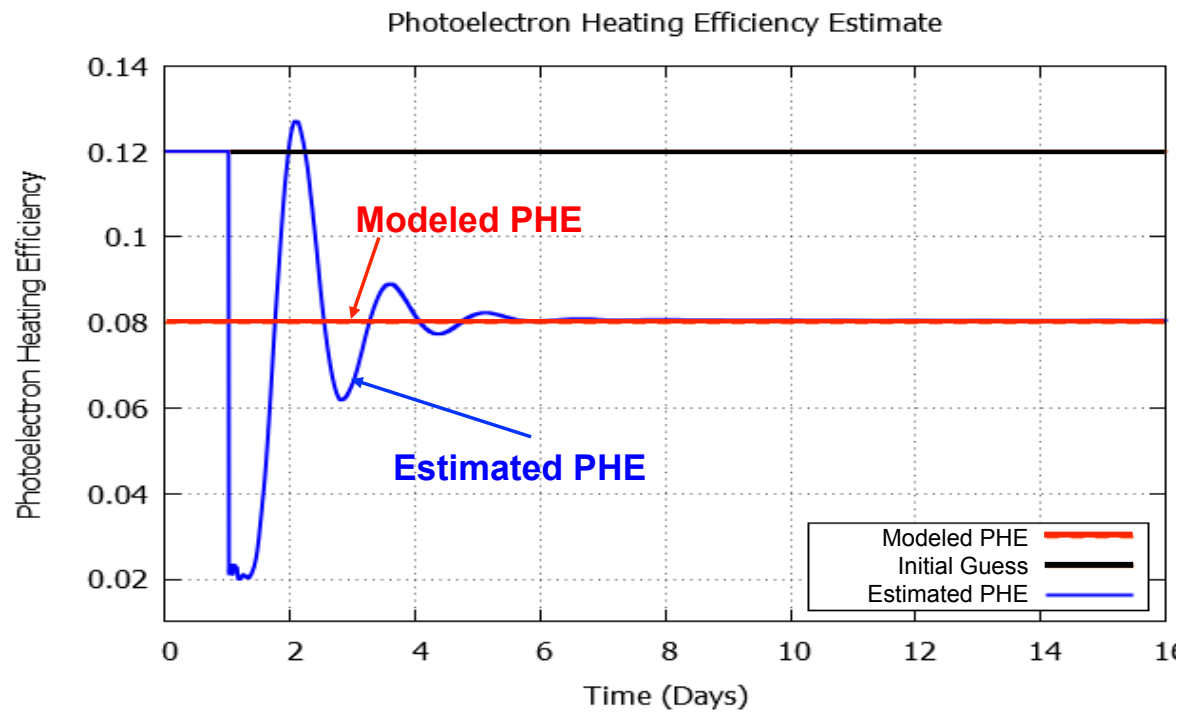
Faux GRACE neutral density is a performance metric



