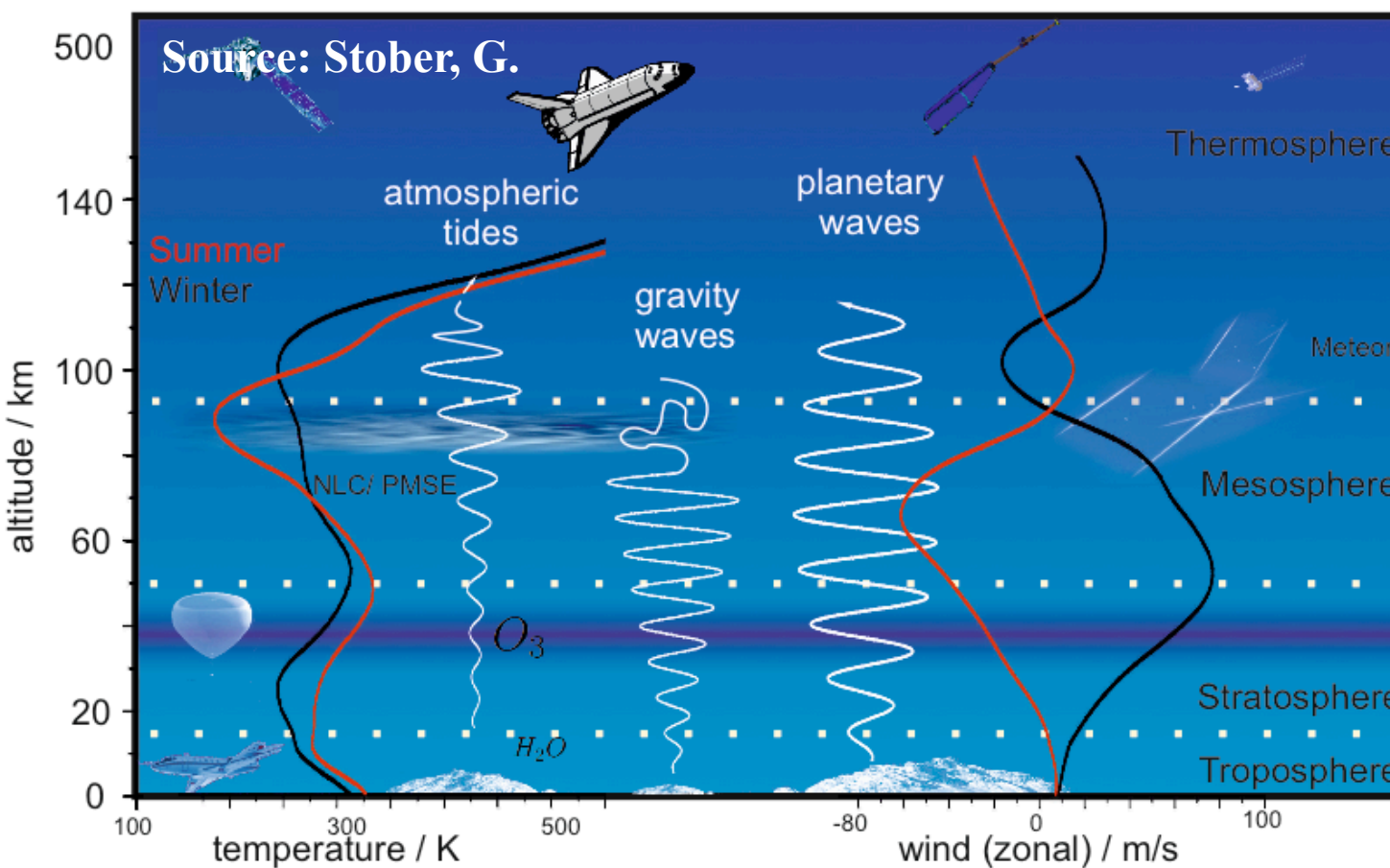


Motivation

- Variability in the middle atmosphere is driven by a variety of **small and large scale** atmospheric waves.
- Specular Meteor Radars (SMRs) have been used for decades to study the middle atmosphere dynamics but with limited time, horizontal and vertical resolution due to the **limited number of meteor detections**



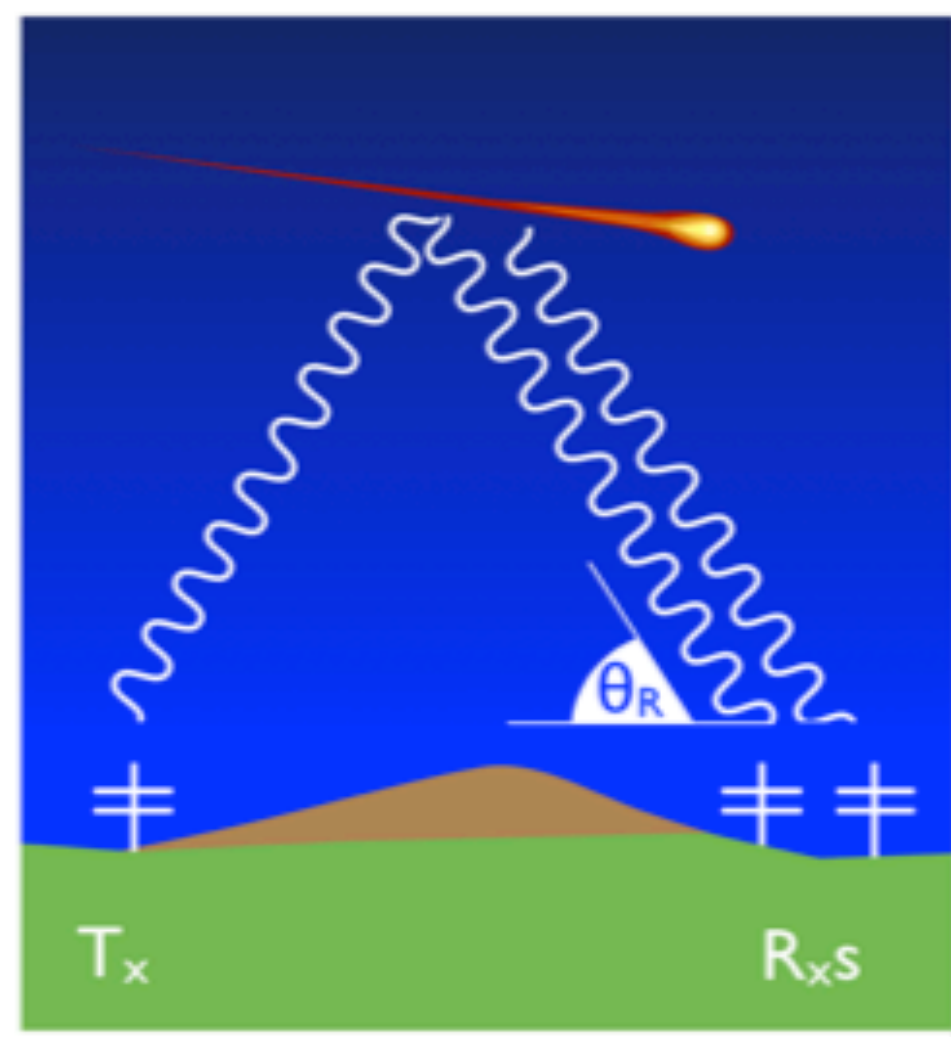
SMR: low resolution in time and space => not sensitive to small-scale wave dynamics

