

***How can we investigate global
Magnetosphere-Ionosphere
coupling?***

***J. Gjerloev, S. Ohtani, R. Barnes, C. Waters, T.
Motoba, C. Olson***



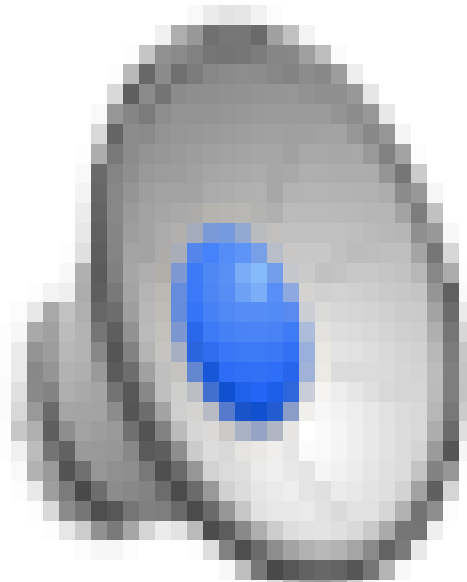
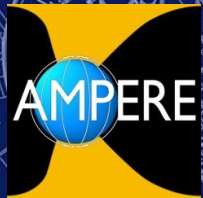
JOHNS HOPKINS
APPLIED PHYSICS LABORATORY

How can we investigate **global** Magnetosphere-Ionosphere coupling?



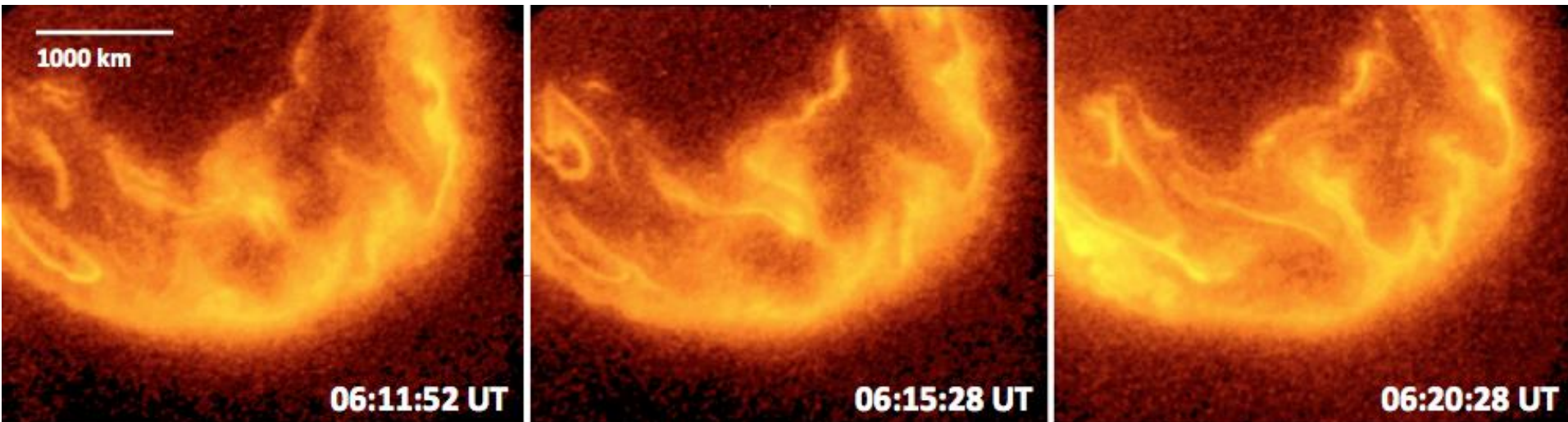
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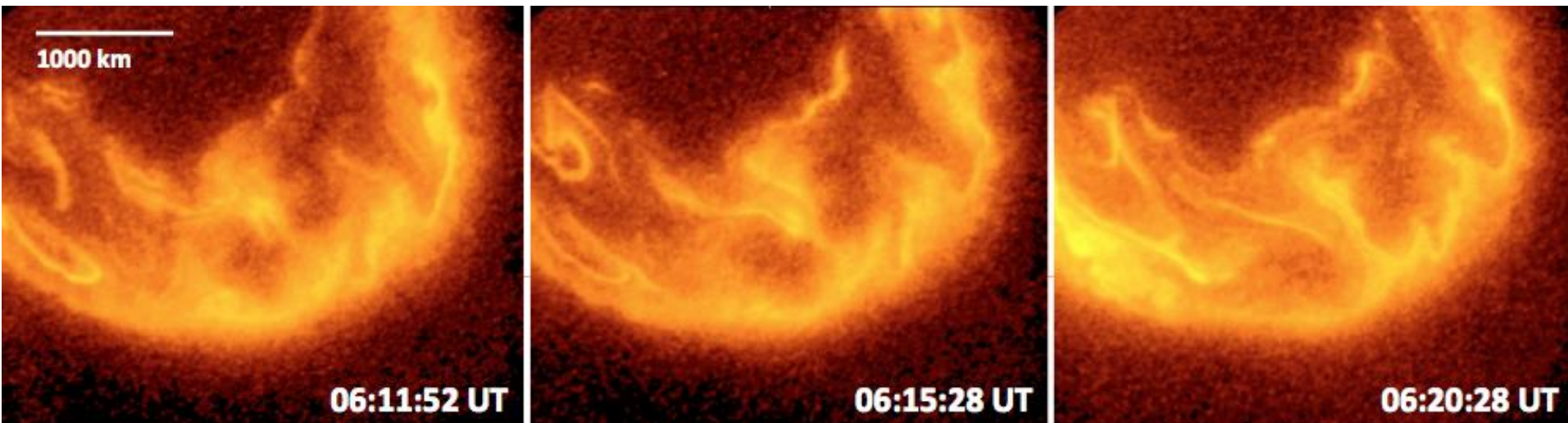
Outline

1. How do we derive global solutions from sparse data coverage?
2. What are the limitations of the global solutions?
 - Derived parameters
 - Processes/phenomena
3. The holy grail of M-I physics: Global, continuous and complete electrodynamic solutions.



Outline

1. **How do we derive global solutions from sparse data coverage?**
2. **What are the limitations of the global solutions?**
 - Derived parameters
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Deriving global solutions: What is the problem?

07 Jan 1997

02:32:00 - 02:33:00 UT

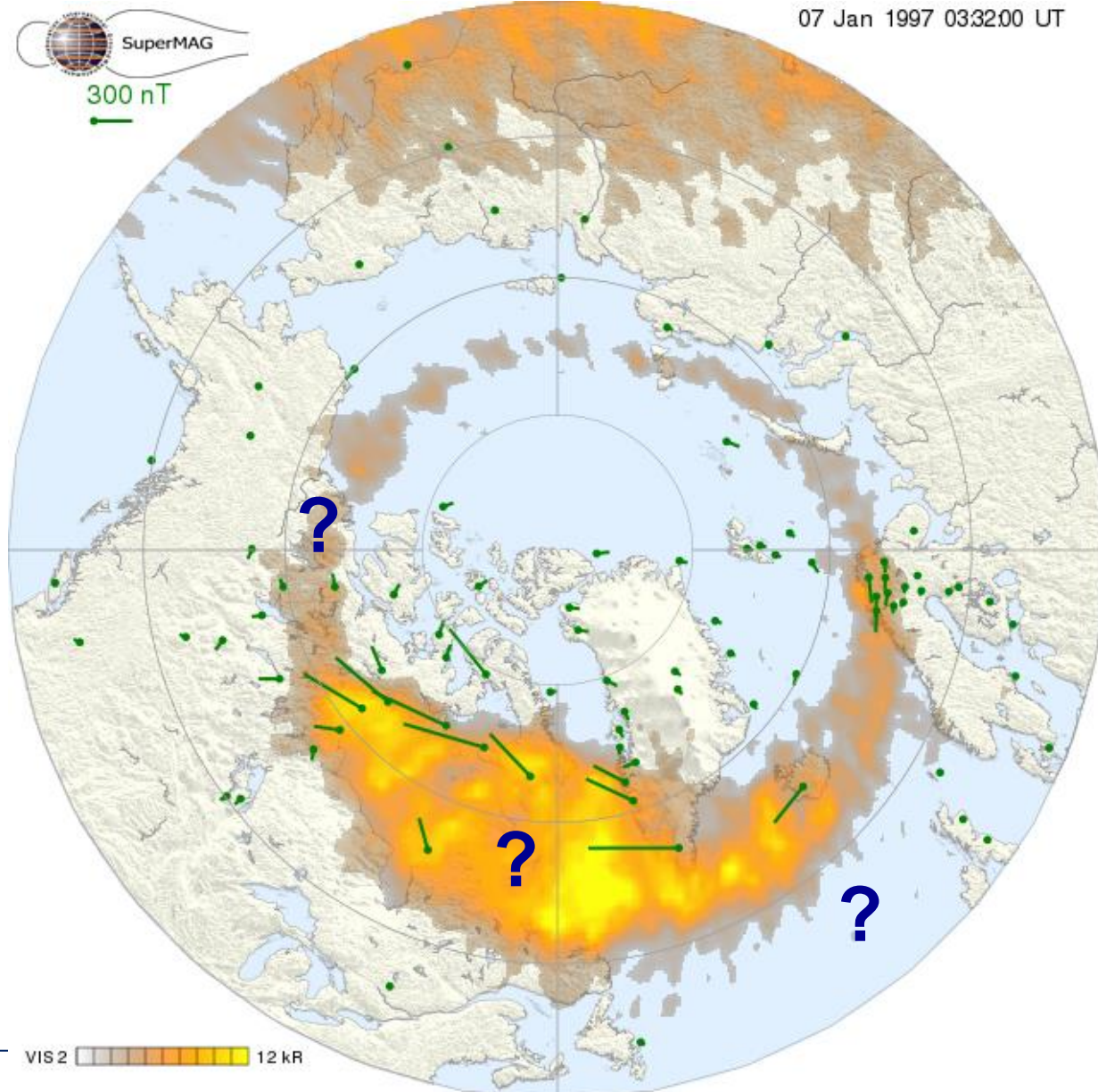
300 nT




- Challenges:**
- Spatial coverage
 - Temporal resolution

Deriving global solutions: What is the problem?

07 Jan 1997 03:32:00 UT



- Challenges:**
- Spatial coverage
 - Temporal resolution

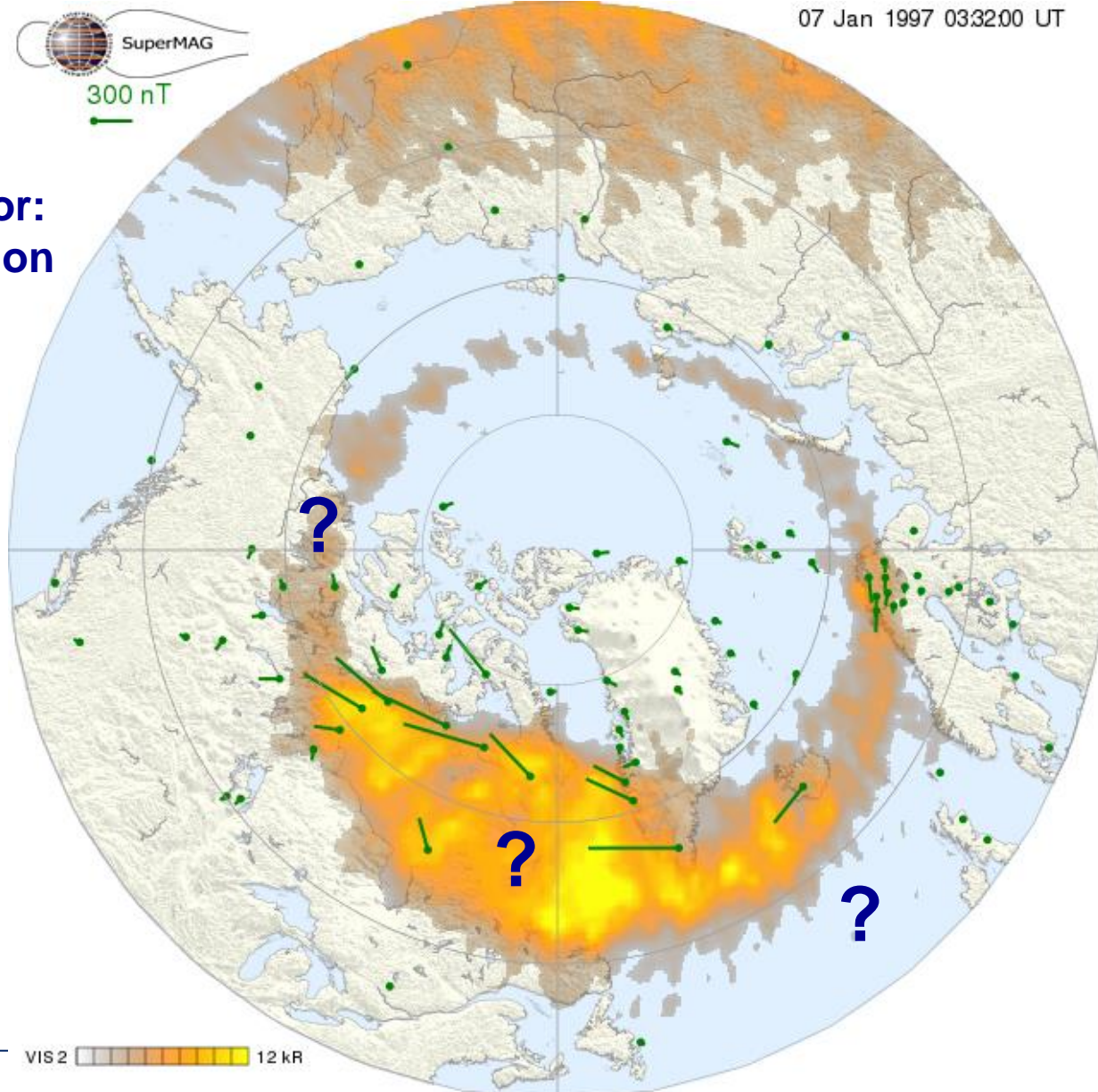
Deriving global solutions: Three approaches

07 Jan 1997 03:32:00 UT



Approach 1: No assumed knowledge of system behavior:
1) Simple spatial interpolation

Approach 2: Assuming knowledge of the system behavior
2) External driver
3) State descriptors



Approach 1: No assumed knowledge of system behavior

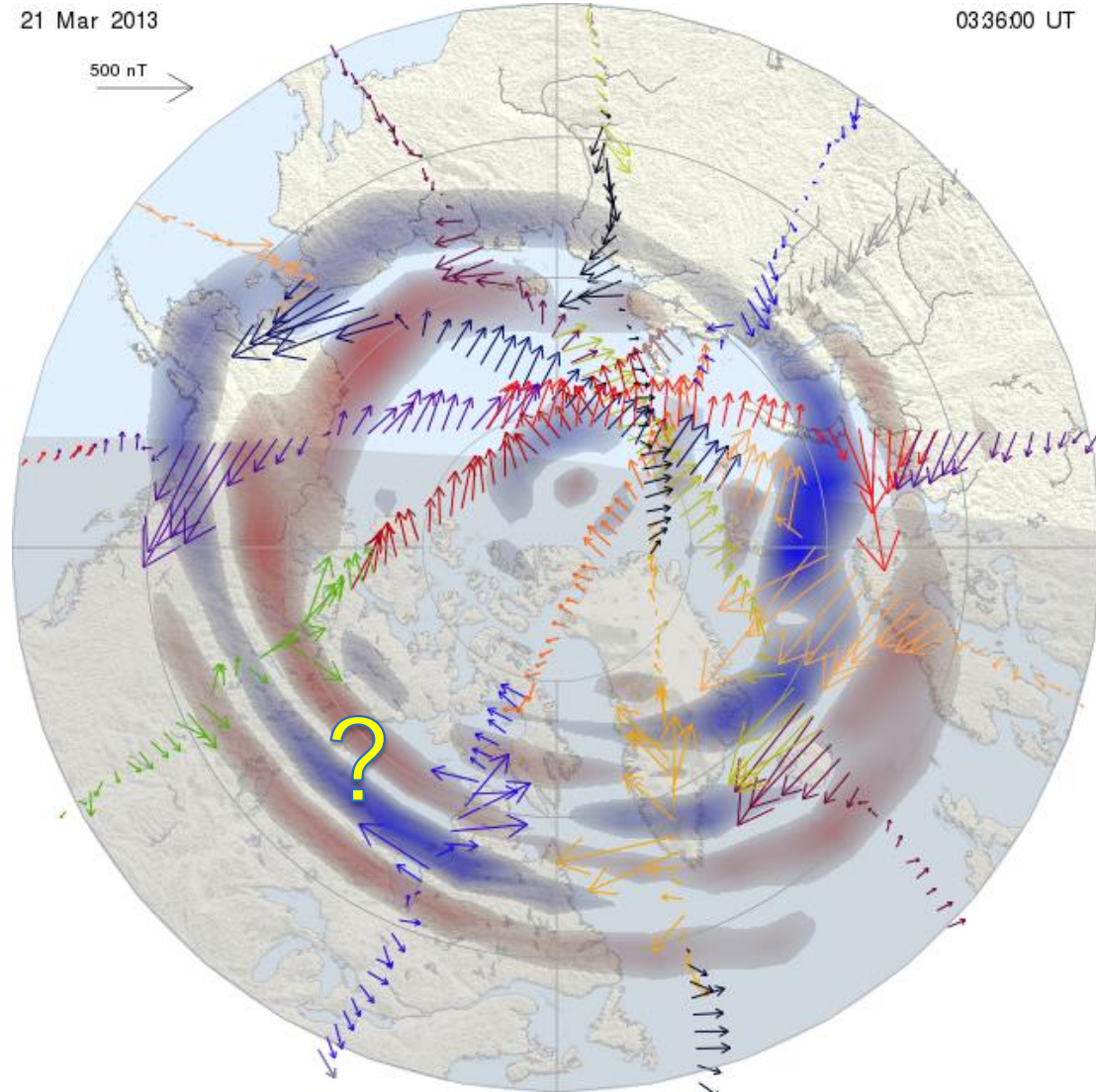
Simple Spatial Interpolation

Approach 1: No assumed knowledge of system behavior:
1) Simple spatial interpolation

Question: Are the scale sizes of the features larger than the spatial data gaps?