Estimate Photoelectron Heating Efficiency Using Artificial Data



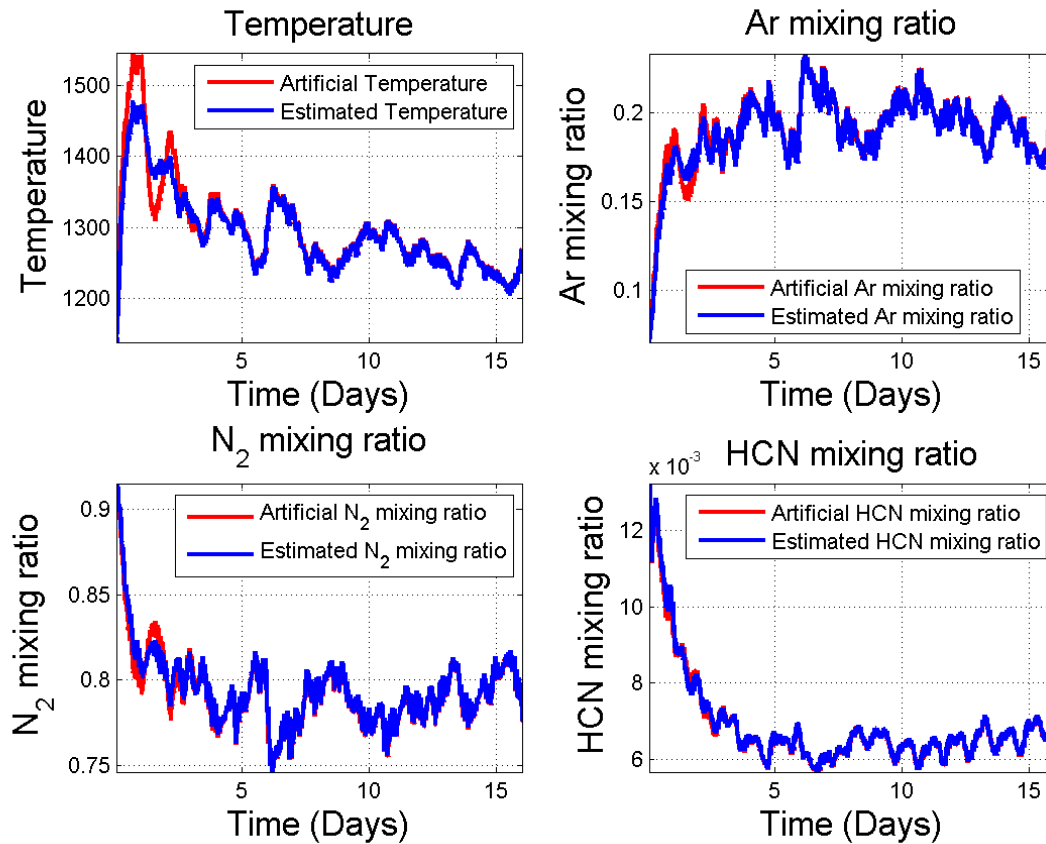
- The RCMR estimate of PHE converges to the artificial (modeled) value of PHE