SMR networks allow to increase the number of meteor detections and improve resolution in time and space. Not all meteors are usable. **New simple and scalable SMR networks to increase the meteors' detections and to improve the measurement accuracy!!**

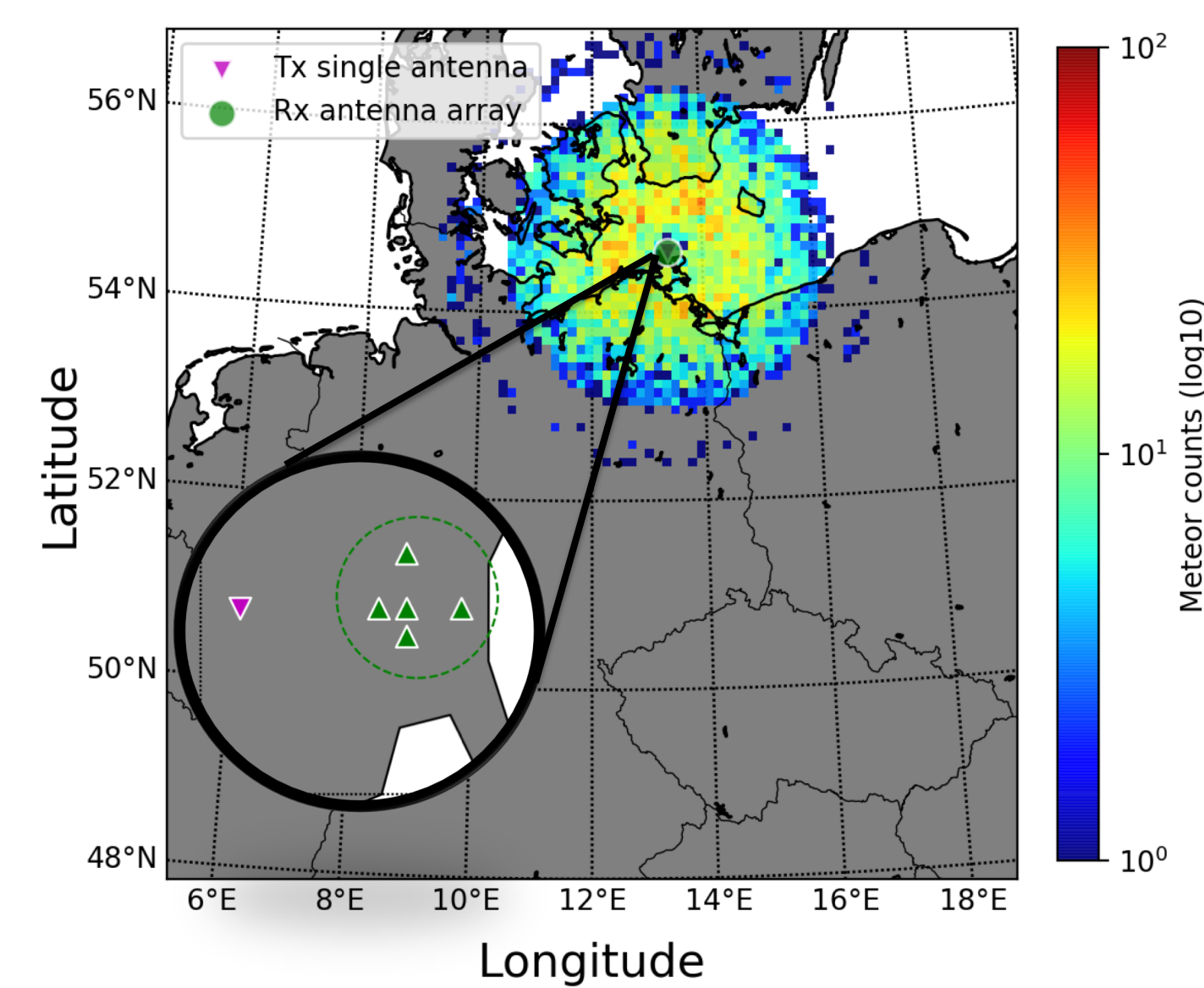
Background

Typical SMR (SIMO radar)