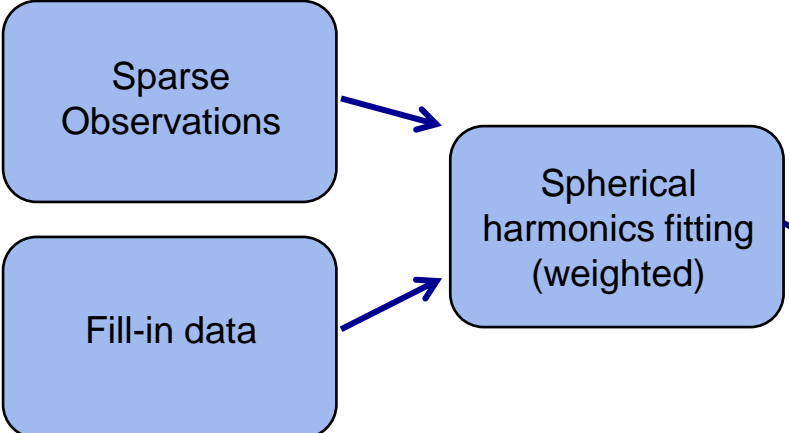
Answer: No/yes/maybe.

Depend on:
- science objective
- parameter

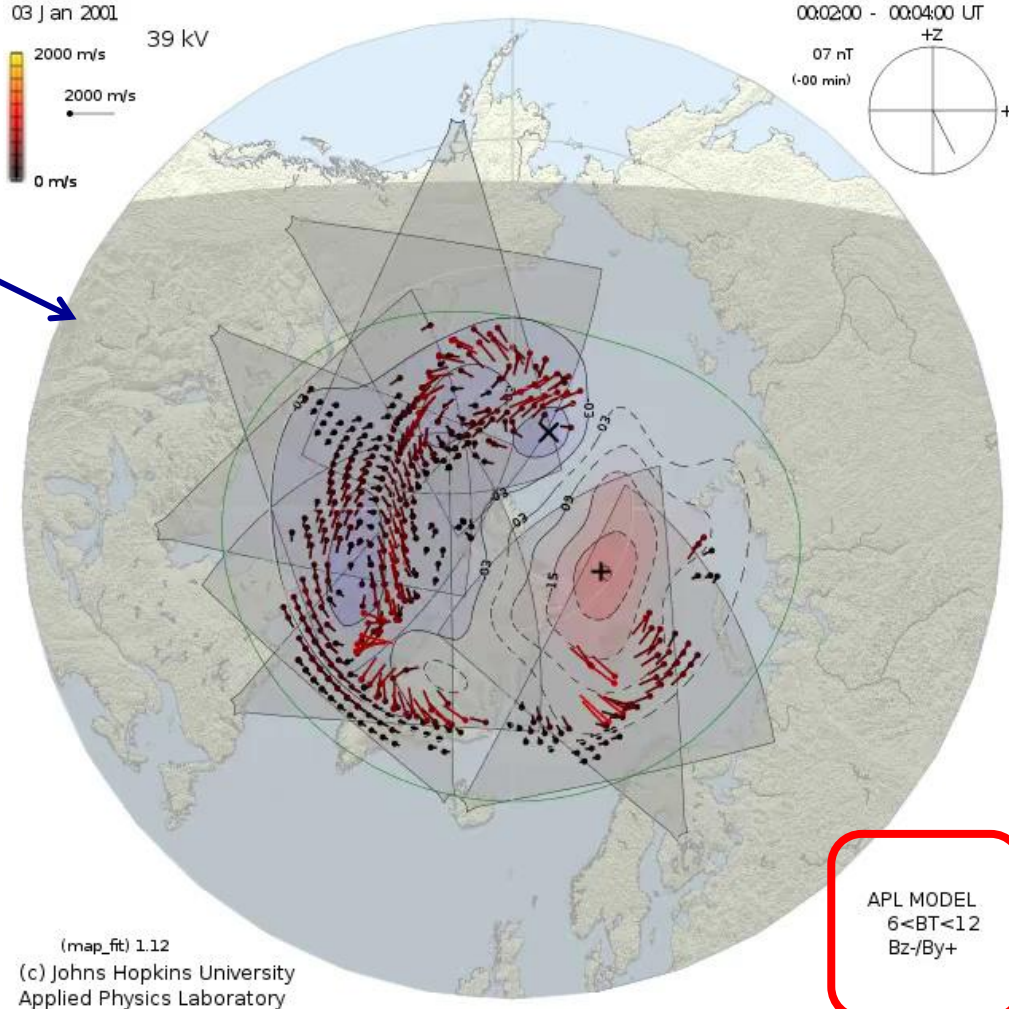
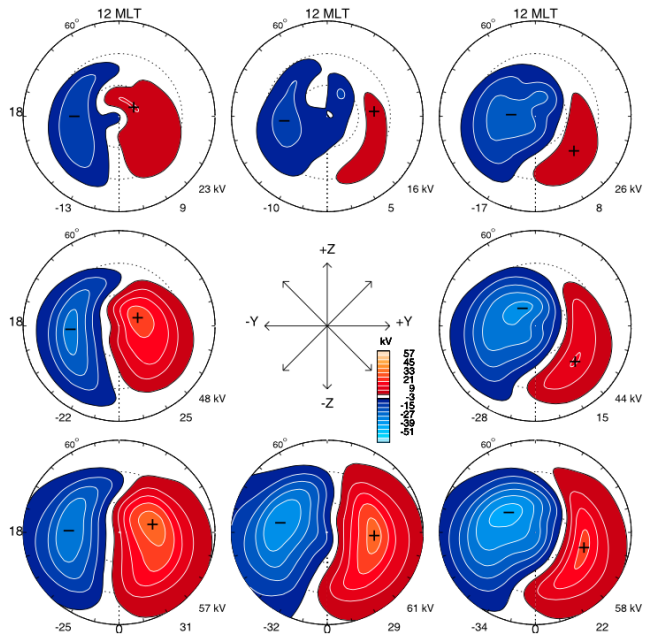


Approach 2: Assuming knowledge of the system behavior

External Drivers



Fill-in data are provided by discrete bins of solar wind driver:



Pettigrew et al. (2010)

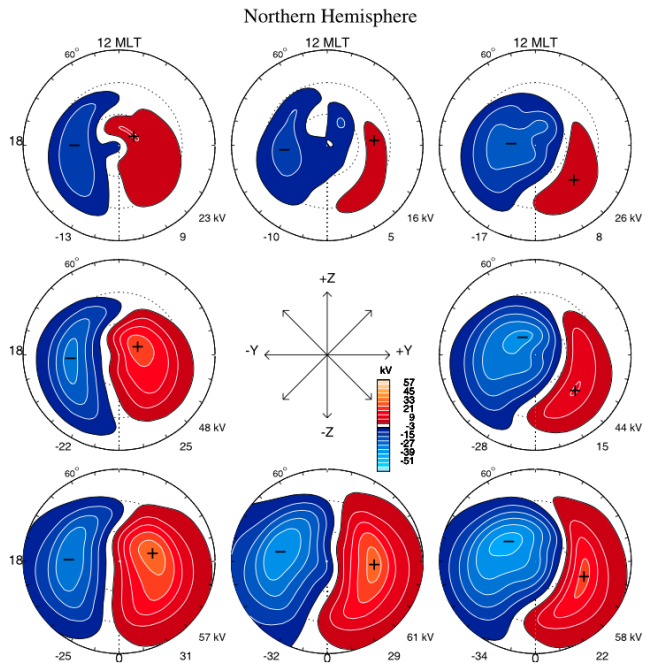
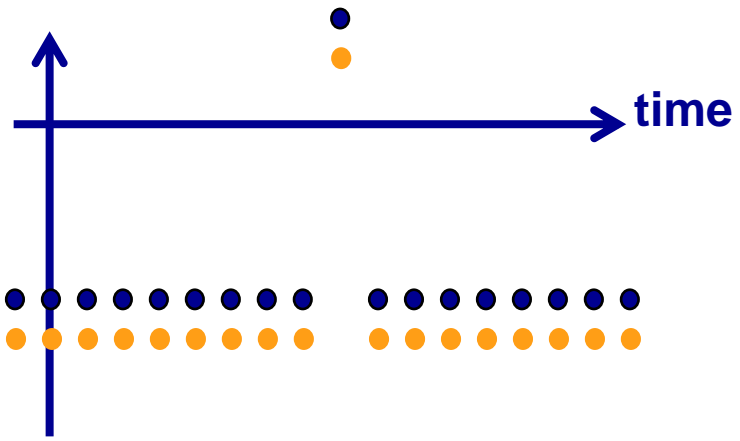
Approach 2: Assuming knowledge of the system behavior

External Drivers

Inherent complexities

- Delay (causality)
- M-I low pass filtering
- SW-M-I history
- M-I internal processes
- Predictability / system info

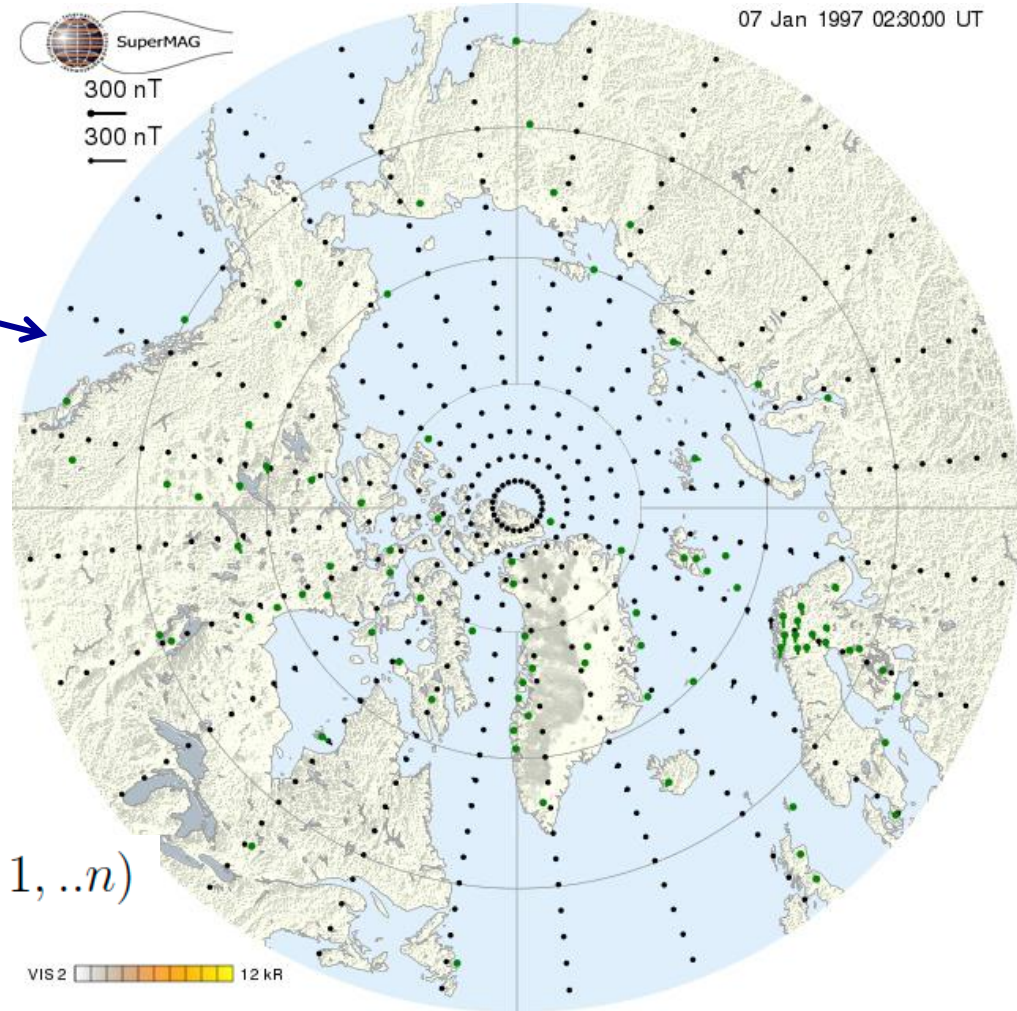
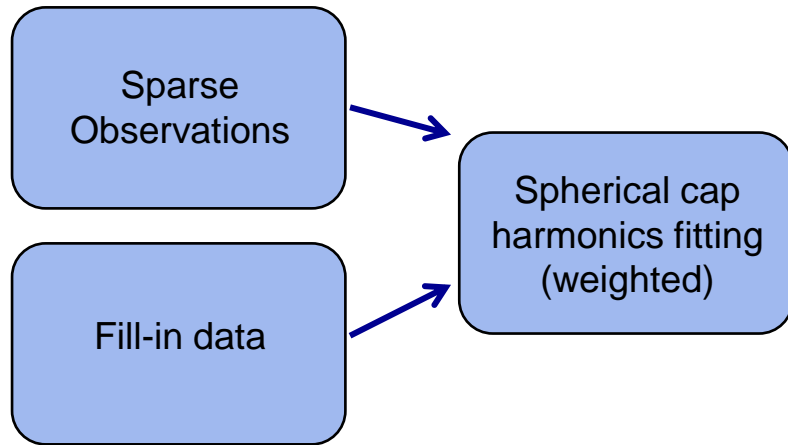
driver /
response



Pettigrew et al. (2010)

Approach 2: Assuming knowledge of the system behavior

State Descriptors



Fill-in data are provided by a multi-linear regression model:

$$y_i = \beta_0 + \beta_1 x_{1i} + \dots + \beta_k x_{ki} + \epsilon_i \quad (i = 1, \dots, n)$$

where β_k are the regression coefficients, x_{ki} are SuperMAG indices, and ϵ_i is the model errors.

Waters, Gjerloev, Dupont, Barnes, JGR, 2015

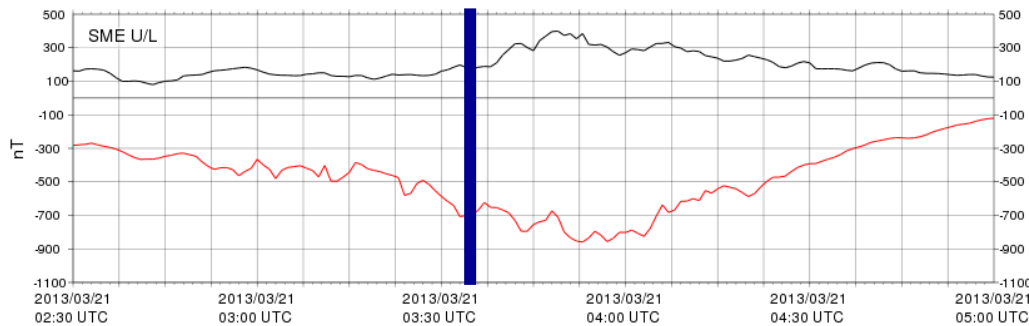
Approach 2: Assuming knowledge of the system behavior

State Descriptors

Inherent complexities

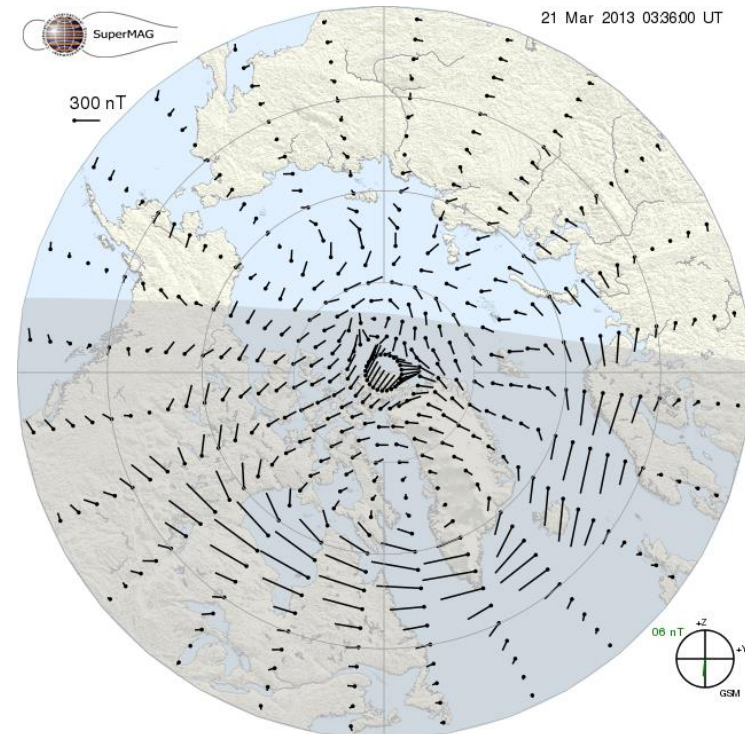
- Can a scalar describe a 2D or 3D system?
- What does the index even mean?
- Does it have appropriate temporal resolution?
- Does it have appropriate spatial resolution?

Rostoker [1972] concluded that in order to avoid the obvious pitfalls for the AE index it should be used only in statistical studies rather than individual events.