Estimate Photoelectron Heating Efficiency Using Artificial Data

PHE convergence yields convergent state estimates

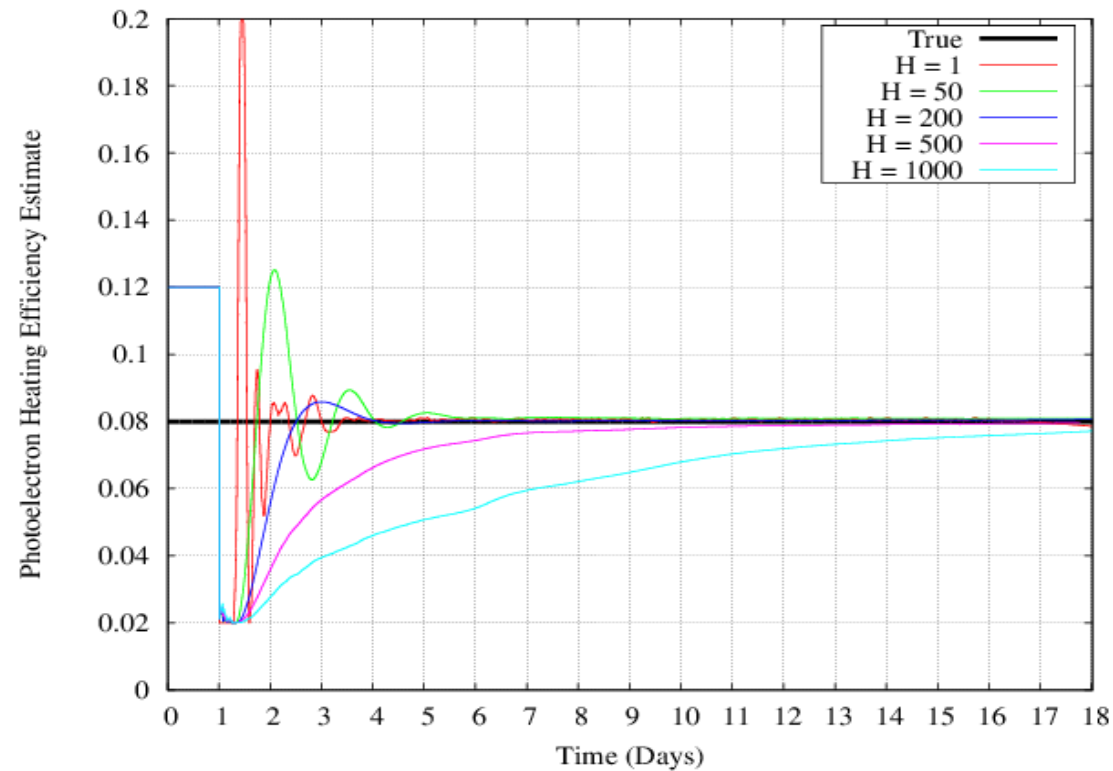




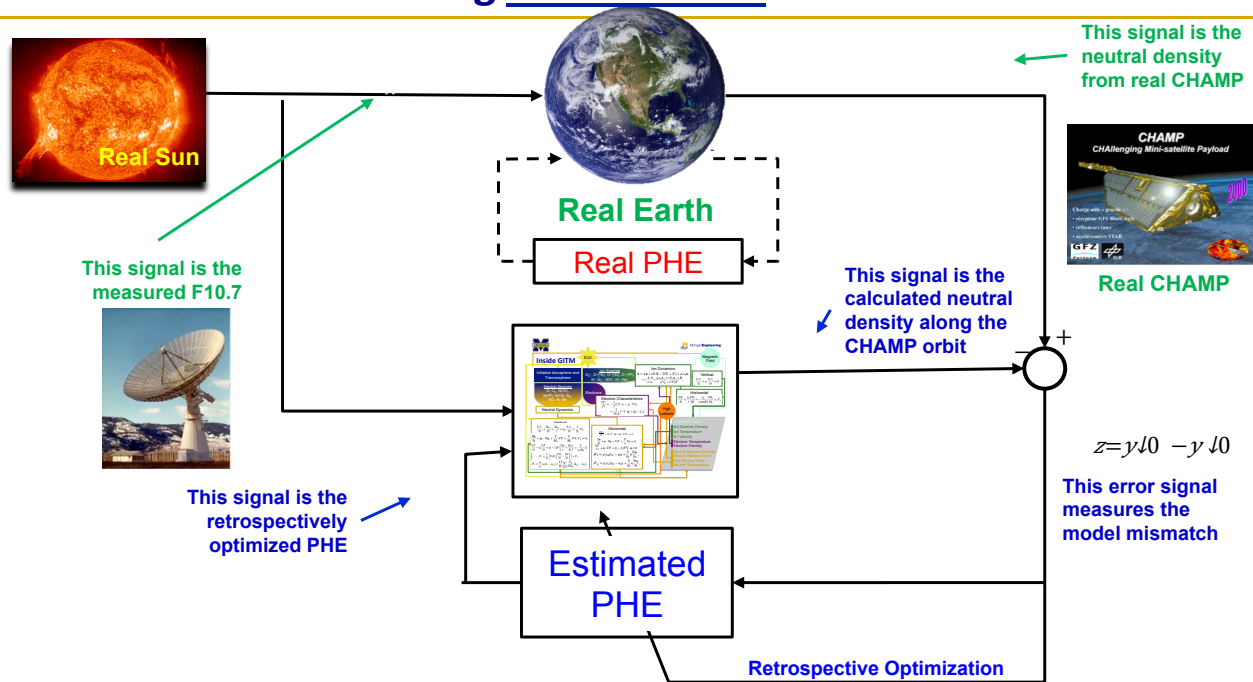
Estimate Photoelectron Heating Efficiency Using Artificial Data



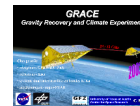
- ❑ We study the robustness of RCMR to the choice of H
- ❑ The estimate converges to the true value of PHE for a wide range of H



Estimate Photoelectron Heating Efficiency Using Real Satellite Data



- ❑ We estimate PHE using neutral density measurements from the **real CHAMP** satellite
 - ❑ We assimilate real **CHAMP** satellite data from 2002-11-24 to 2002-12-06
- ❑ Neutral density measurements from **GRACE** are used as a quality metric
 - ❑ But these data are NOT assimilated