SIMO radar



Meteor map distribution

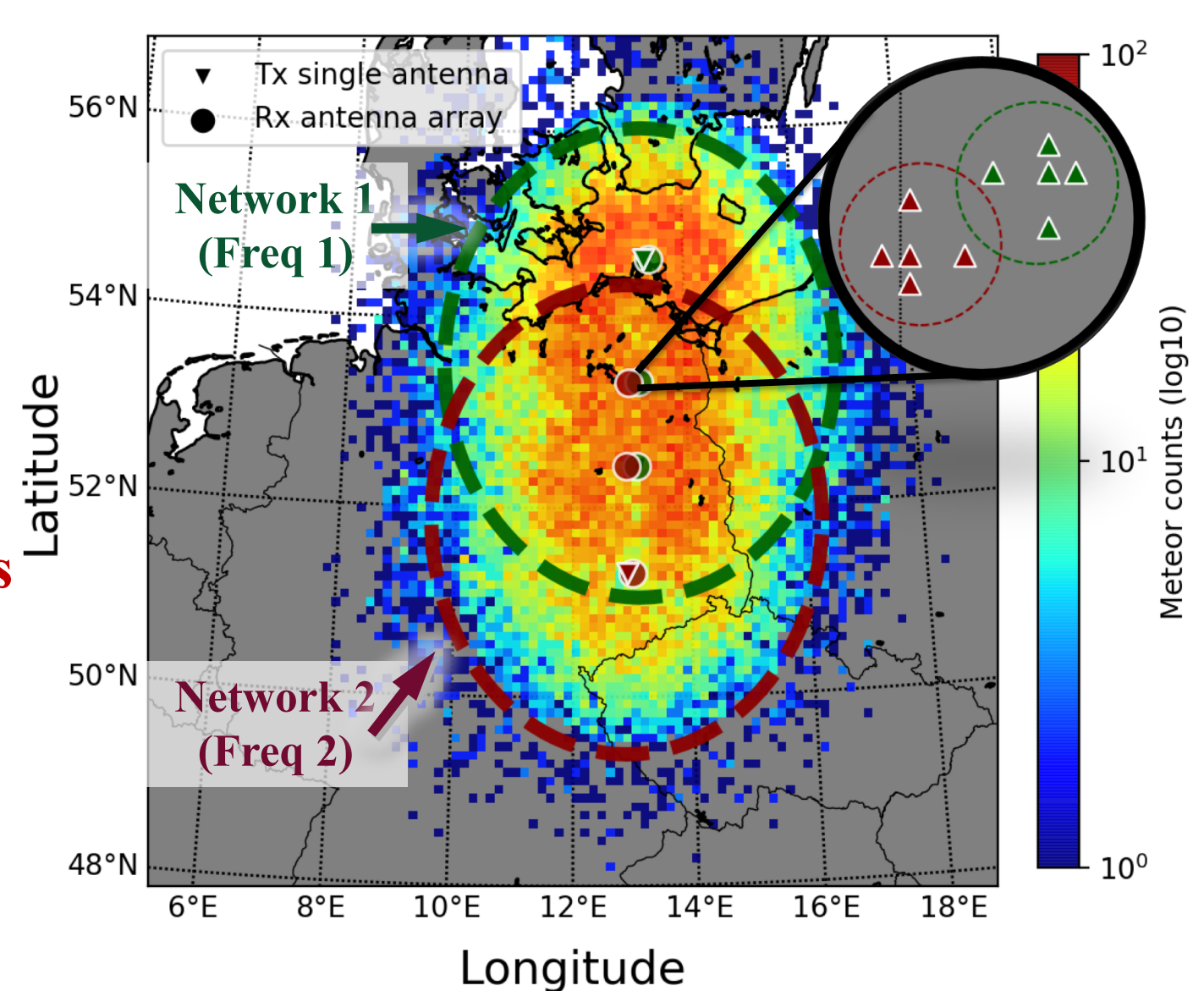


- SIMO (Single-Input Multiple-Output): multiple Rx antennas (antenna array) to estimate θ_R (angle of arrival = meteor's location).

- Limited number of meteor detections.**
- Meteors with low elevation angles removed**
- Mean winds can be estimated

SMR networks based on SIMO

Meteor map distribution



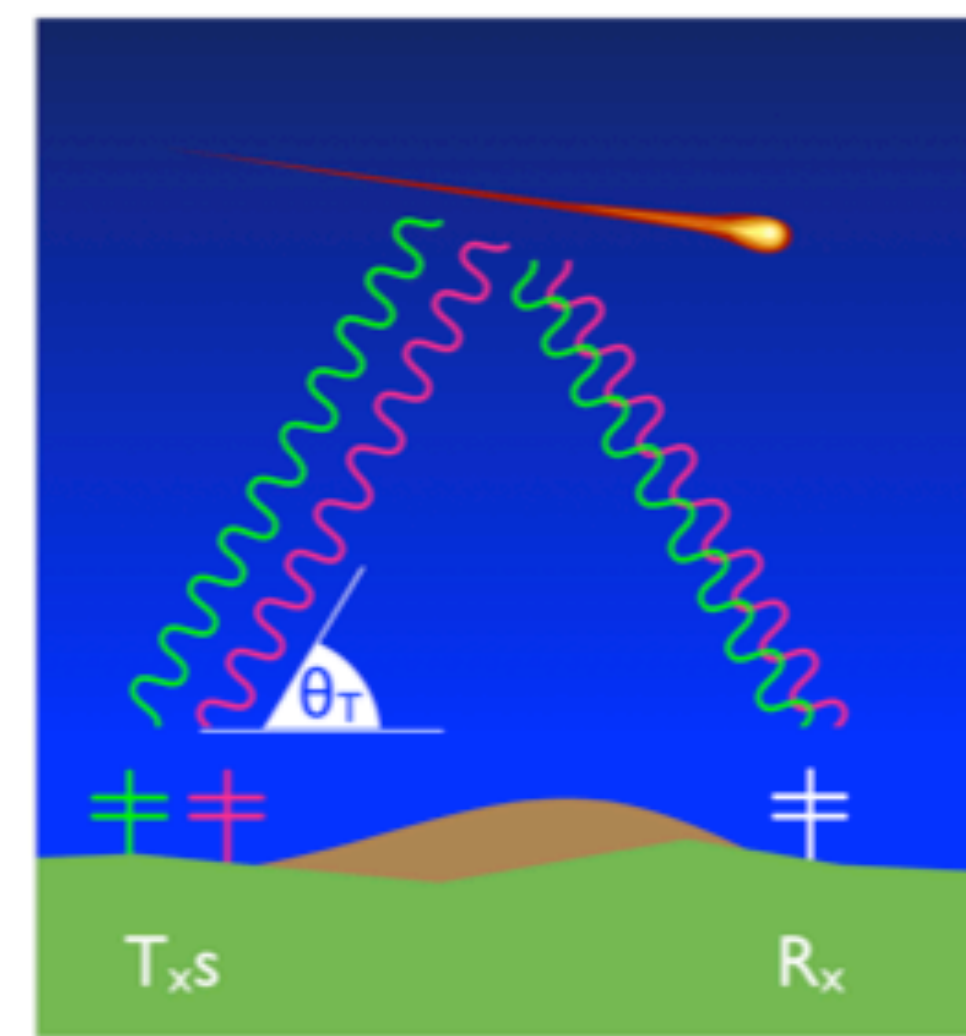
- Meteor counts increases by adding Rx sites around the Tx sites (Network).
- Area coverage increases by adding new networks (Tx + Rx).
- 3D wind fields can be estimated.**
- Networks (Tx) are isolated by using different frequencies (diversity on Tx).
- Frequency diversity does not allow Rx (from Network 1) listen the Tx (from Network 2)**
- Rx sites require large space.**
- Tx sites require high power.** [Stober and Chau 2015]