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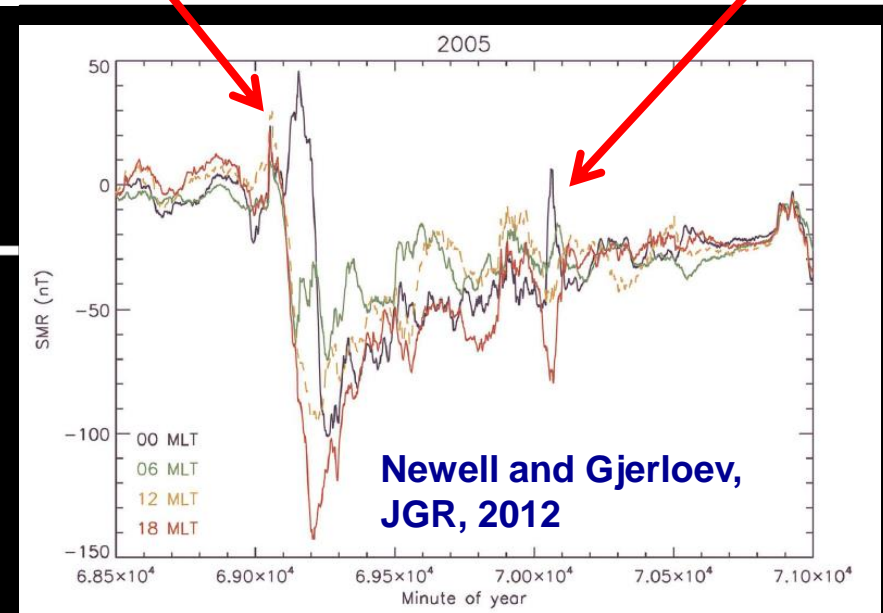
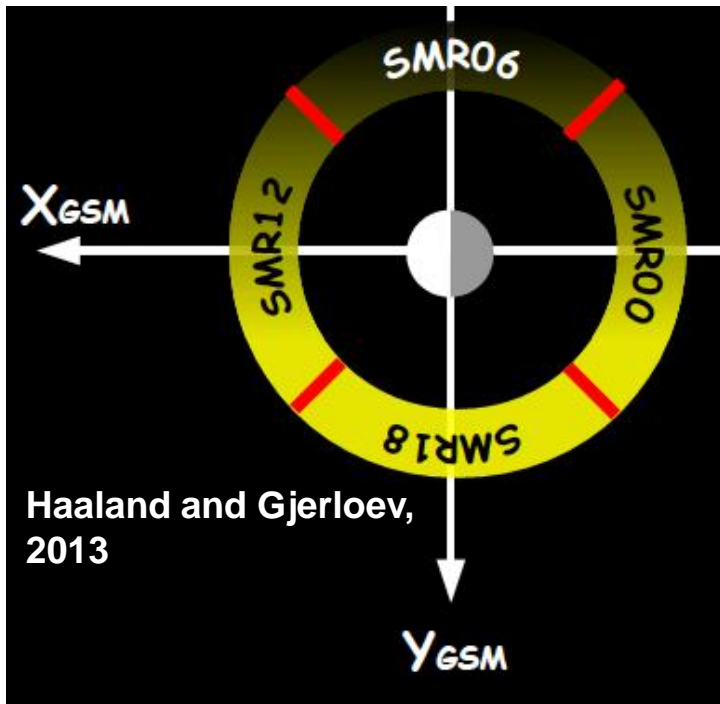


Approach 2: Assuming knowledge of the system behavior

State Descriptors

$$\bar{B}_{measured}(\bar{r}, t) = \bar{B}_{main}(\bar{r}) + \bar{B}_{noise}(t)$$

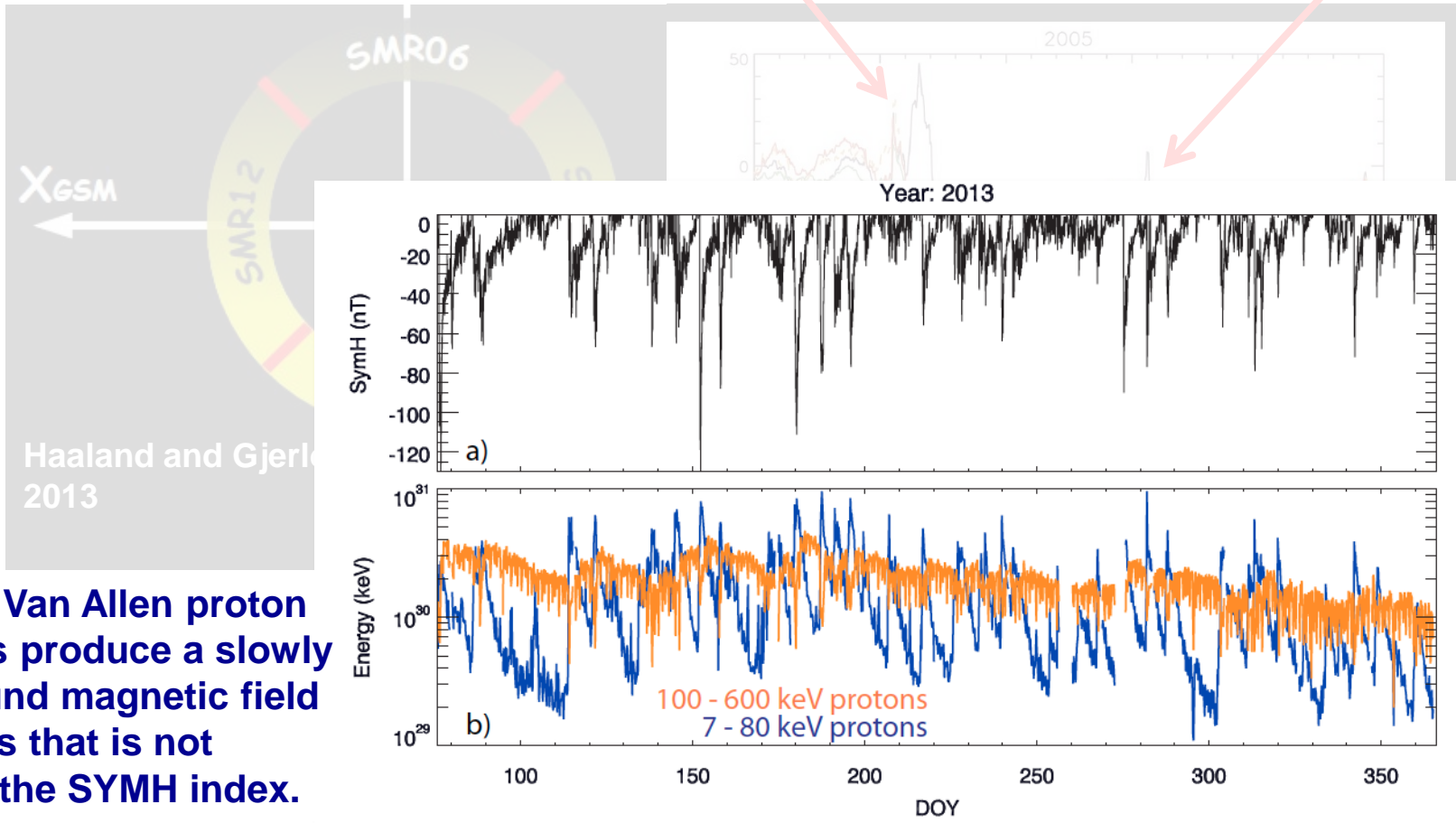
$$- \bar{B}_{Sq}(\bar{r}, t) - \bar{B}_{EEJ}(\bar{r}, t) + \bar{B}_{RC}(\bar{r}, t) + \bar{B}_{CT}(\bar{r}, t) + \bar{B}_{MP}(\bar{r}, t) + \bar{B}_{AEJ}(\bar{r}, t) + \bar{B}_{GI}(\bar{r}, t) + \bar{B}_{FAC}(\bar{r}, t)$$



Approach 2: Assuming knowledge of the system behavior

State Descriptors

$$\bar{B}_{measured}(\vec{r}, t) = \bar{B}_{main}(\vec{r}) - \bar{B}_{noise}(t) - \bar{B}_{Sq}(\vec{r}, t) - \bar{B}_{EEJ}(\vec{r}, t) + \bar{B}_{RC}(\vec{r}, t) + \bar{B}_{CT}(\vec{r}, t) + \bar{B}_{MP}(\vec{r}, t) + \bar{B}_{AEJ}(\vec{r}, t) + \bar{B}_{GI}(\vec{r}, t) + \bar{B}_{FAC}(\vec{r}, t)$$



High energy Van Allen proton observations produce a slowly varying ground magnetic field perturbations that is not captured by the SYMH index.

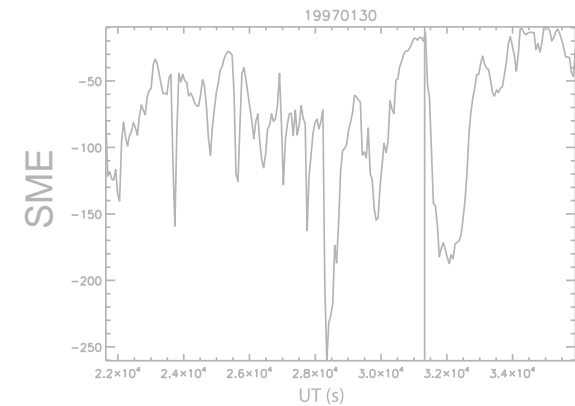
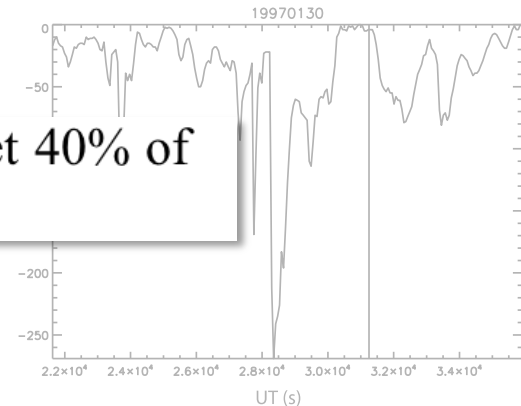
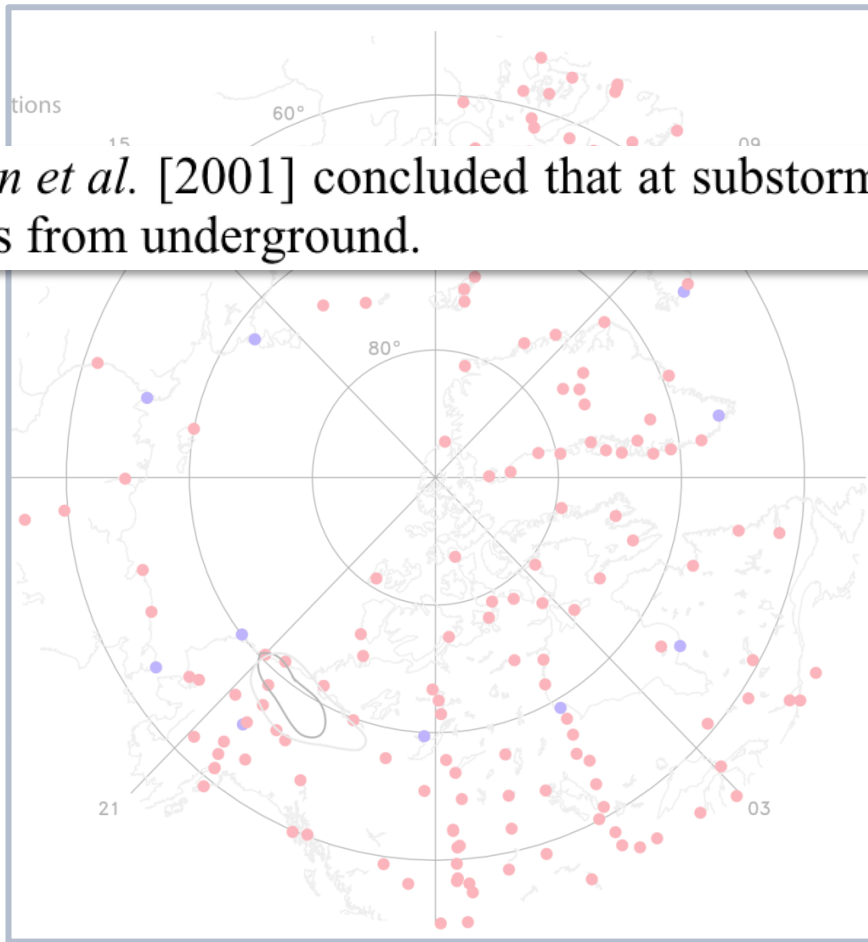
Approach 2: Assuming knowledge of the system behavior

State Descriptors

$$\bar{B}_{measured}(\bar{r}, t) = \bar{B}_{main}(\bar{r}) + \bar{B}_{noise}(t)$$

$$+ \bar{B}_{Sq}(\bar{r}, t) + \bar{B}_{EEJ}(\bar{r}, t) + \bar{B}_{RC}(\bar{r}, t) + \bar{B}_{CT}(\bar{r}, t) + \bar{B}_{MP}(\bar{r}, t) + \bar{B}_{AEJ}(\bar{r}, t) + \bar{B}_{GI}(\bar{r}, t) + \bar{B}_{FAC}(\bar{r}, t) \dots$$

Tanskanen et al. [2001] concluded that at substorm onset 40% of AL comes from underground.



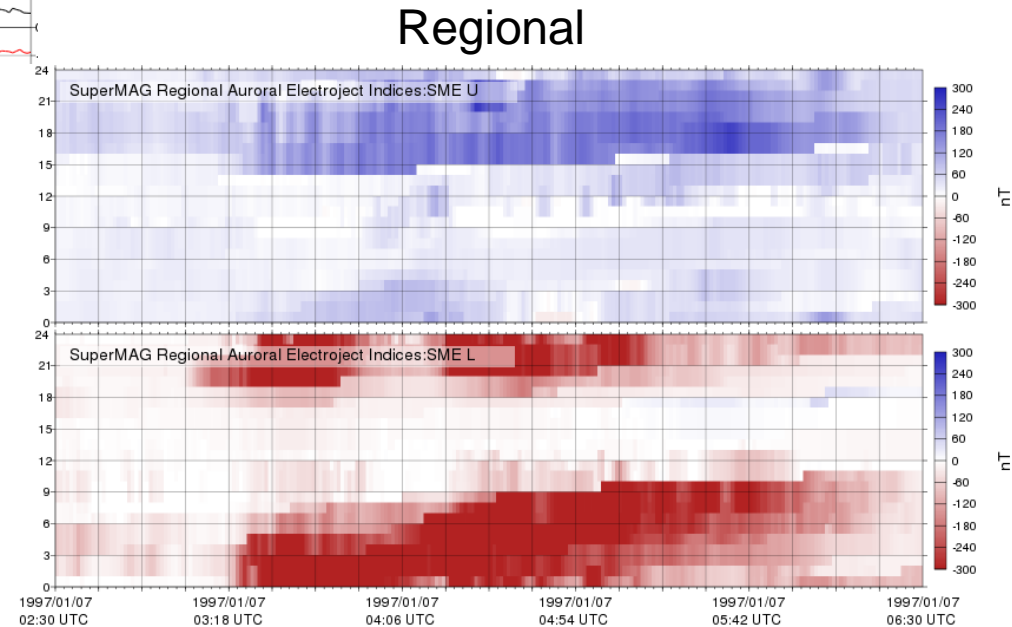
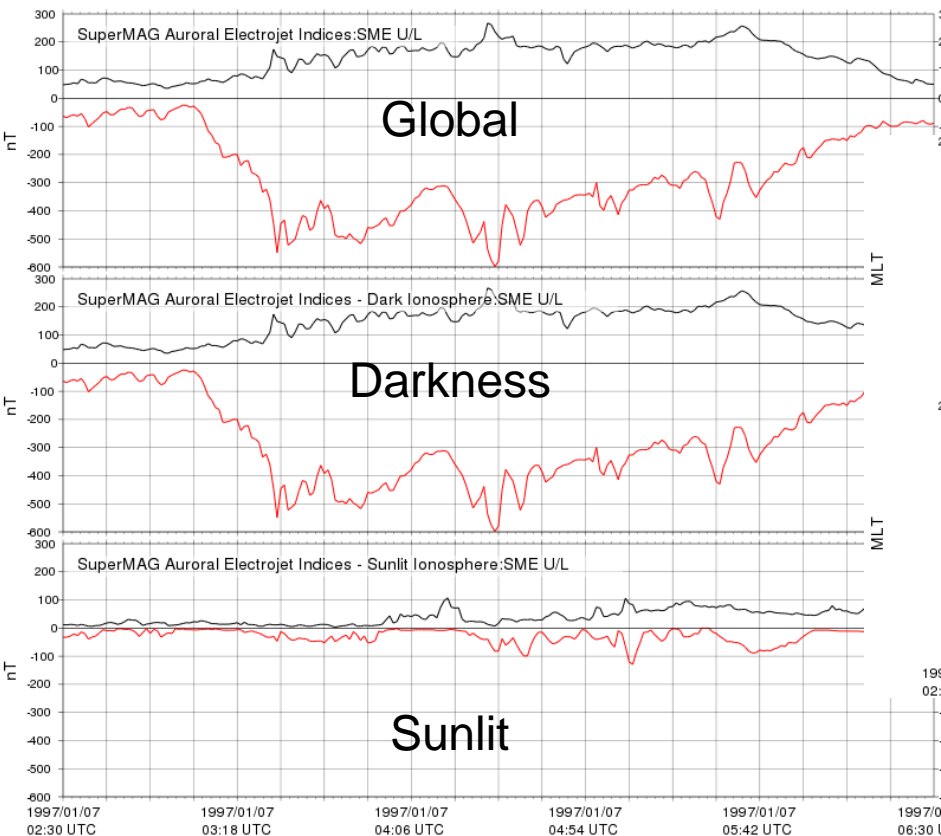
Newell and Gjerloev, JGR, 2011 a,b

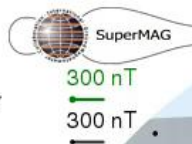
Approach 2: Assuming knowledge of the system behavior

State Descriptors

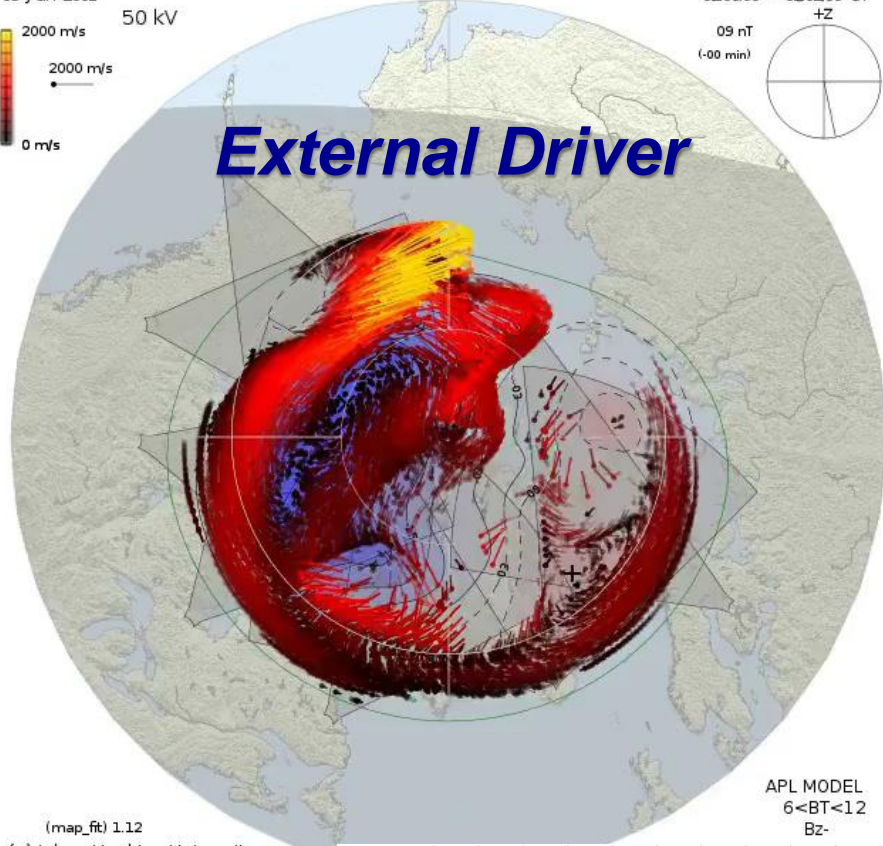
$$\bar{B}_{measured}(\bar{r}, t) = \bar{B}_{main}(\bar{r}) + \bar{B}_{noise}(t)$$

$$+ \bar{B}_{Sq}(\bar{r}, t) + \bar{B}_{EEJ}(\bar{r}, t) + \bar{B}_{RC}(\bar{r}, t) + \bar{B}_{CT}(\bar{r}, t) + \bar{B}_{MP}(\bar{r}, t) + \bar{B}_{AEJ}(\bar{r}, t) + \bar{B}_{GI}(\bar{r}, t) + \bar{B}_{FAC}(\bar{r}, t) \dots$$