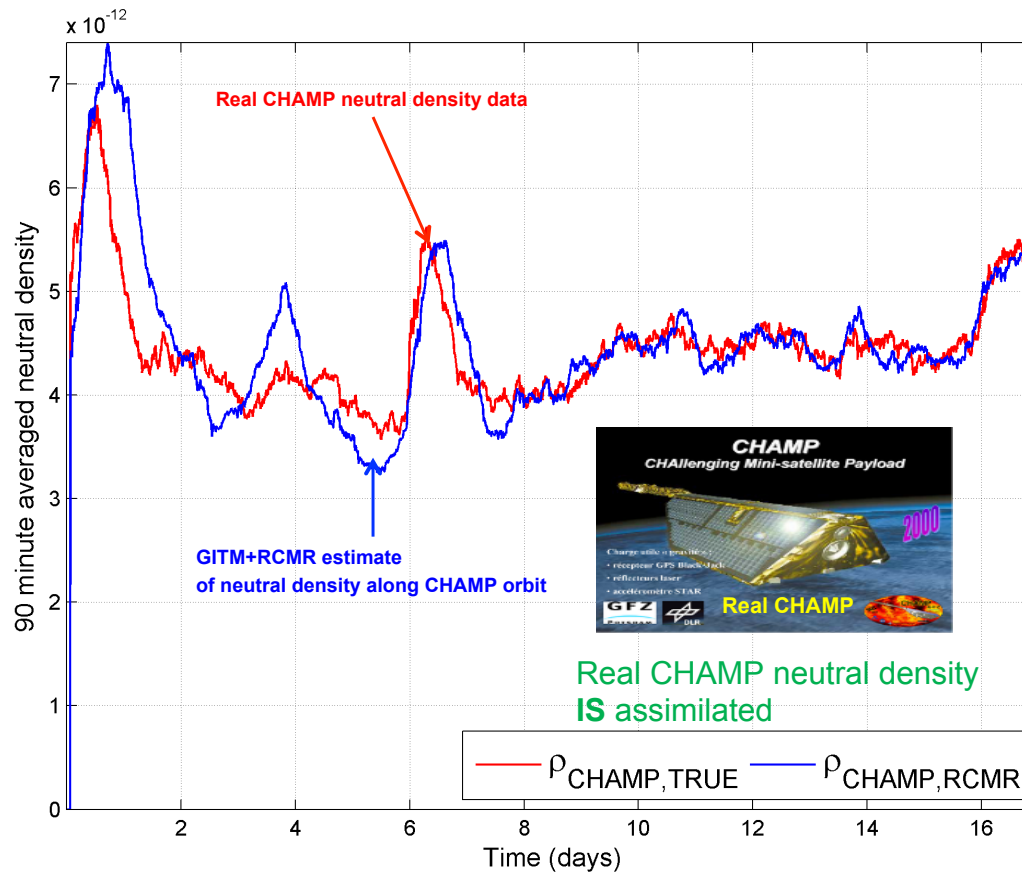
Real GRACE



Estimate Photoelectron Heating Efficiency Using Real Satellite Data



RCMR minimizes the error z in the CHAMP neutral density

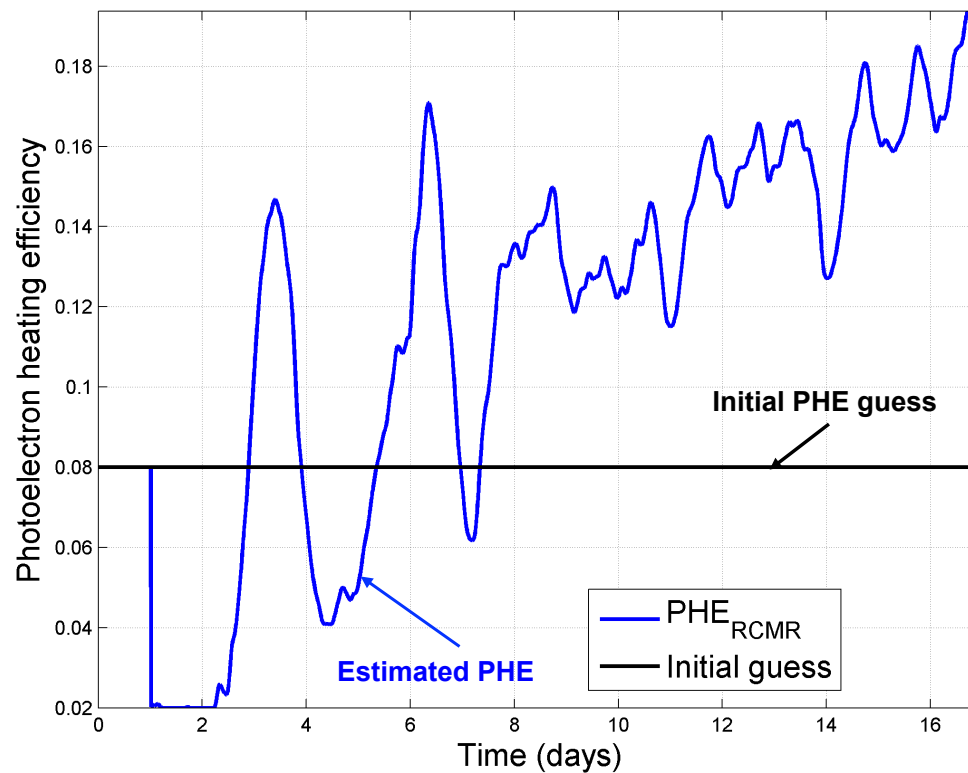




Estimate Photoelectron Heating Efficiency Using Real Satellite Data



- RCMR determines the value of PHE that minimizes the error z in the neutral density estimate