SMR networks increase number of meteor detections but they are not scalable.

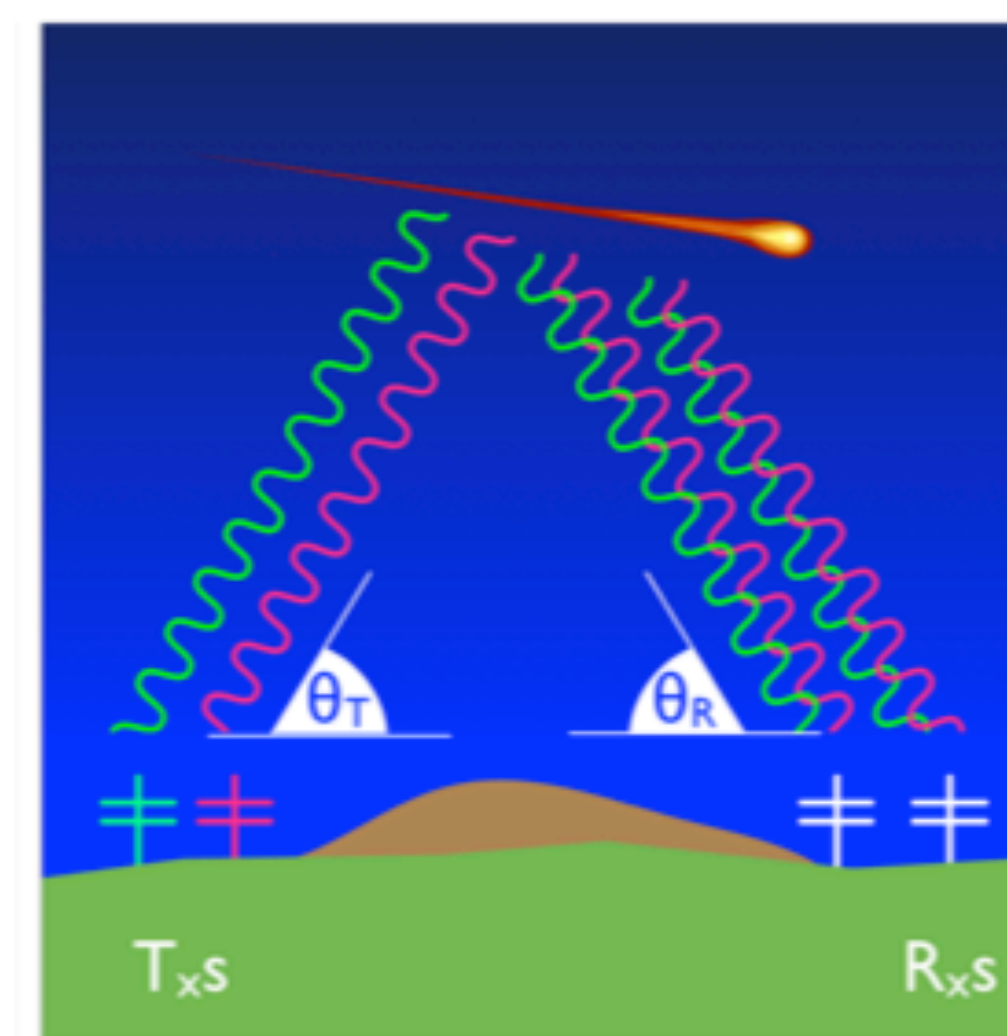
Our SMR network based on MIMO => Scalable (All Rx sites listen all Tx) and simple (complexity located only in the Tx side)