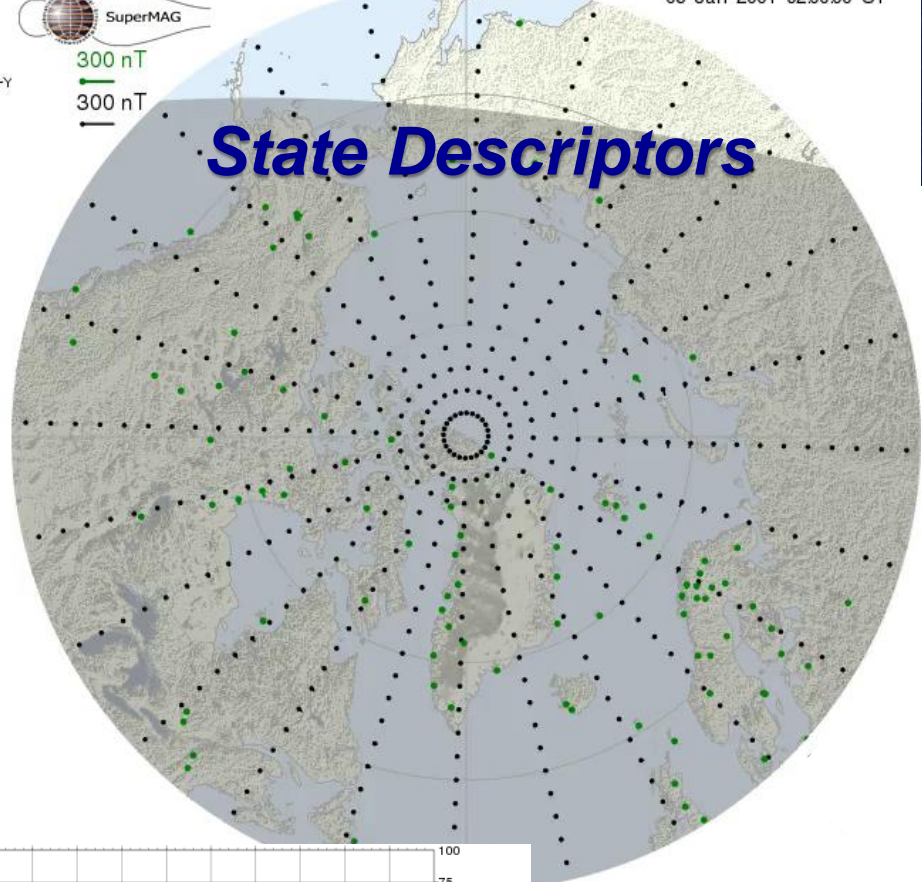




External Driver

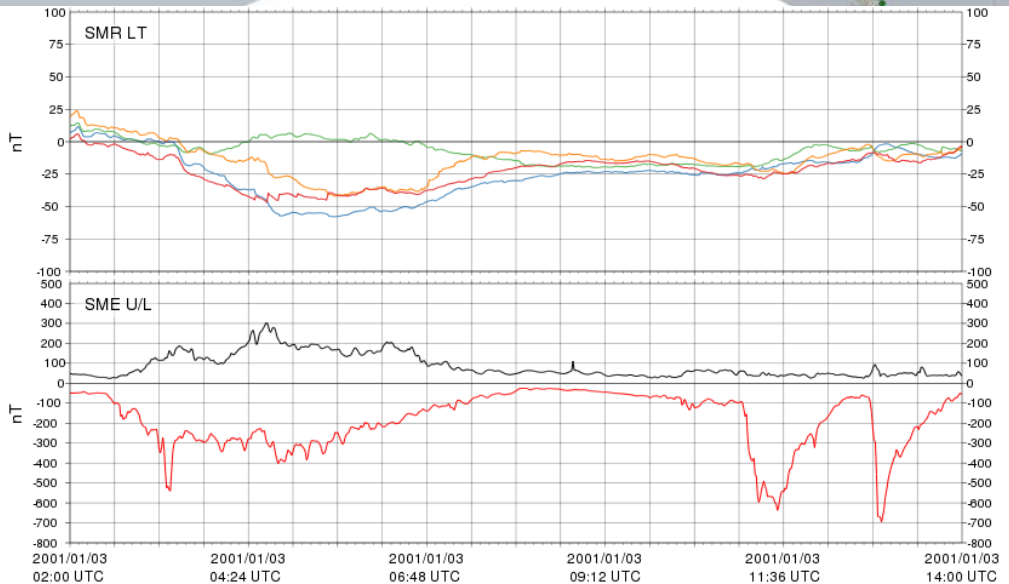


State Descriptors



APL MODEL
6<BT<12
Bz-

(map_ft) 1.12
(c) Johns Hopkins University
Applied Physics Laboratory



Deriving global distributions: What have we learned?

Conclusions:

- **Simple spatial interpolation:**
 - assume scale sizes are larger than spatial data gaps
- **External driver:**
 - assume causality
- **State descriptors:**
 - assume these adequately describe the system state
- It is unclear to what extent pretty smooth distributions provide insight into system behavior.

Recommendations:

- More emphasis should be put on validation of results/models.
- We must remember which underlying physical processes are excluded/ignored by the large-scale solutions.
- New models should include/acknowledge the dynamics of the system.
- Models should increasingly allow the user to control settings.

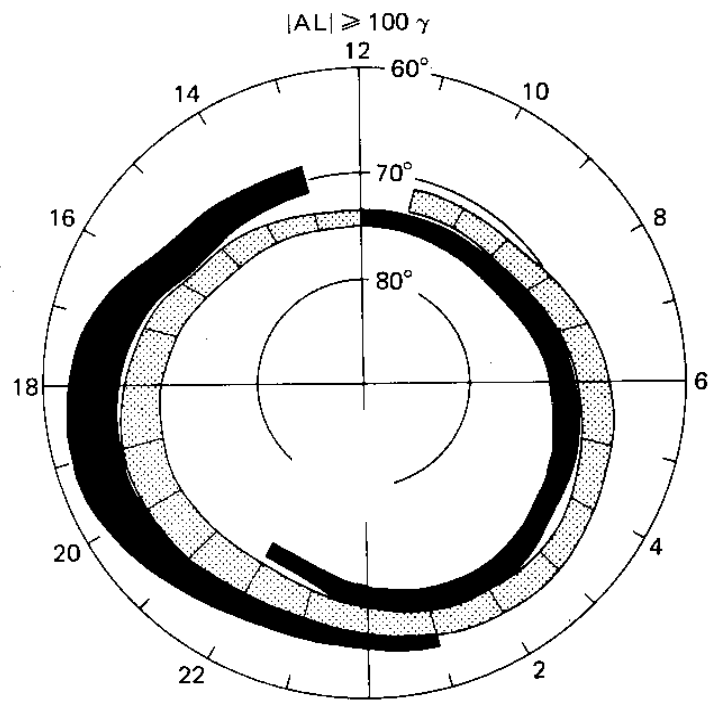
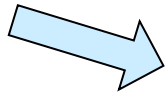
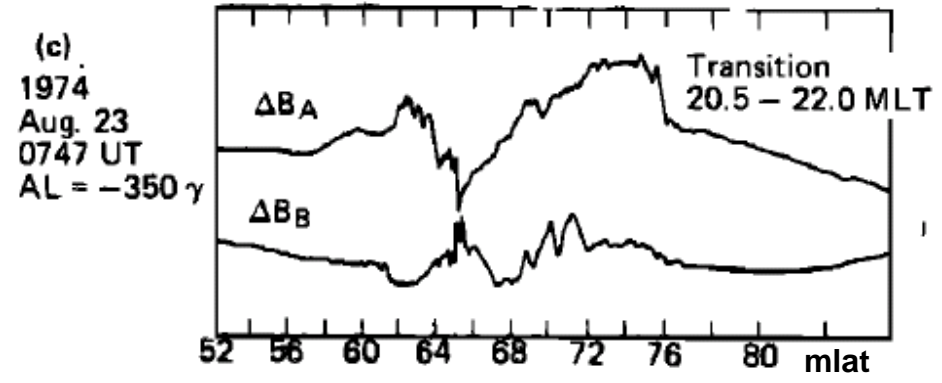
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Global Birkeland Current Distribution: Inherent Assumptions

Reality



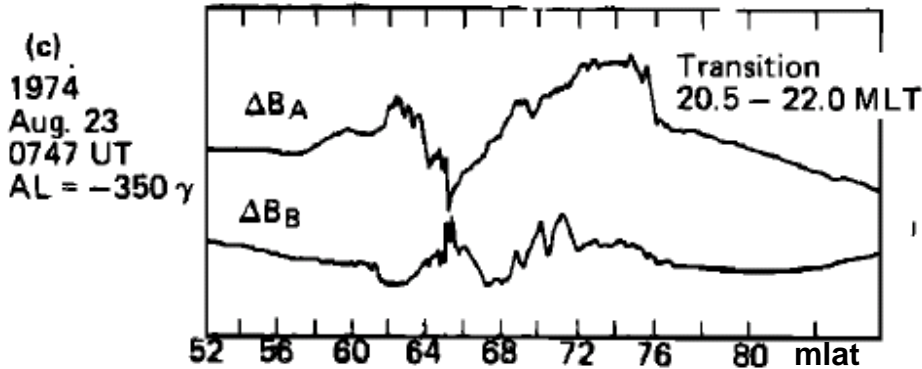
liijima and Potemra, 1978

Inherent assumption:

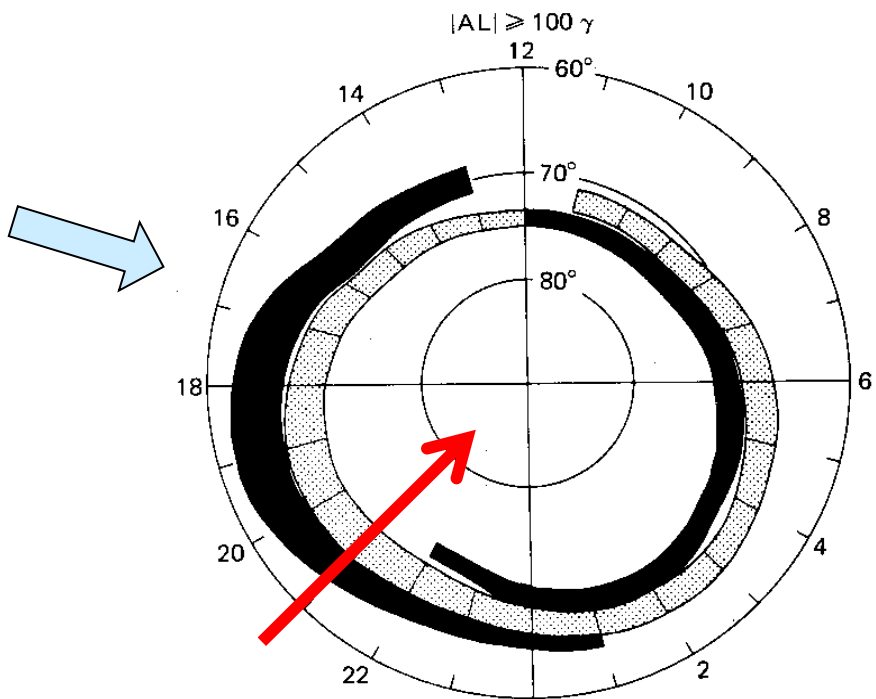
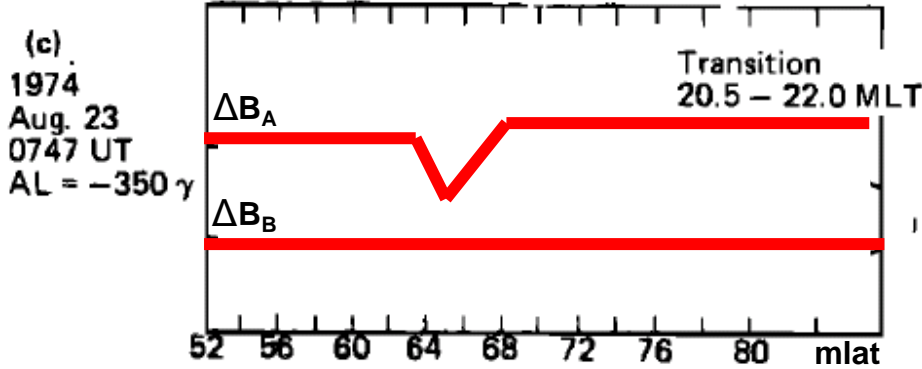
- Currents with scale sizes smaller than the R1-R2 currents are insignificant;

Global Birkeland Current Distribution: Inherent Assumptions

Reality



Model



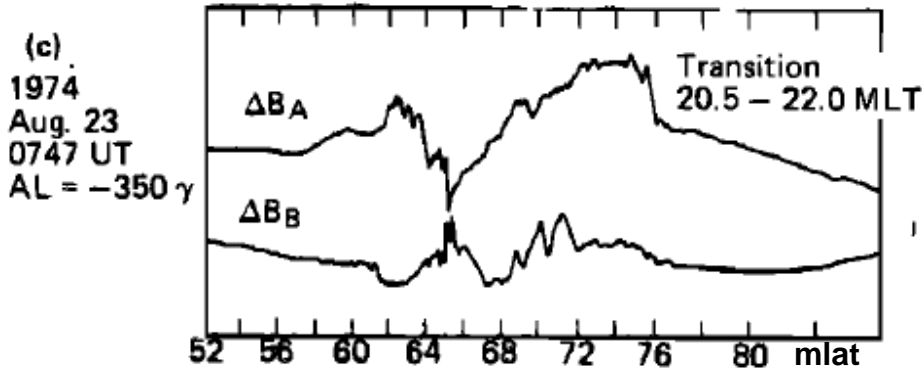
Iijima and Potemra, 1978

Inherent assumption:

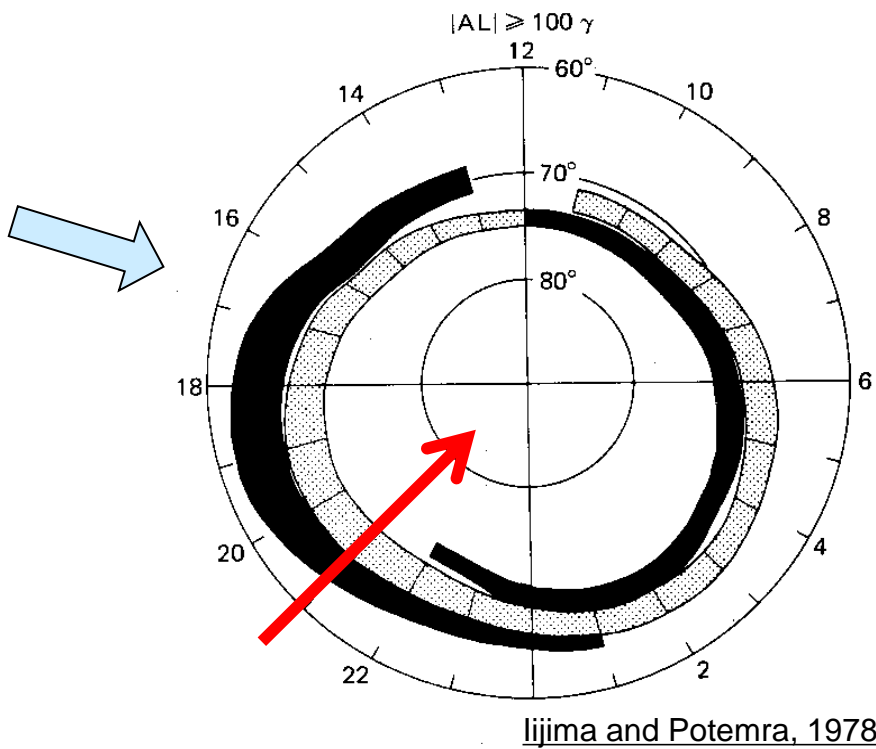
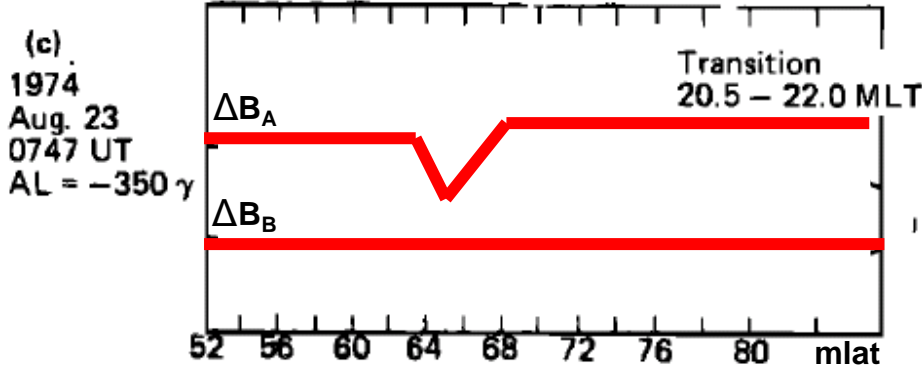
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Global Birkeland Current Distribution: Inherent Assumptions

Reality



Model

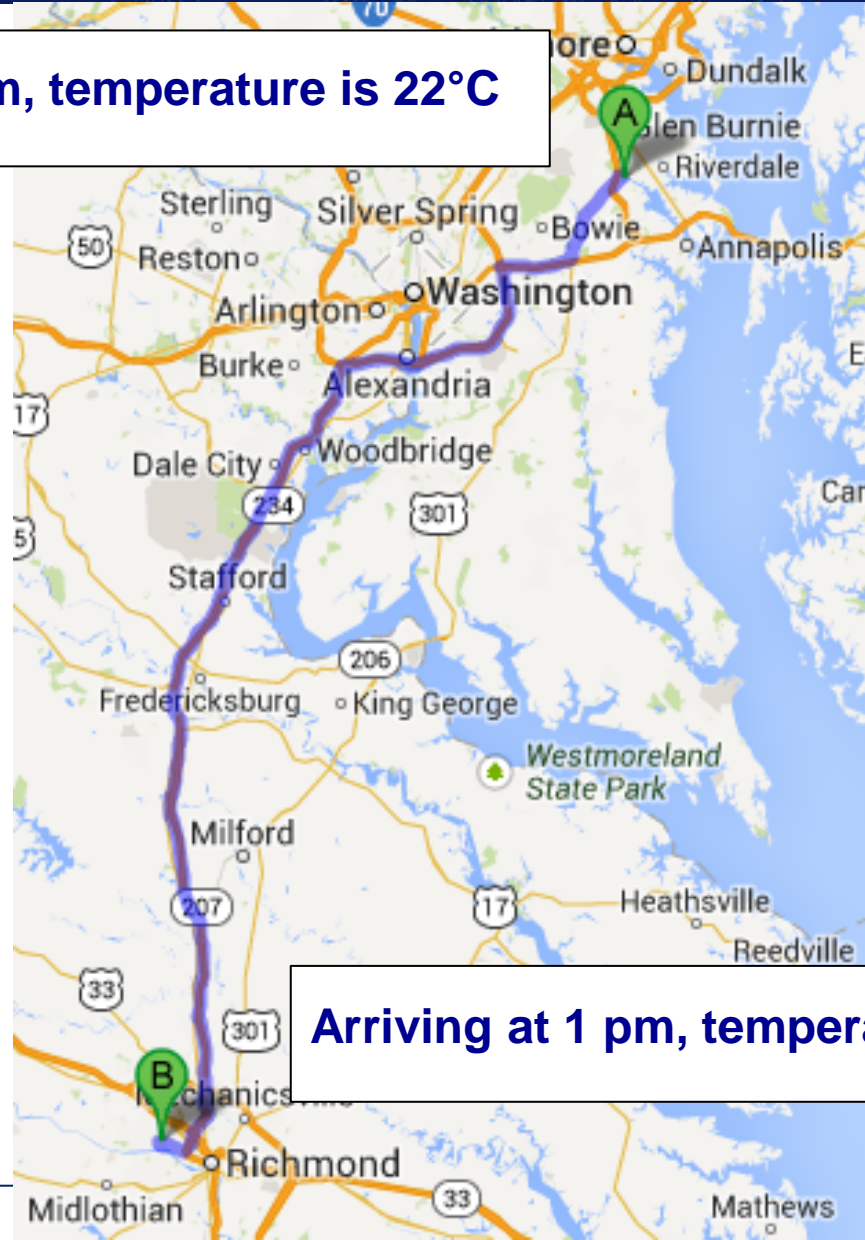


Inherent assumption:

- Currents with scale sizes smaller than the R1-R2 currents are insignificant;
- The observed magnetic field perturbations are due to **static currents**.