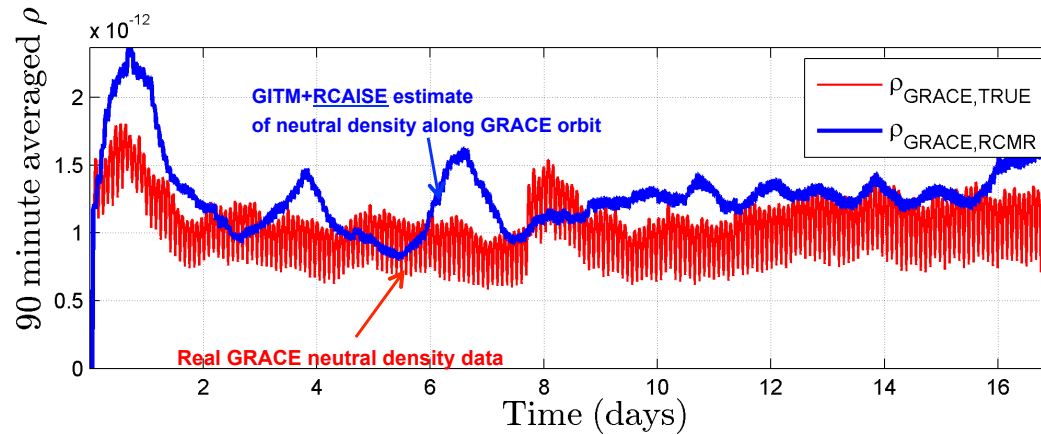




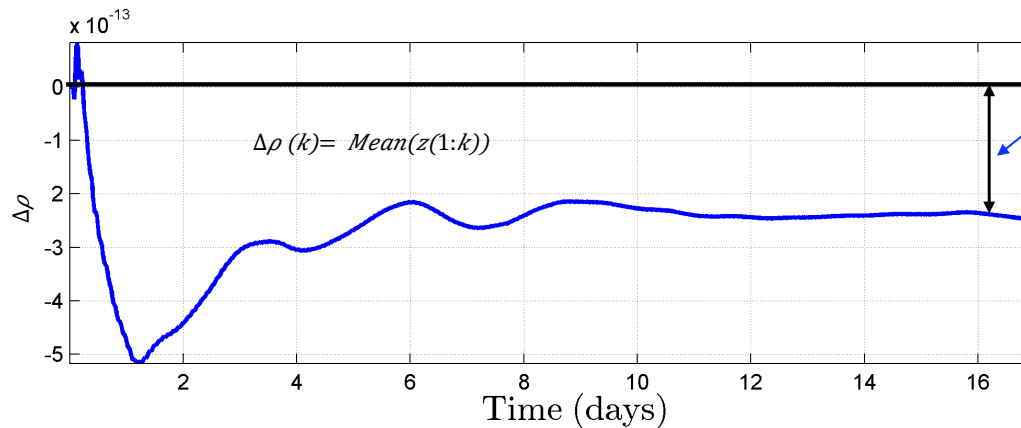
Estimate Photoelectron Heating Efficiency Using Real Satellite Data



RCAISE also corrects the neutral density at GRACE's location



GRACE neutral density data is **NOT** assimilated
This data is used only as a quality metric