SMR network based on (coherent) MIMO

MISO radar



MIMO radar

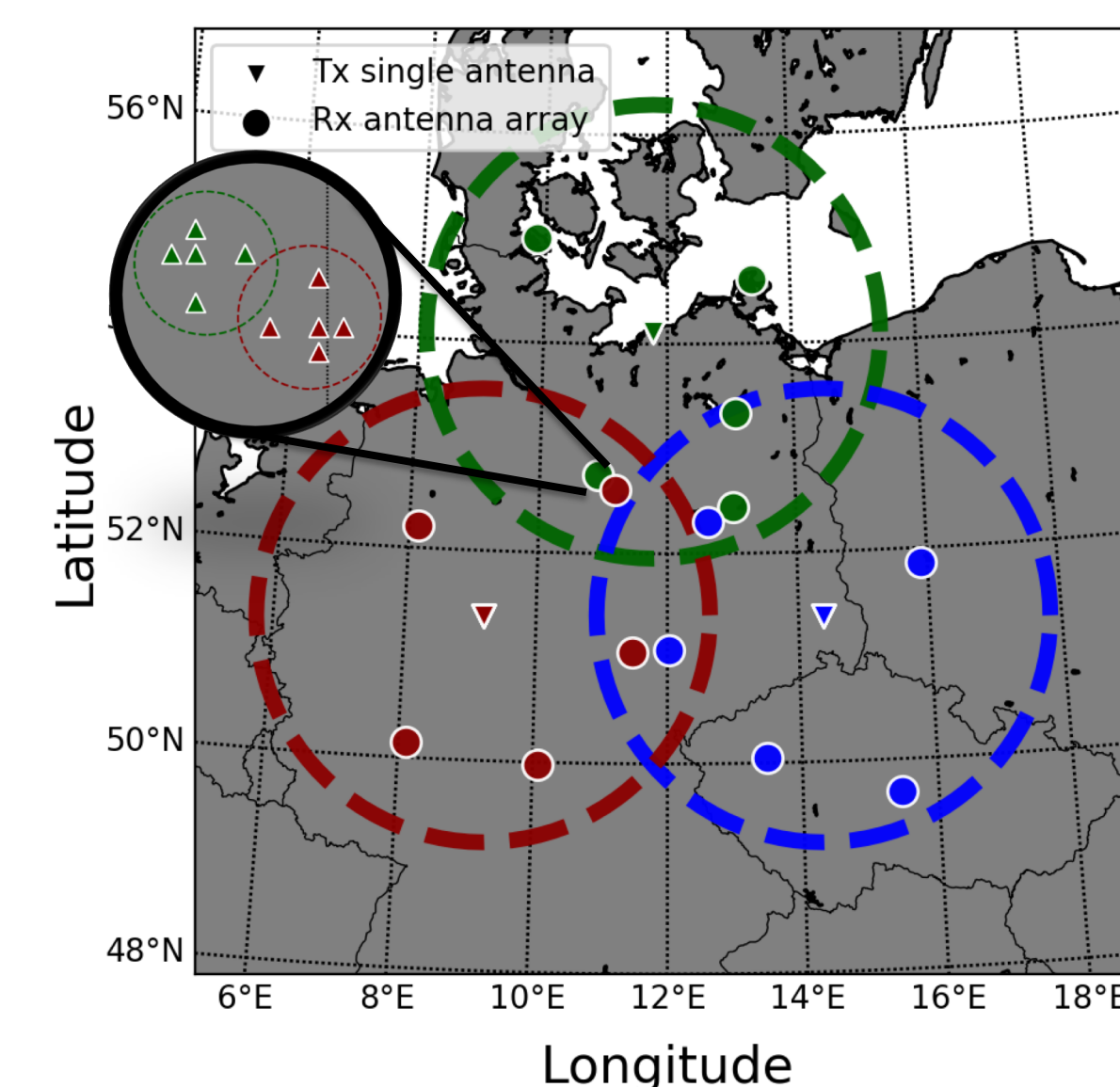


- MISO (Multiple-Input Single-Output): multiple Tx antennas to estimate θ_T (angle of departure).
- MIMO (Multiple-Input Multiple-Output): multiple Tx and Rx antennas to estimate θ_R and θ_T , respectively.

For MISO or MIMO:

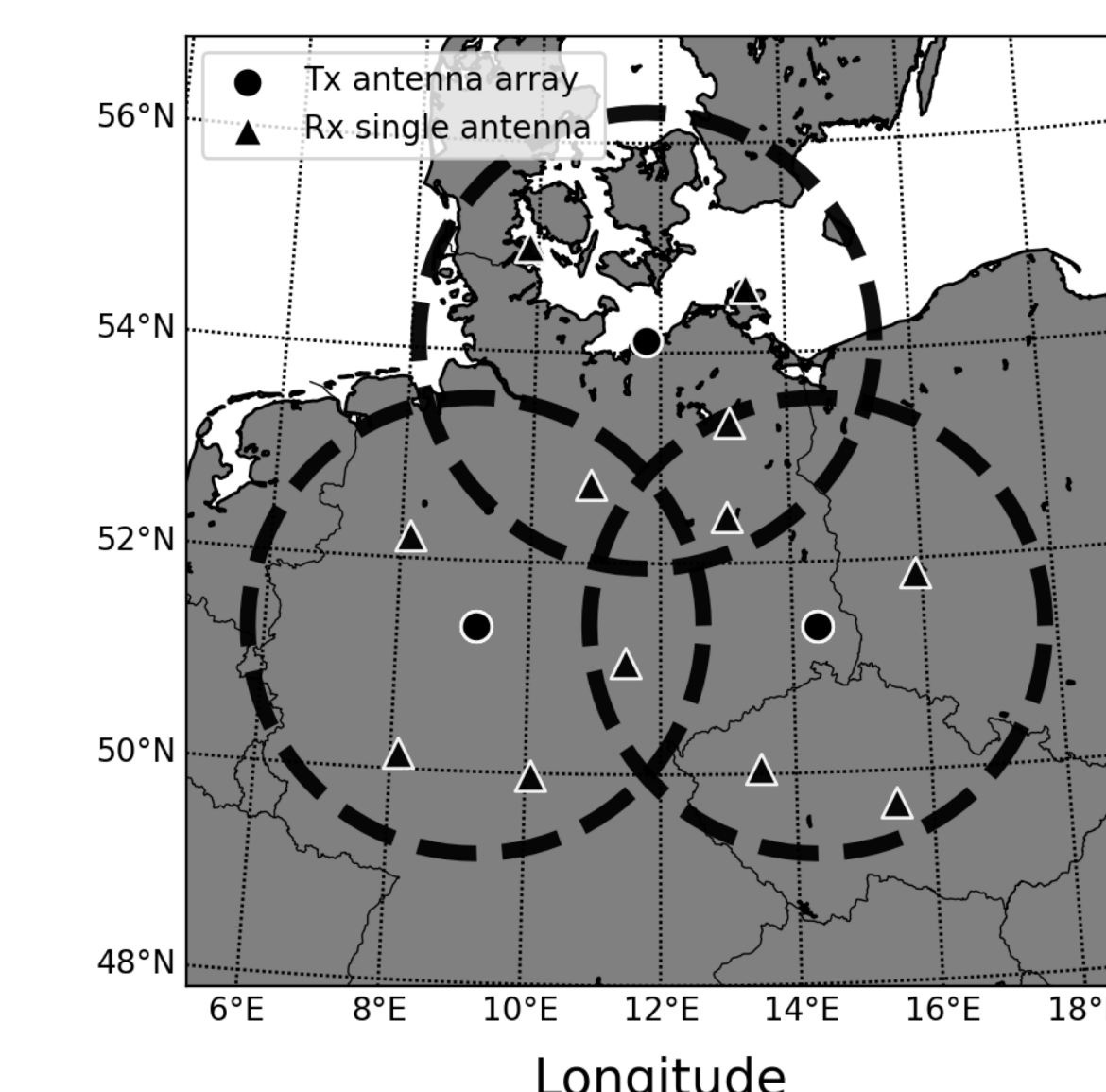
- Recovery (decoupling) of transmitted signals on the Rx side requires the use of orthogonal waveforms on transmission.
- CW radar + pseudo random coded sequences (quasi-orthogonal signals) allows to minimize cross-interference between Tx.
- Meteors' locations can be estimated respect to the Tx side (θ_T).