Observational Challenge: Mixing Space and Time

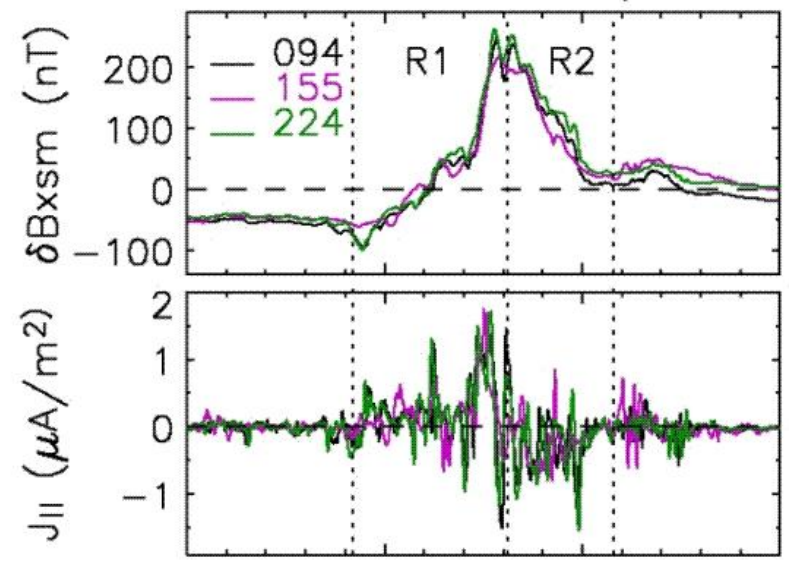
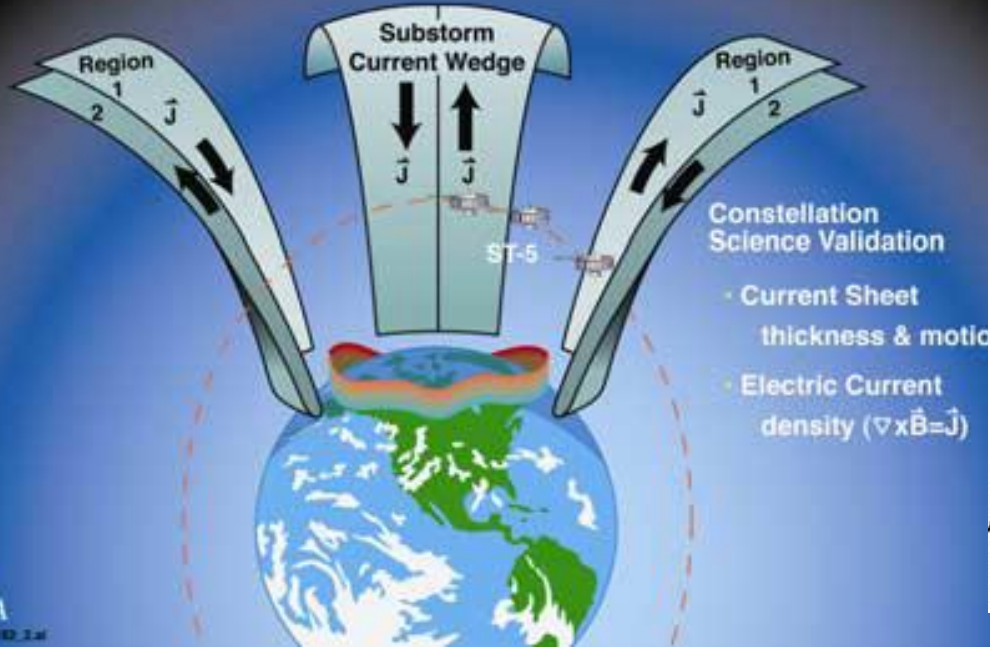
Leaving at 9 am, temperature is 22°C



Arriving at 1 pm, temperature is 31°C

ST 5 Mission: Multi point measurements enabling separation of space and time

Space Technology 5



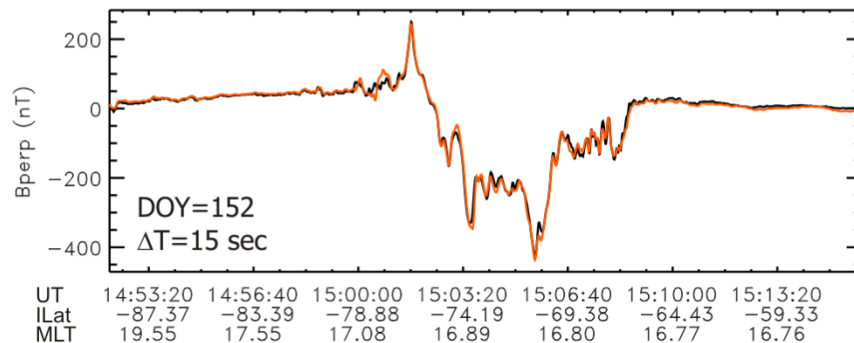
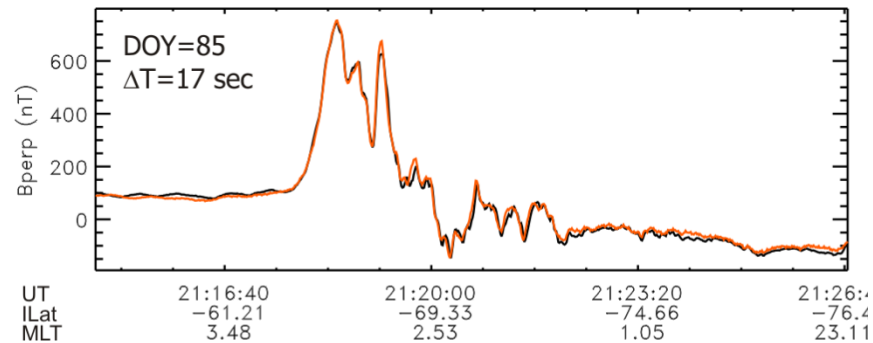
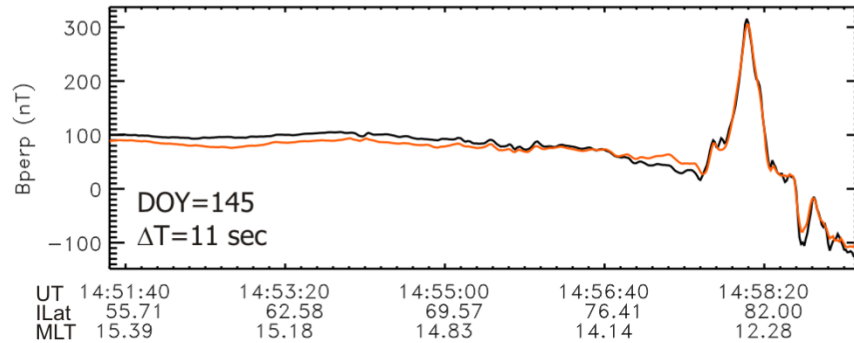
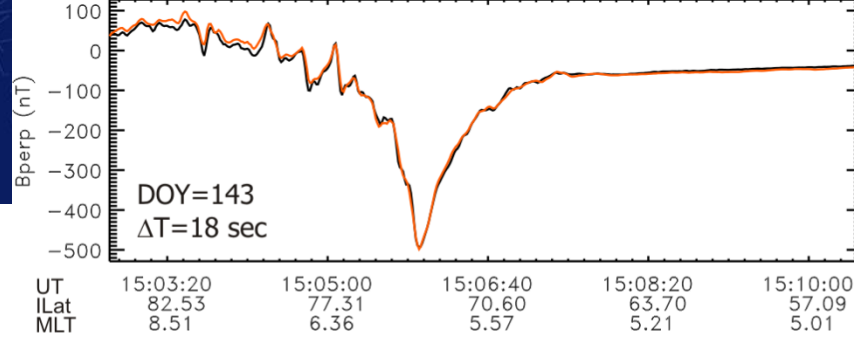
U.T. (hr)	20:20	20:25	20:30	20:35
Alt (km)	3414	3774	4070	4299
MLT (hr)	20.42	19.18	18.61	18.27
MLAT ($^{\circ}$)	-74.6	-66.6	-58.1	-49.6

Slavin et al., 2008

Observations appear to indicate:

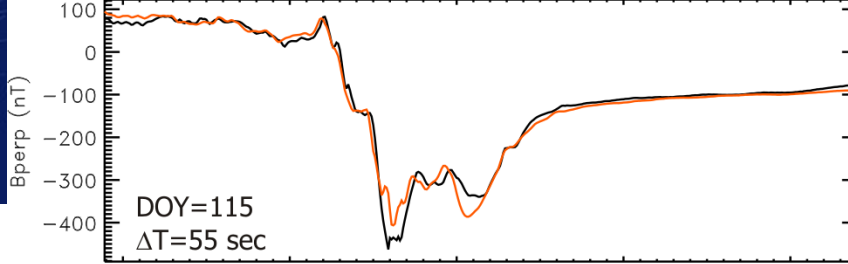
- The FAC density is highly structured;
- The FAC density changes significantly over the 1-6 min separation of the ST 5 satellites.

Typical Events: $\Delta t \sim 15$ sec

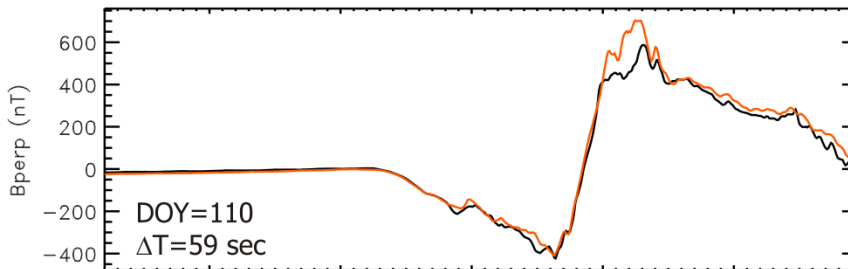


Current filaments with scale sizes larger than ~ 50 km change on time scales longer than ~ 15 sec.

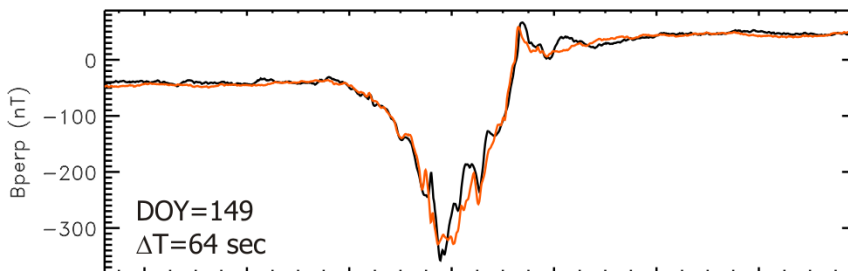
Typical Events: $\Delta t \sim 60$ sec



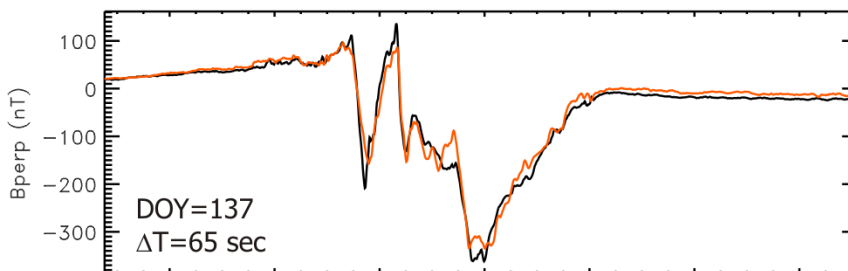
UT	13:26:40	13:28:20	13:30:00	13:31:40	13:33:20
ILat	80.73	77.72	72.05	65.25	58.01
MLT	9.90	7.60	6.40	5.77	5.41



UT	14:31:40	14:33:20	14:35:00	14:36:40	14:38:20
ILat	58.93	64.13	69.66	75.33	80.53
MLT	15.48	15.27	14.95	14.37	13.06



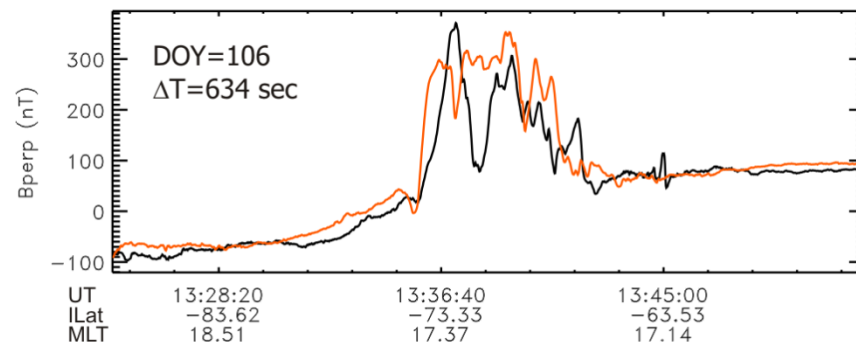
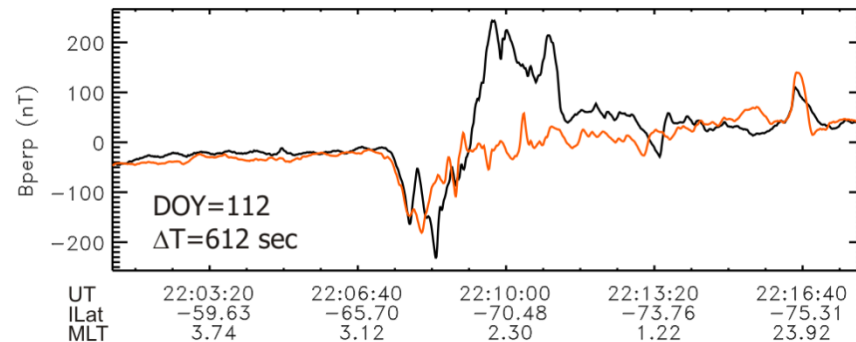
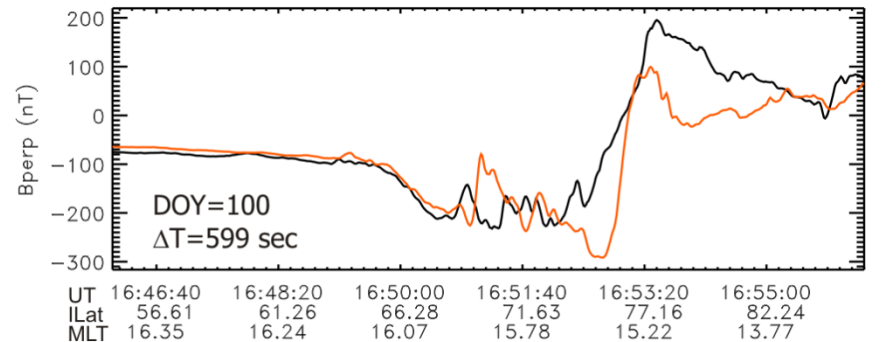
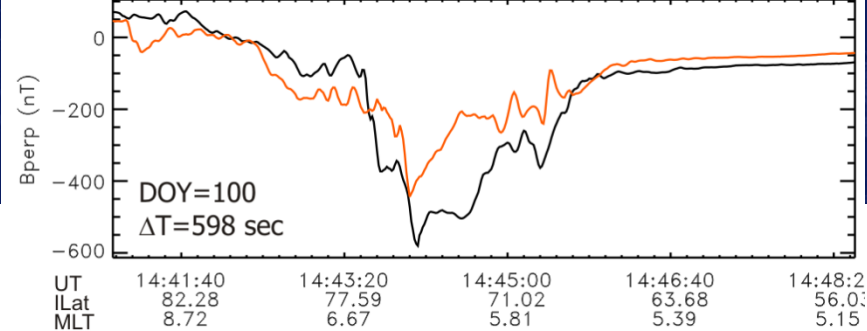
UT	20:06:40	20:10:00	20:13:20	20:16:40	20:20:00	20:23:20	20:26:40
ILat	-56.95	-61.72	-66.22	-70.41	-74.20	-77.41	-79.68
MLT	4.73	4.49	4.20	3.81	3.26	2.43	1.20



UT	11:53:20	11:56:40	12:00:00	12:03:20	12:06:40	12:10:00	12:13:20
ILat	-83.99	-81.05	-77.15	-72.80	-68.13	-63.20	-58.03
MLT	20.94	19.20	18.38	17.94	17.67	17.49	17.37

Current filaments with scale sizes larger than ~ 200 km change on time scales longer than ~ 60 sec.