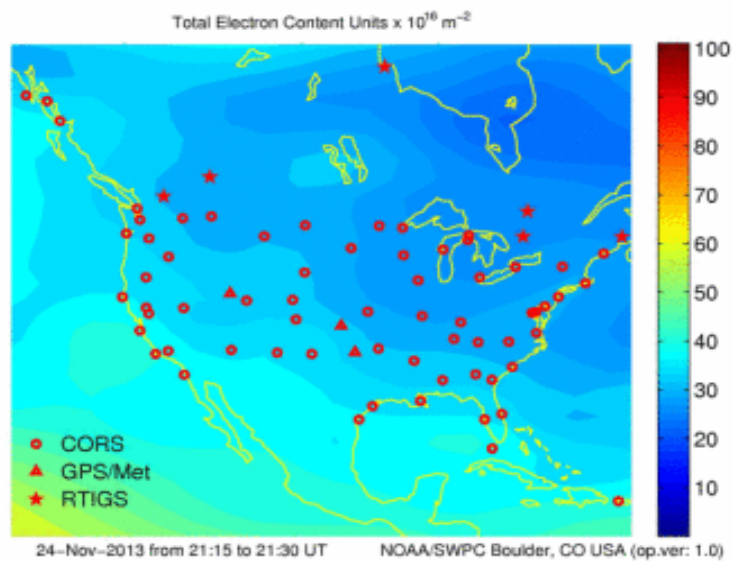
This error may be due to what scientists believe is a calibration error in the GRACE data



Estimate Eddy Diffusion Coefficient in GITM using Total Electron Content



- Total electron content (or TEC) is an important descriptive quantity for the ionosphere.
- TEC is the **total number of electrons** integrated **between two points**, along a tube of one meter squared cross section. Units are **1 TECU = 10^{16} m^{-2}**



TEC plot for the continental USA, made on 11/24/2013

CORS = Continuously Operating Reference Stations.

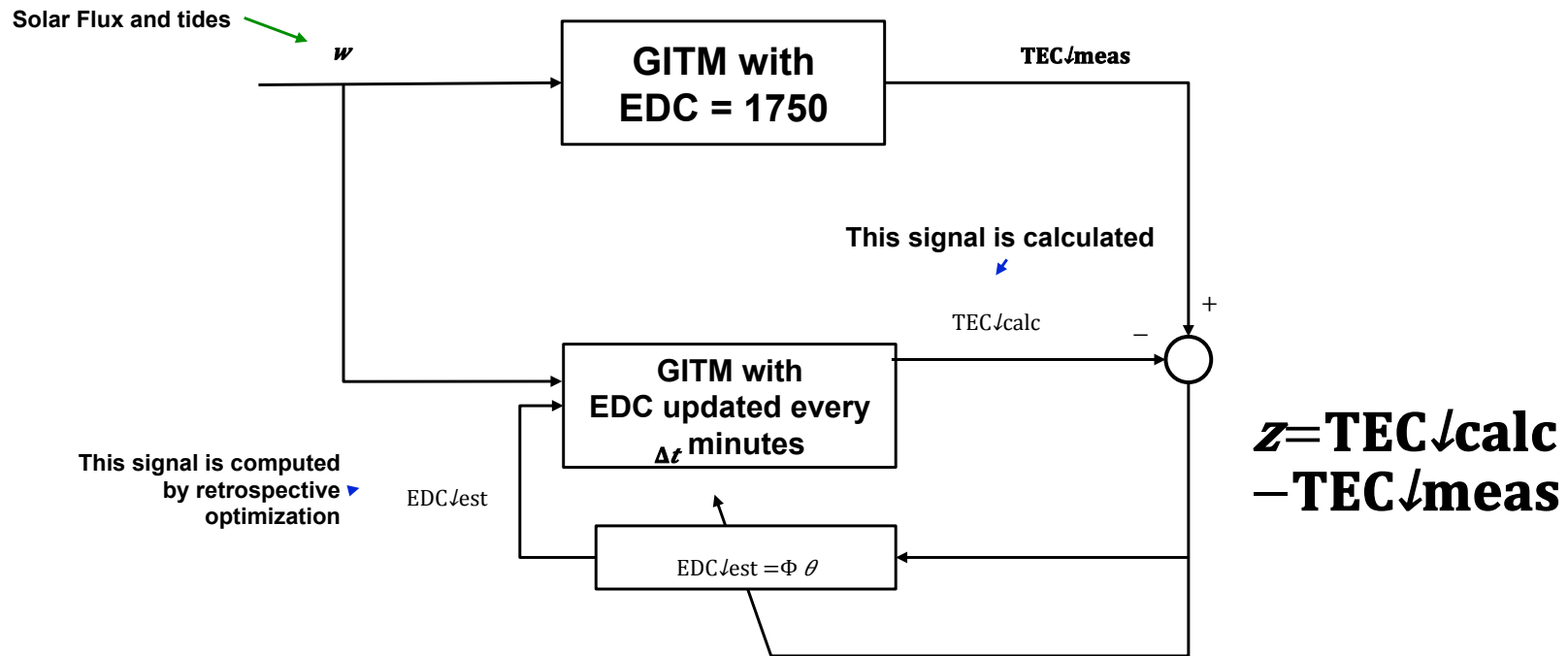
GPS/Met = Ground-Based GPS Meteorology.