SMR network based on SIMO



- Meteor's location respect to the Rx site.
- Different networks use different frequencies.
- New networks (Tx) require new Rx sites.**
- Rx sites require multiple antennas (large space and various digital receivers).**
- Use of a broad spectrum bandwidth.**
- Tx sites require one single antenna.**
- No interference between Tx**

SMR network based on MISO/MIMO



- Meteor's location respect to the Tx site.
- Different networks use different waveforms (pseudo-random sequences)
- New networks (Tx) can use previous Rx sites.**
- Rx sites require one single antenna and one digital receiver (small space). Ideal to be installed in school, gardens.**
- One single frequency for all networks.**
- Tx sites require multiple antennas.**
- High interference between Tx.**

MISO with waveform diversity:

- Complexity moved to the Tx side.
- Rx sites are simple and can be installed in schools, gardens, etc.**
- Only one working frequency needed.**

MIMO with waveform diversity:

- With MIMO, meteor location estimated respect to both the Tx and Rx site (more accurate). Number of usable meteors increases.
- Problem: High cross-interference between transmitted waveforms!!**

Signal recovery in a MIMO-SMR network

MIMO-SMR: System model

$$y = \Phi X + \eta$$

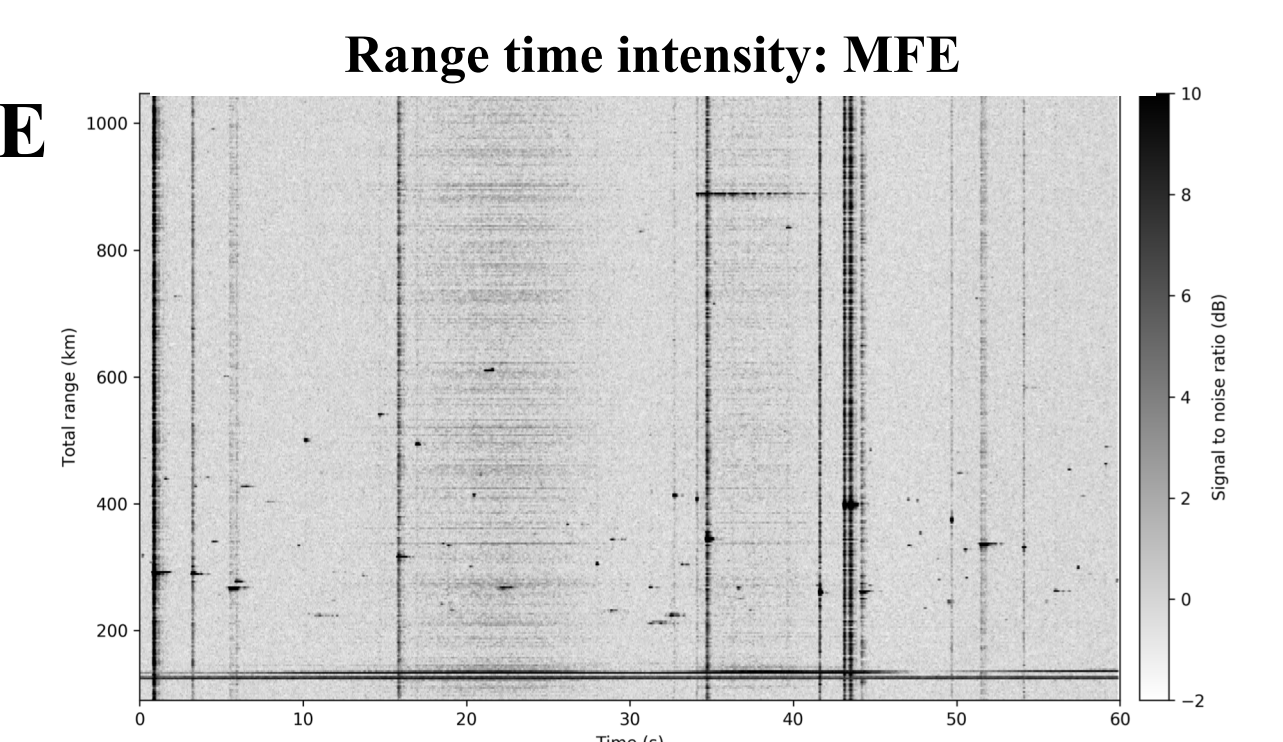
where:
 $y \in \mathbb{C}^M$: measurement vector at Rx.
 $x_j \in \mathbb{C}^R$: scattered echo from transmitter j .
 $A_j \in \mathbb{C}^{M \times R}$: sensing matrix due to waveform j .
 $N = t \times R$.