Typical Events: $\Delta t \sim 600$ sec

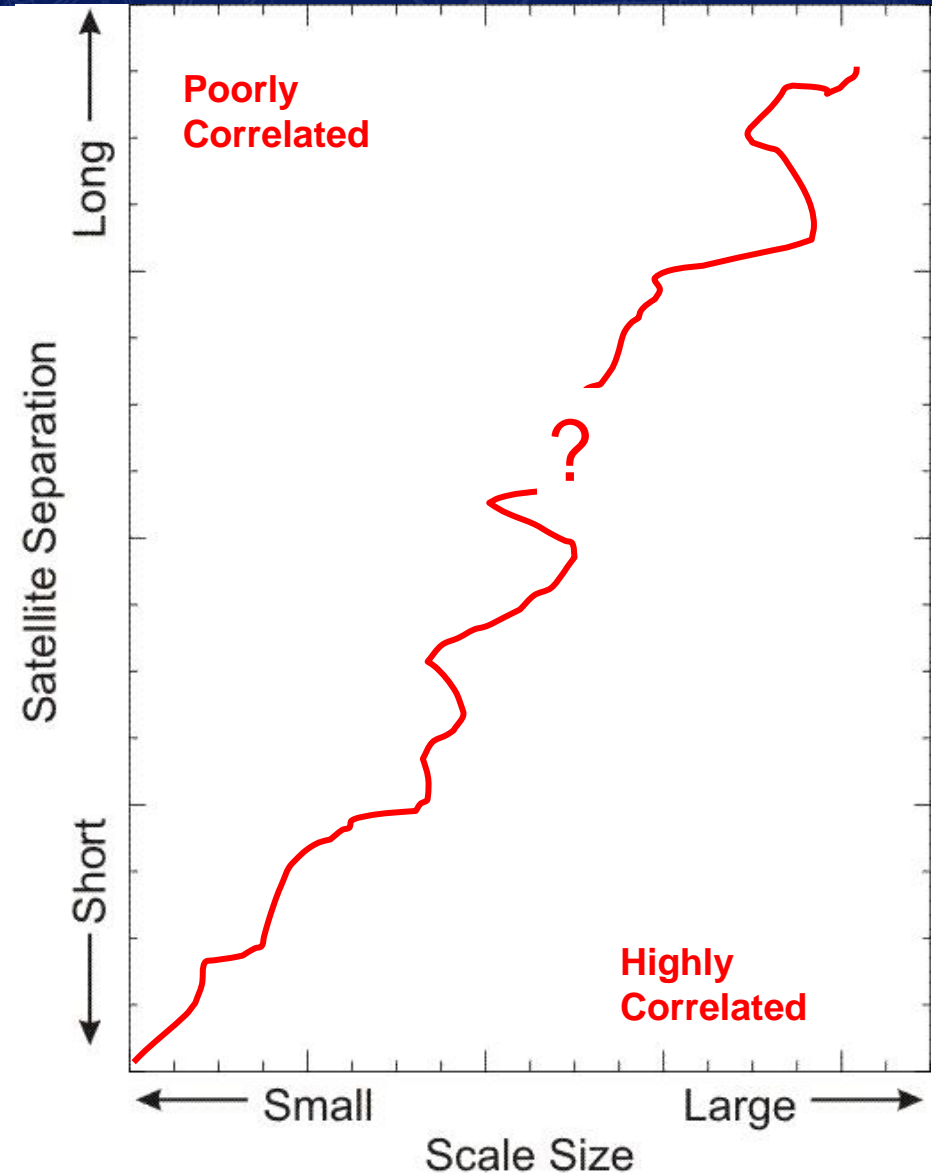


On time scales of ~ 600 sec we find significant changes to the entire FAC system at all scale sizes.

Scale Size and Variability of Birkeland Currents

Anticipated result

Is it reasonable to assume that the magnetosphere-ionosphere system is repeatable?

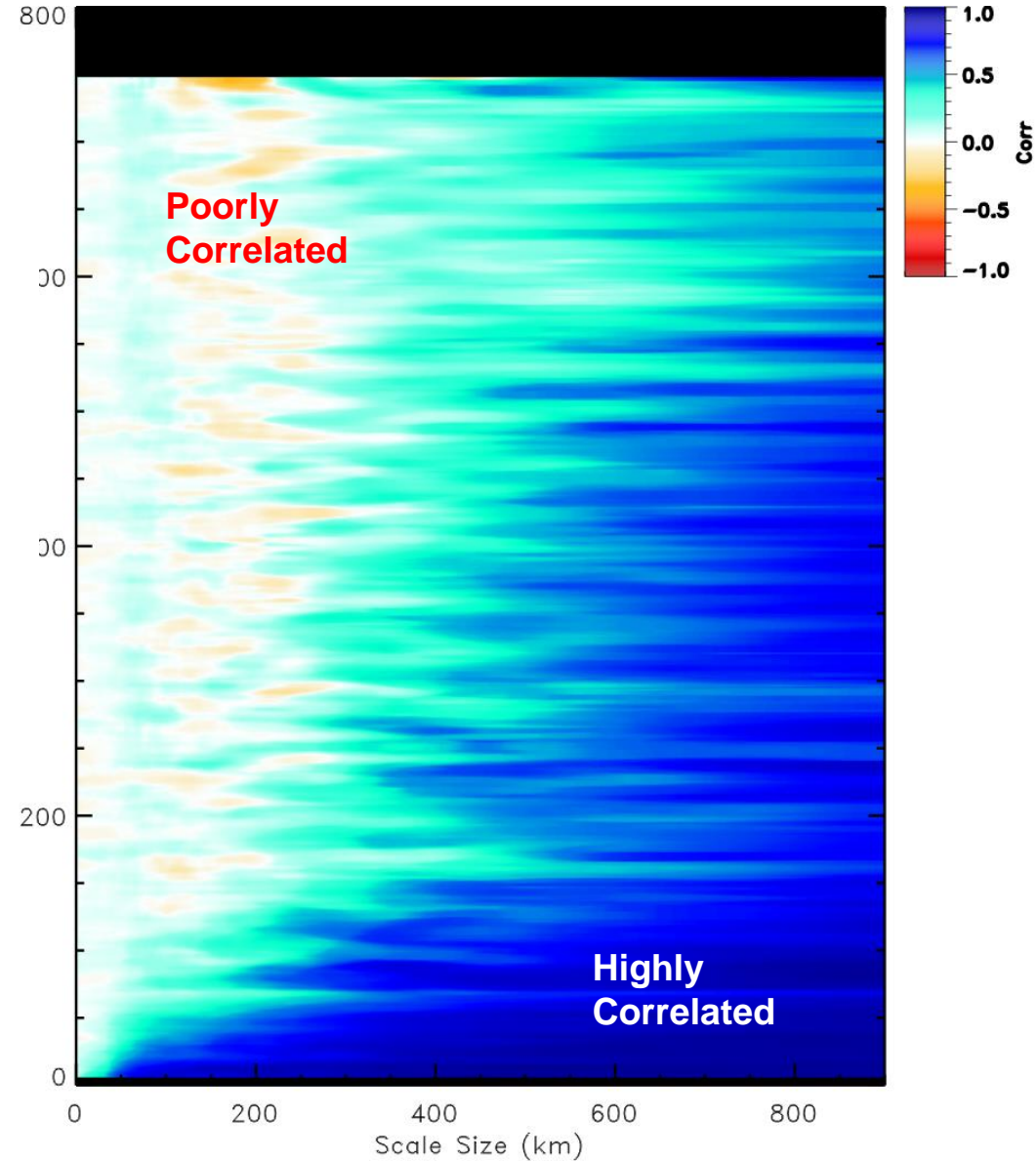


Scale Size and Variability of Birkeland Currents

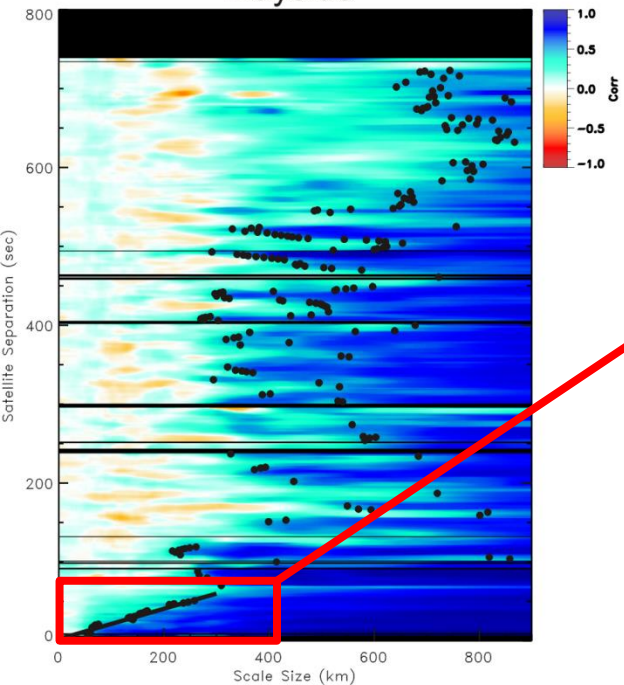
Actual result

Is it reasonable to assume that the magnetosphere-ionosphere system is repeatable?

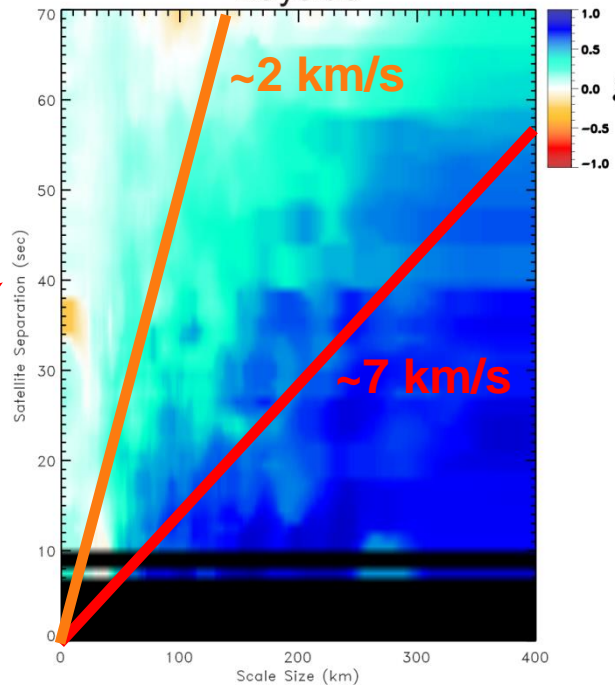
Surprisingly the answer is yes.



Dayside



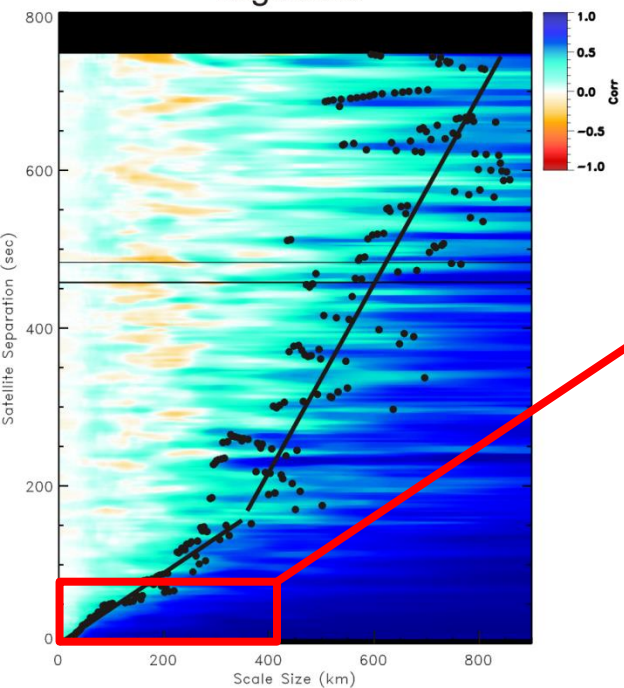
Dayside



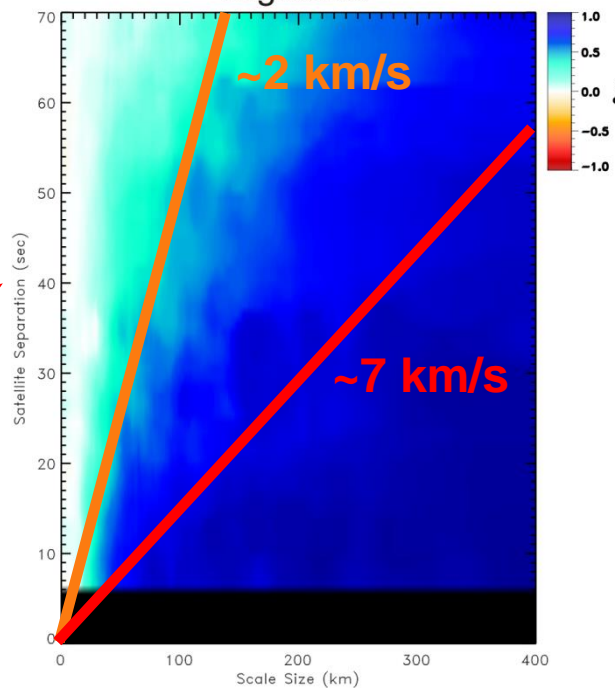
A satellite pass is marginally in the high correlation region on the dayside.

A sounding rocket is typically in the poor correlation region.

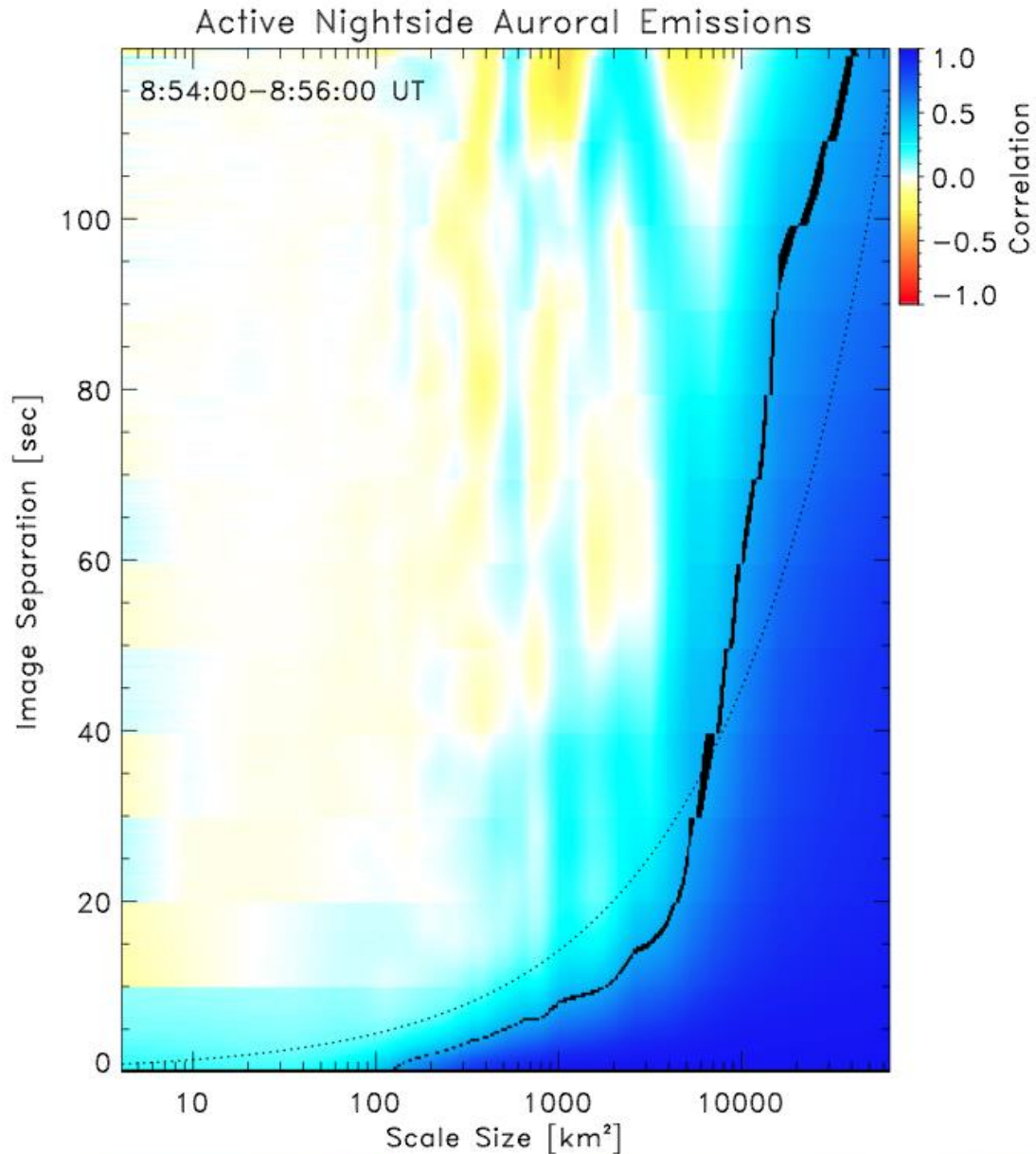
Nightside



Nightside



Scale Size and Variability of Green Light Emissions



Calculating FAC's using Swarm

Single satellite (classical)

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J} \Rightarrow J_z = [\partial B_y / \partial x - \partial B_x / \partial y] / \mu_0$$

Assumptions:

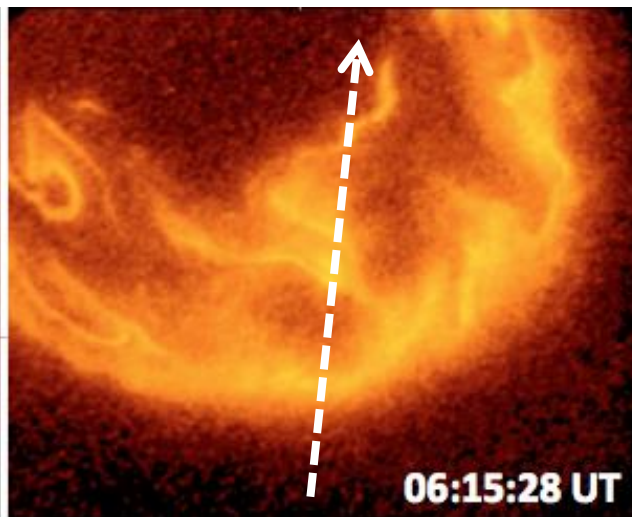
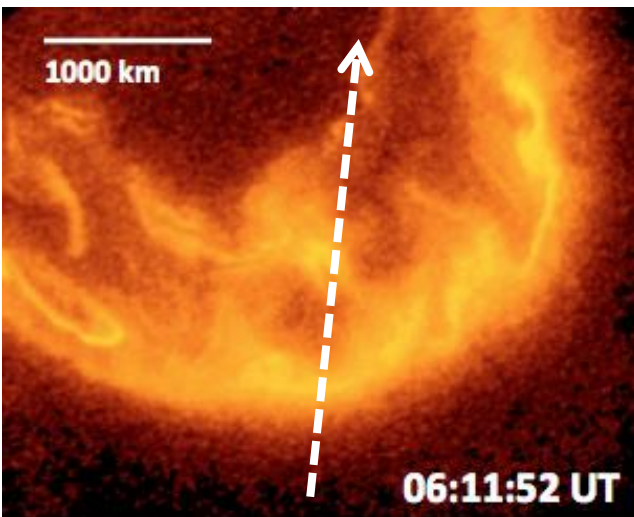
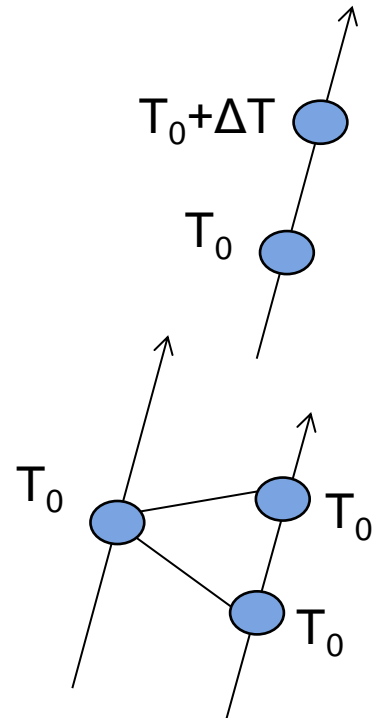
- Static over the time it takes to traverse current sheet
- Simplistic current configuration (e.g. infinite sheet)