RTIGS = Real Time International GNSS Service.

GNSS = Global Navigation Satellite Systems.

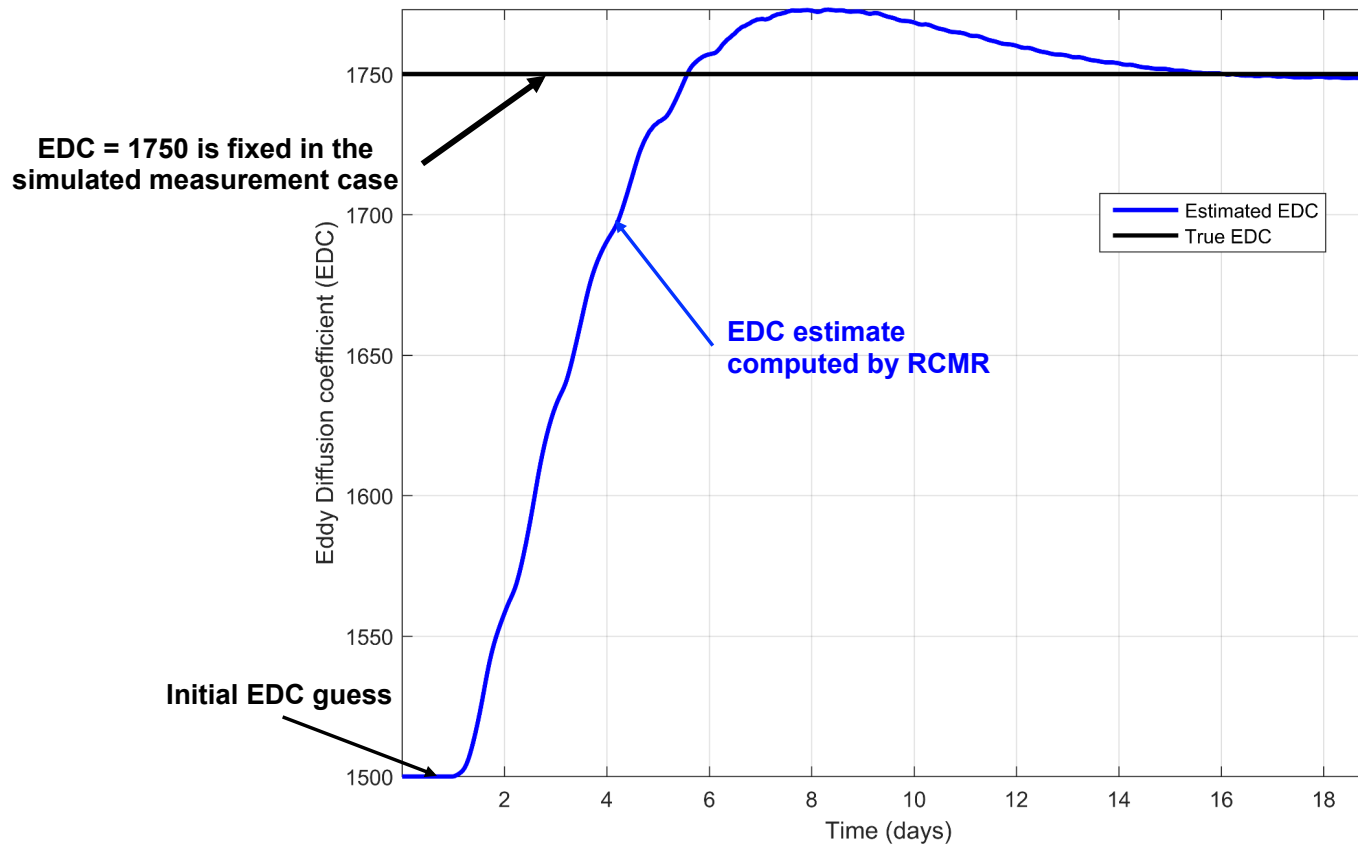


Estimate Eddy Diffusion Coefficient in GITM using Total Electron Content



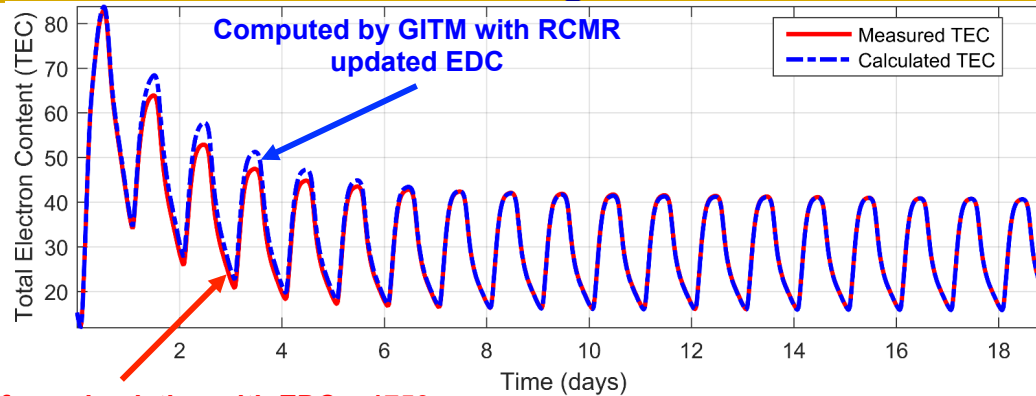


Estimate Eddy Diffusion Coefficient in GITM using Total Electron Content

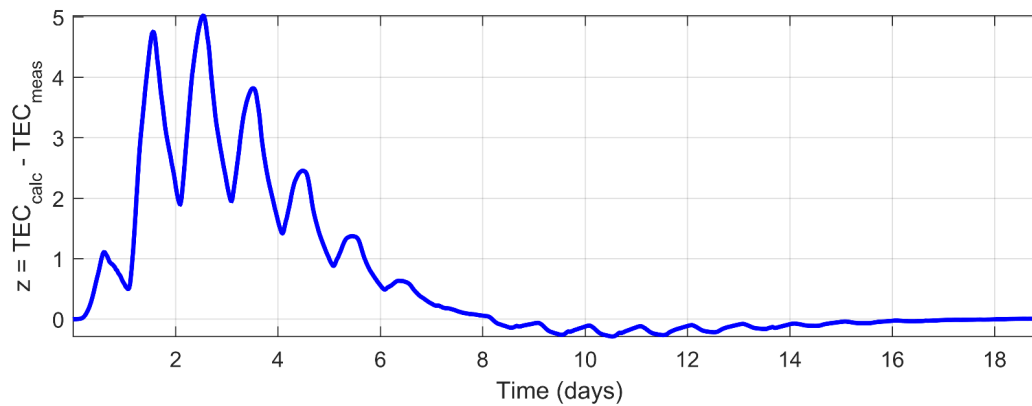




Estimate Eddy Diffusion Coefficient in GITM using Total Electron Content



TEC is measured at
a fictional TEC
station near Somalia





RCMR/RCAISE versus Standard Methods



- ❑ RCAISE does not provide statistical error measures
 - ❑ No estimate of covariance or probability distribution
 - ❑ Uses no priors---not Bayesian
 - ❑ Uses no ensemble---only a single simulation
- ❑ Uses only linear least squares techniques
 - ❑ Requires no adjoint code (none is available for GITM)
- ❑ Computationally inexpensive
 - ❑ Adds minutes to multi-hour ensemble data assimilation
 - ❑ But requires estimates of H's---determined by numerical testing
- ❑ May be useful as an adjunct to ensemble codes
 - ❑ For model refinement or input estimation in strongly driven systems-----
systems whose evolution is primarily due to external inputs



- ❑ RCMR requires minimal modeling information (H values)
 - ❑ Since no analytical model is available, this modeling information has been found by numerical testing
 - ❑ For EDC estimation this is tedious
 - ❑ We seek an efficient technique for concurrent optimization

- ❑ For adaptive control we have developed concurrent optimization
 - ❑ Frantisek Sobolic, Ankit Goel, Dennis S. Bernstein, " Retrospective-Cost Adaptive Control Using Concurrent Controller and Target-Model Optimization," submitted to ACC 2016.



Questions?