High interference and an undetermined problem $M < N$

Traditional Matched Filter estimator (MFE)

Nyquist requires a sampling twice the signal bandwidth. MFE requires more measurements than unknowns ($M > N$)

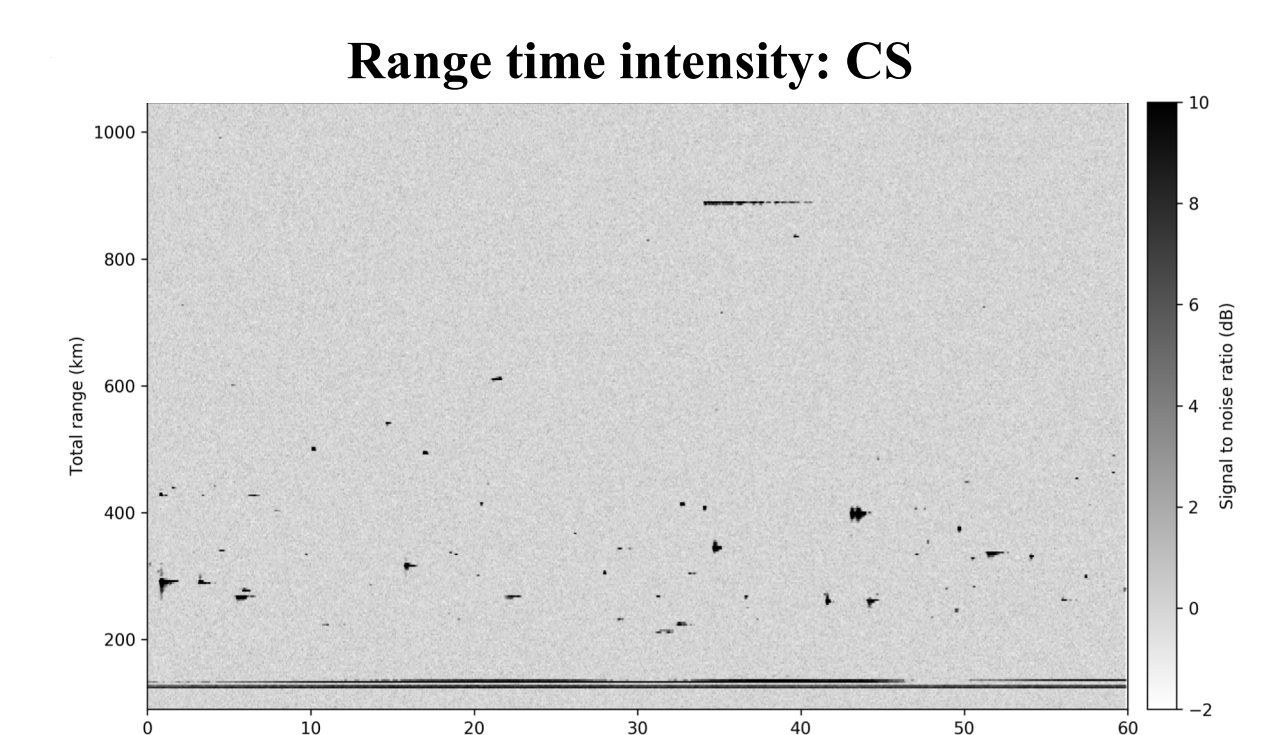
$$\hat{X}^{MFE} = \Phi^H y,$$



Compressed sensing approach (CS)

CS claims that a signal can be recovered even when $M < N$, if the signal X is K -sparse and the sensing matrix ϕ satisfies the RIP condition.

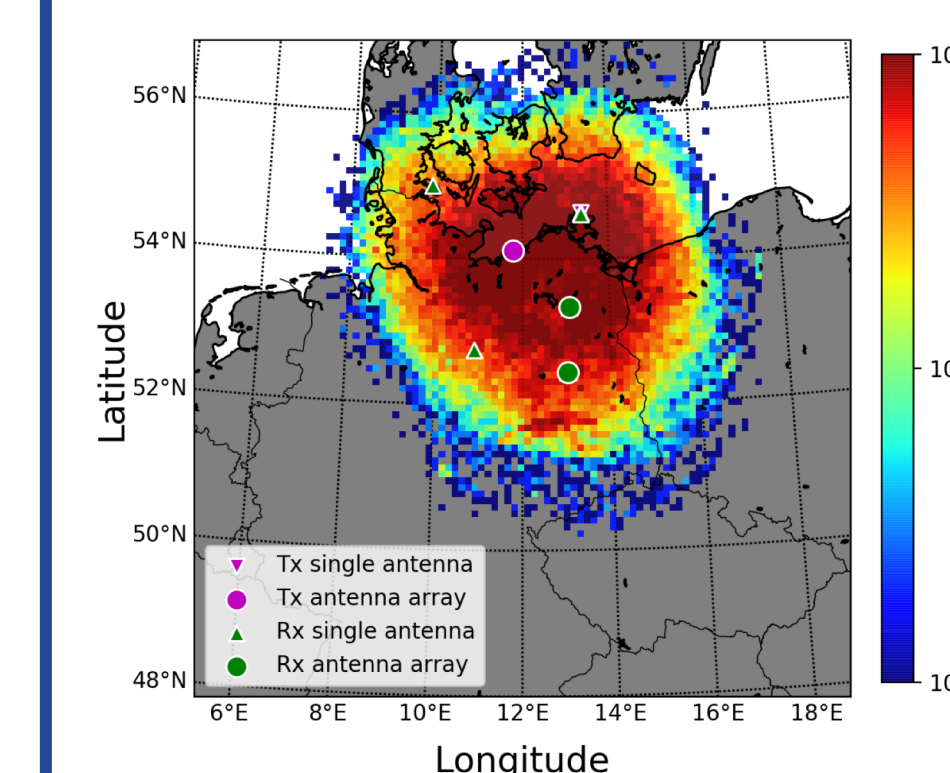
$$\hat{X}^{CS} = \arg \min_X \|y - \Phi X\|_2^2, \text{ subject to } \|X\|_0 < K,$$