Three satellites (curlometer technique)

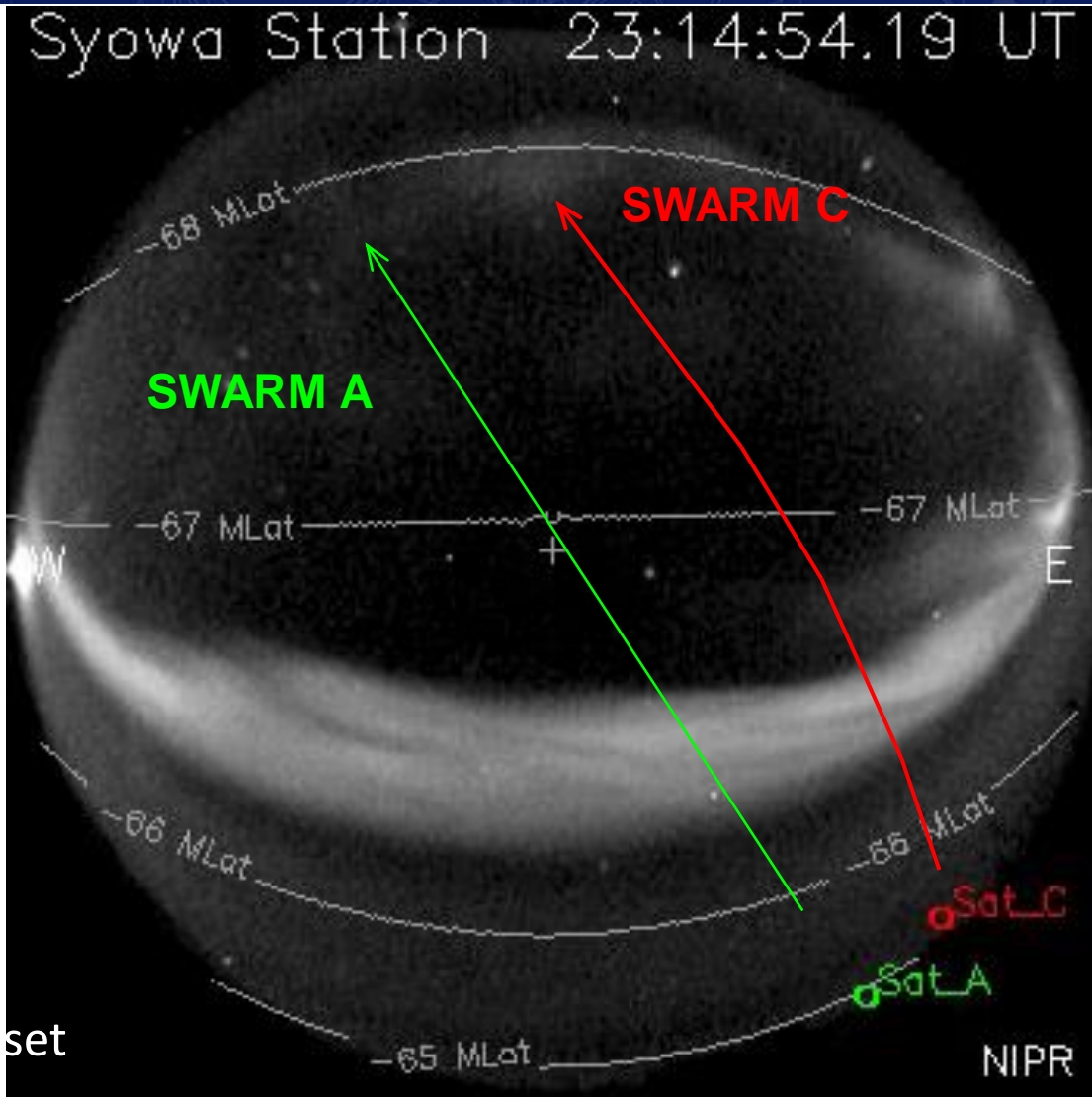
$$j = \frac{1}{\mu_0 A} \oint \mathbf{B} \cdot d\mathbf{l} \Rightarrow J_z \approx \frac{1}{\mu_0} \left(\frac{\mathbf{r}_{13} \cdot \Delta \mathbf{B}_{12} - \mathbf{r}_{12} \cdot \Delta \mathbf{B}_{13}}{|\mathbf{r}_{13} \times \mathbf{r}_{12}|} \right)$$

Assumption:

- Constant current over area

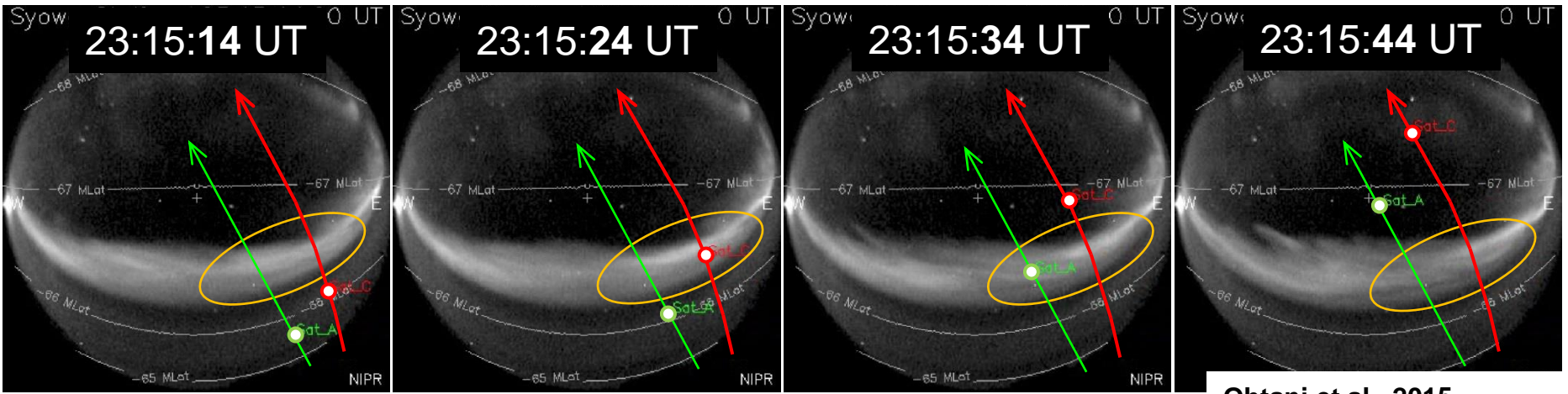


Calculating Birkeland Currents using ESA Swarm Example on 1 September 2014



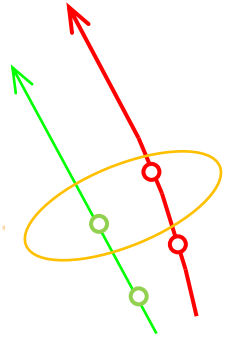
Calculating Birkeland Currents using ESA Swarm

Example on 1 September 2014



Ohtani et al., 2015

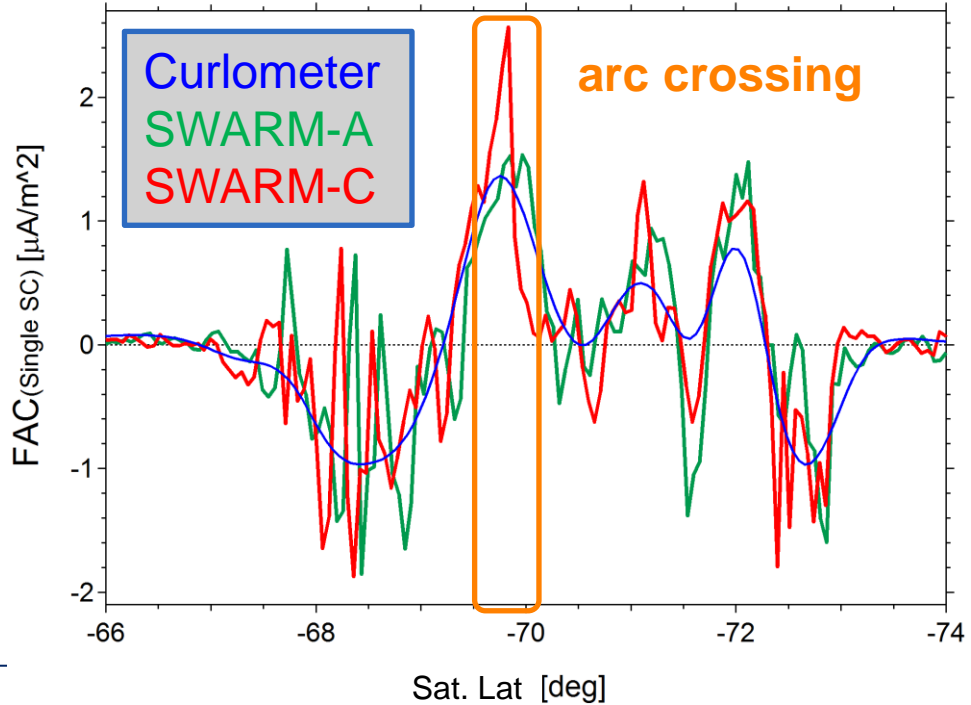
$$j = \frac{1}{\mu_0 A} \oint B \cdot dl$$



Even for best case scenario (stable arcs)

Birkeland currents:

- are not static
- are not infinite sheets
- are not uniform over 50 km

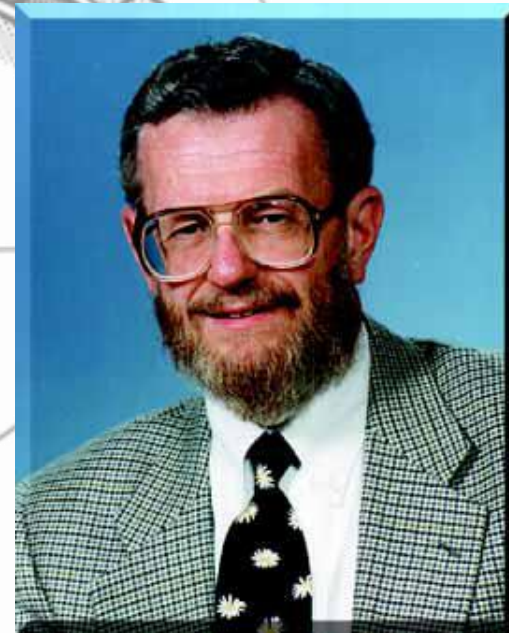


**Special Session at the 2016 Fall AGU Meeting
(San Francisco; 12-16 December 2016; Abstract Submission : 15 June - 3
August 2016)**

Birkeland Currents: Achievements since Iijima and Potemra [1976], and Challenges in Years to Come



Takeshi Iijima (1938–)



Thomas A. Potemra (1938–1998)

Conveners:

**Aoi Nakamizo,¹ Natalia Ganushkina,² Hermann J. Opgenoorth,³
and Lawrence J. Zanetti,^{4,5}**

1: NICT (Japan); 2: FMI (Finland)/Univ. Michigan (USA); 3: IRF (Sweden); 4: NOAA (USA); 5: JHU/APL (USA)

Outline

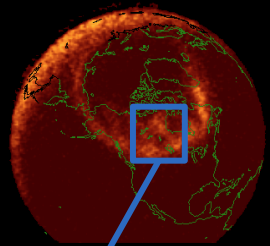
1. How do we derive global solutions from sparse data coverage?
2. What are the limitations of the global solutions?
Derived parameters
Processes/phenomena
3. The holy grail of M-I physics: Global, continuous and complete electrodynamic solutions.



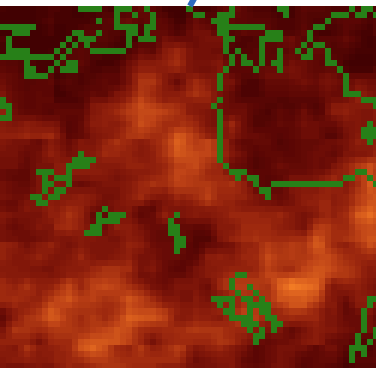
North-South Structures

VIS Earth Camera
NOV 09, 1998/313 0612:49 UT

06:12:49 UT

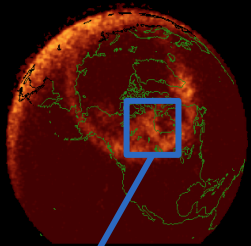


OI 130.4 nm
Visible Imaging System/POLAR
The University of Iowa/NASA-GSFC

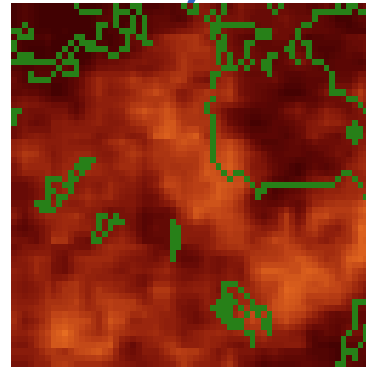


VIS Earth Camera
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06:16:25 UT

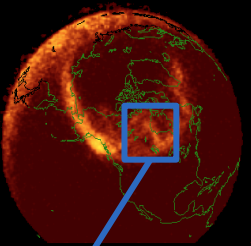


OI 130.4 nm
Visible Imaging System/POLAR
The University of Iowa/NASA-GSFC

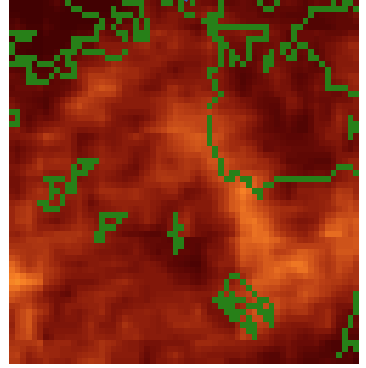


VIS Earth Camera
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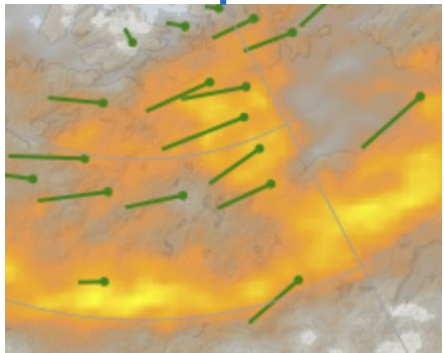
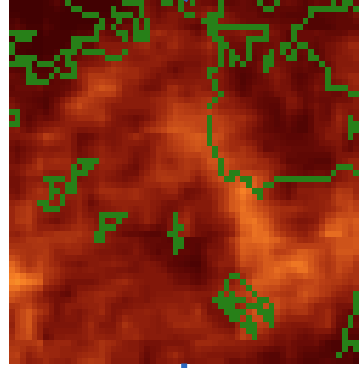
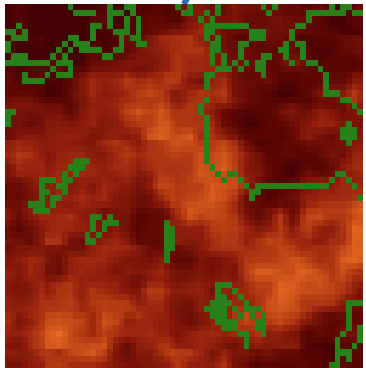
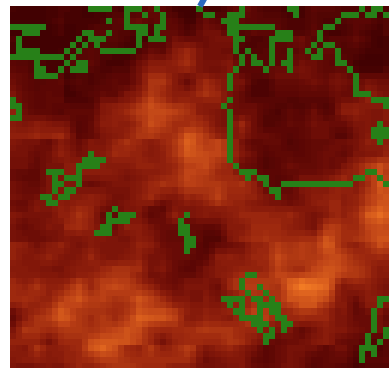
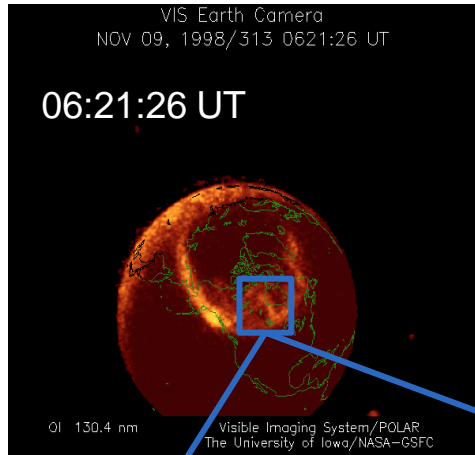
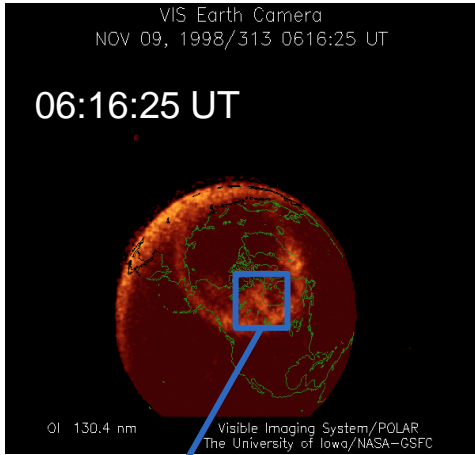
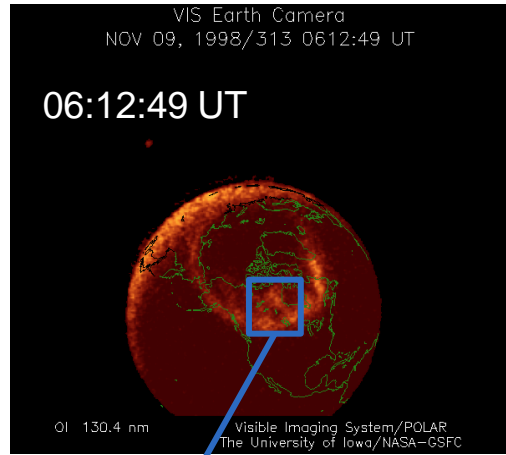
06:21:26 UT