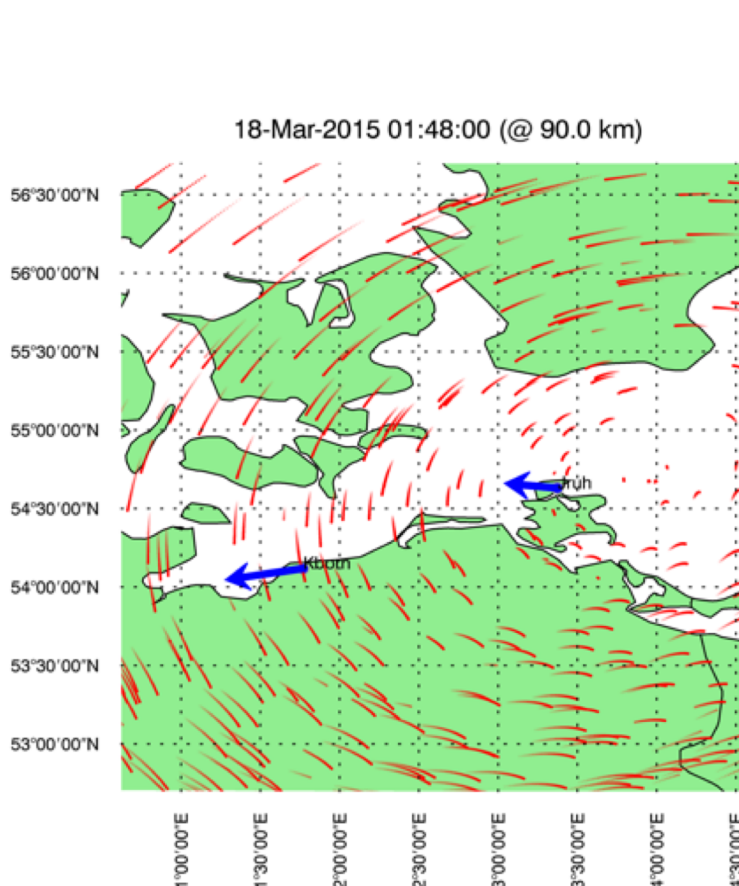
- CS allows us to recover meteor signals in a interference environment even when the number of measurements is much less than the number of unknowns.**

Results and applications

SMR network based on MISO/MIMO

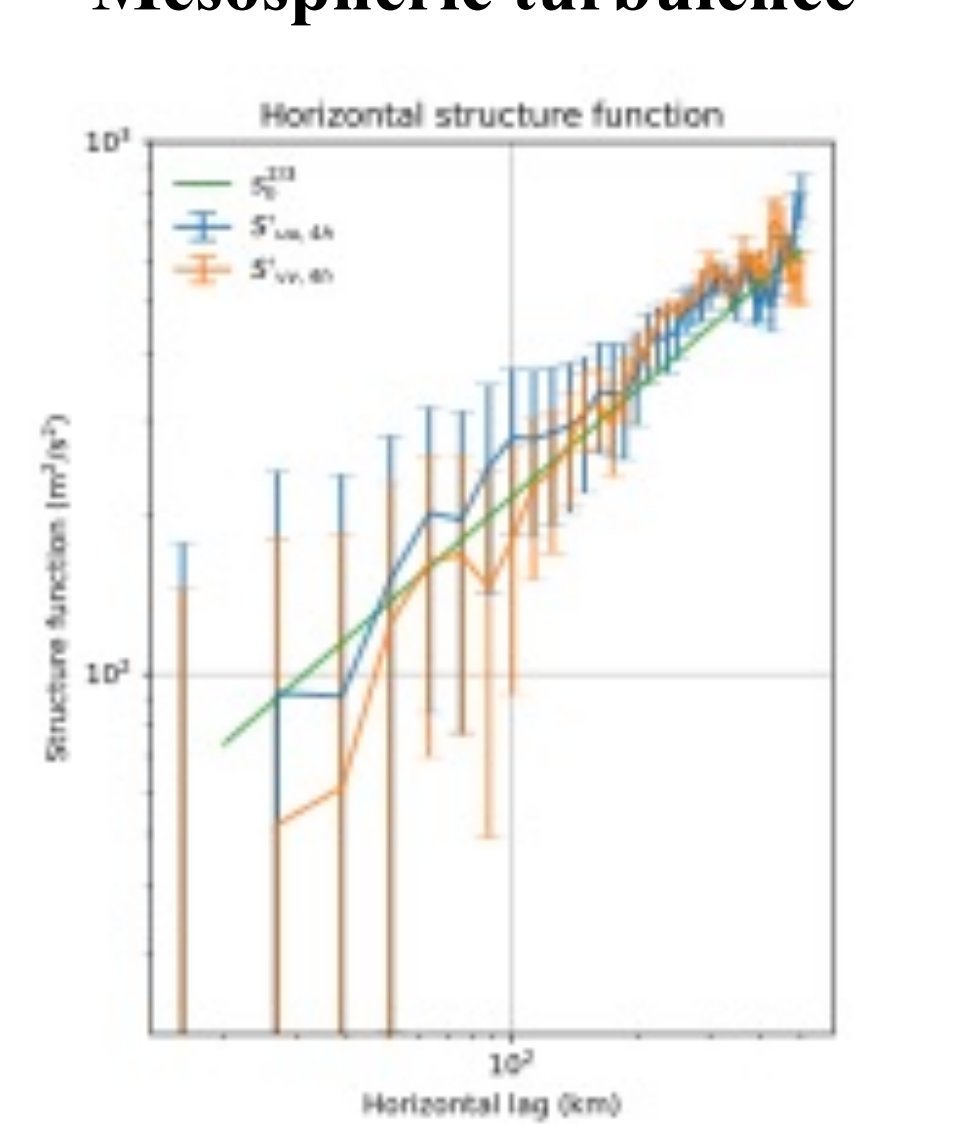


3D wind flow



SMR: mean wind
 SMR network: 3D wind field

Mesospheric turbulence



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Chau, J. L., Urco, J. M., Vierinen, J. P., Volz, R. A., Clahsen, M., Pfeffer, N., and Trautner, J.: Novel specular meteor radar systems using coherent MIMO techniques to study the mesosphere and lower thermosphere, *Atmos. Meas. Tech. Discuss.* 2019.

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