OI 130.4 nm
Visible Imaging System/POLAR
The University of Iowa/NASA-GSFC

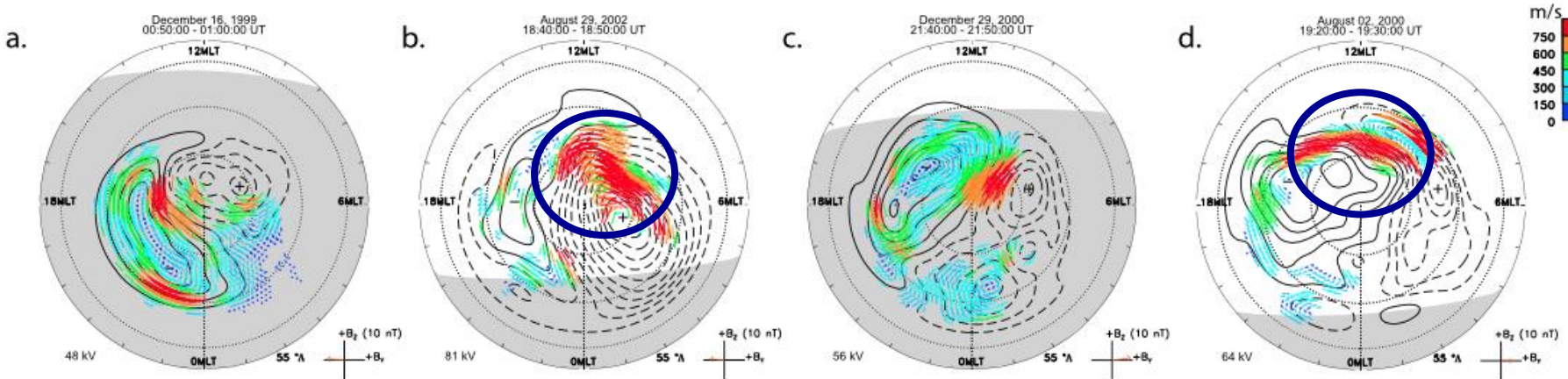


North-South Structures

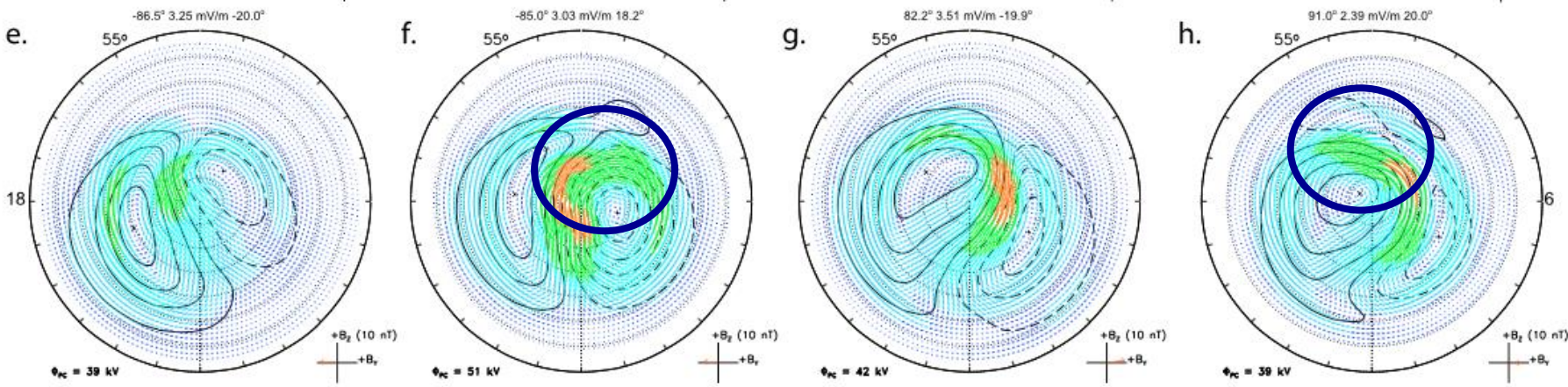


Limitations of statistical models

Instantaneous



Statistical



Cousins, E. D. P. and S. G. Shepherd (2010)

To what extent does pretty smooth average solutions provide the system information we seek?

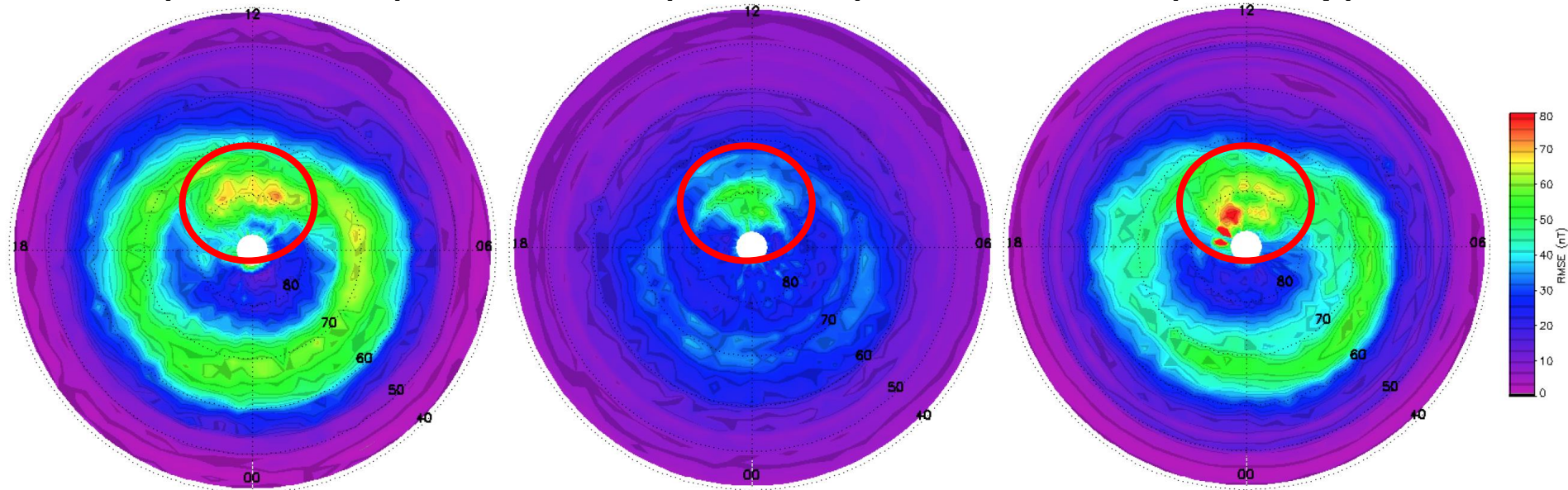
Limitations of statistical models

Waters, Gjerloev, Dupont, Barnes, JGR, 2015

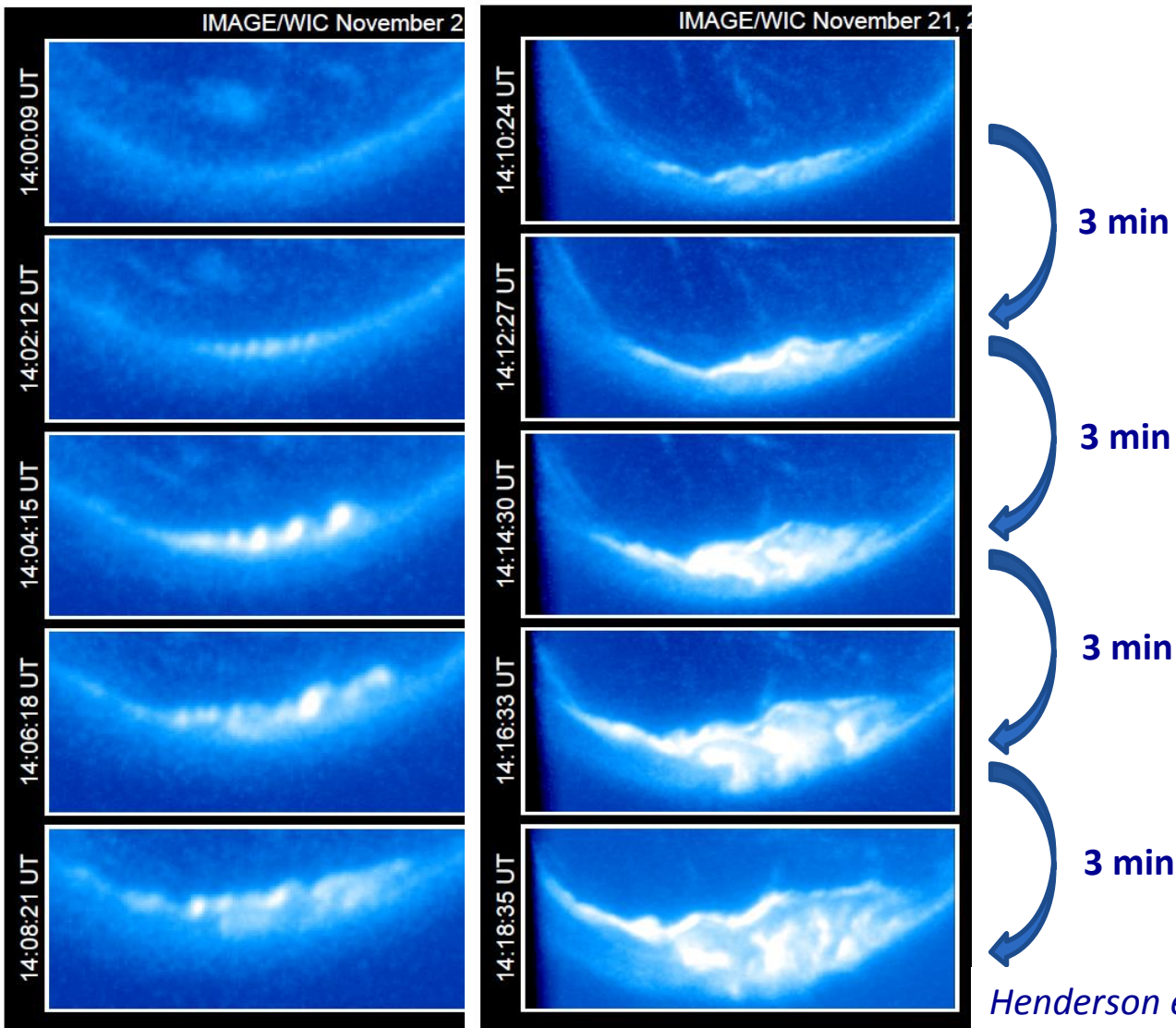
N (north-south)

E (east-west)

Z (down-up)



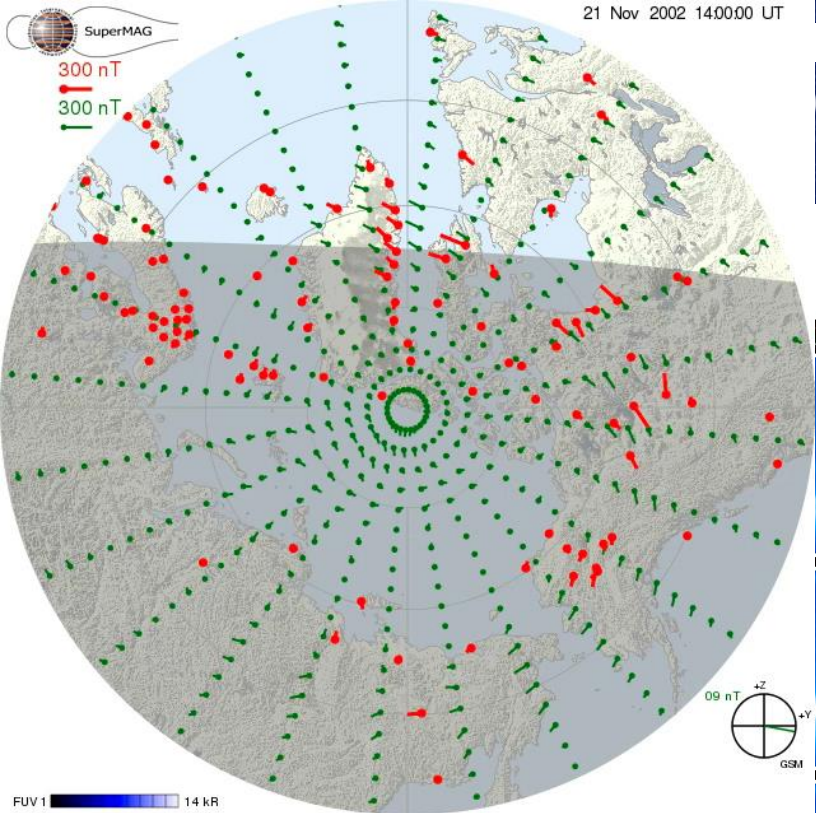
Special Session at the 2016 Fall AGU Meeting
(San Francisco; 12-16 December 2016; Abstract Submission : 15 June - 3 August 2016)



SM003. *Advancing our Understanding of the Dynamic Magnetosphere-Ionosphere System Using Auroral Imaging*

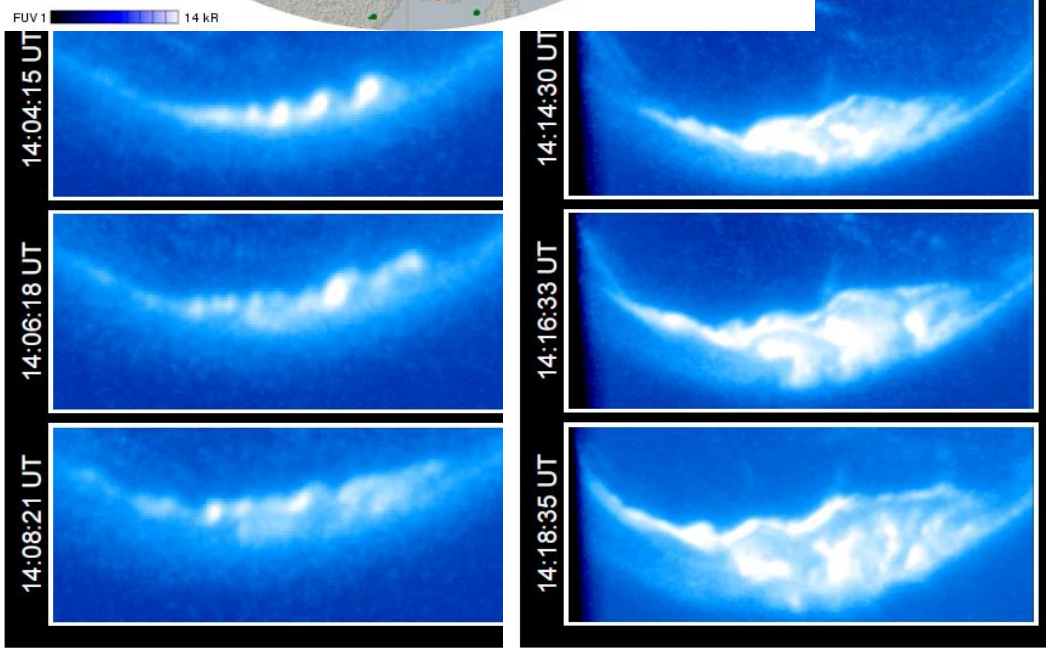
Conveners:
J. Gjerloev, R. Floberhagen, S. Zou, D. Knudsen

Henderson et al. [2009]

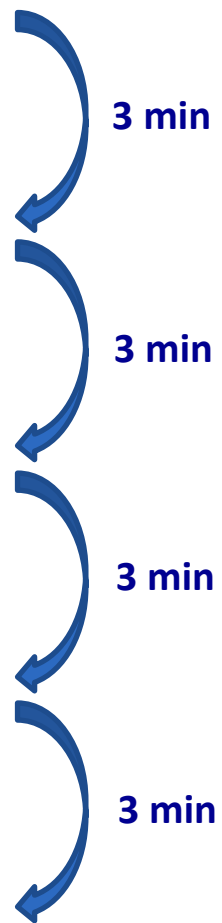


SM003. Advancing our Understanding of the Dynamic Magnetosphere-Ionosphere System Using Auroral Imaging

Conveners:
 J. Gjerloev, R. Floberhagen,
 S. Zou, D. Knudsen



WIC November 21, 2002



3 min
 3 min
 3 min
 3 min

Limitations of global distributions: What have we learned?

Conclusions:

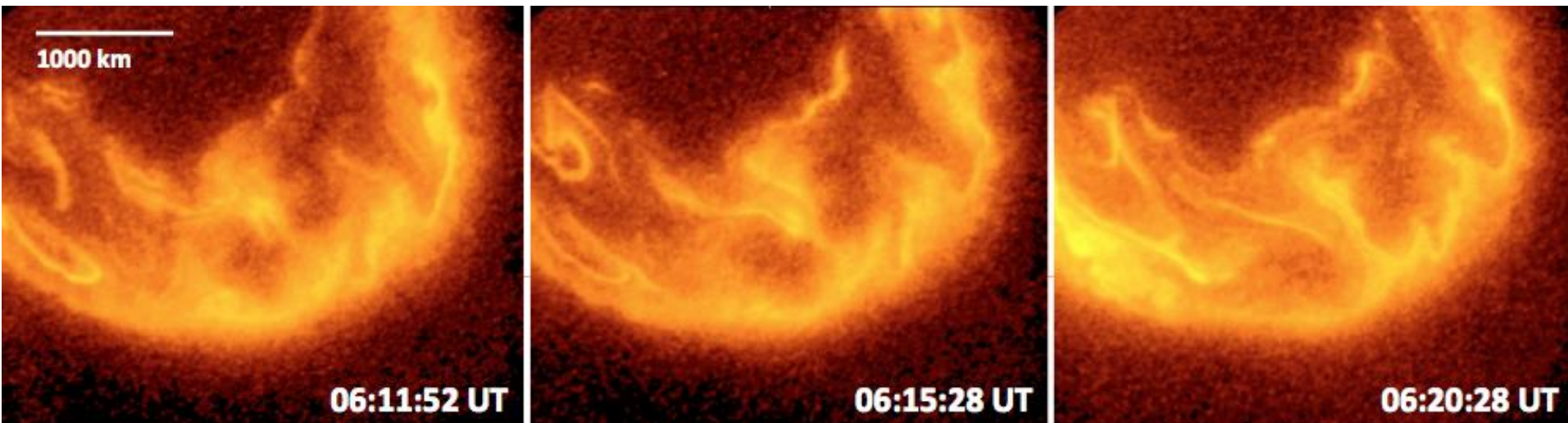
- **Derived quantities from measurements is based on assumptions that often are violated.**
- **SuperMAG-SuperDARN-AMPERE spatiotemporal resolution limit the processes and phenomena that can be addressed.**

Recommendations:

- **Users should keep assumptions and limitations in mind before making conclusions. Providers should be open about these complexities and provide quality flags (when possible).**
- **Relationship between large-scale and meso-scale processes should be emphasized (e.g. feeding and drainage of the auroral electrojet system).**

Outline

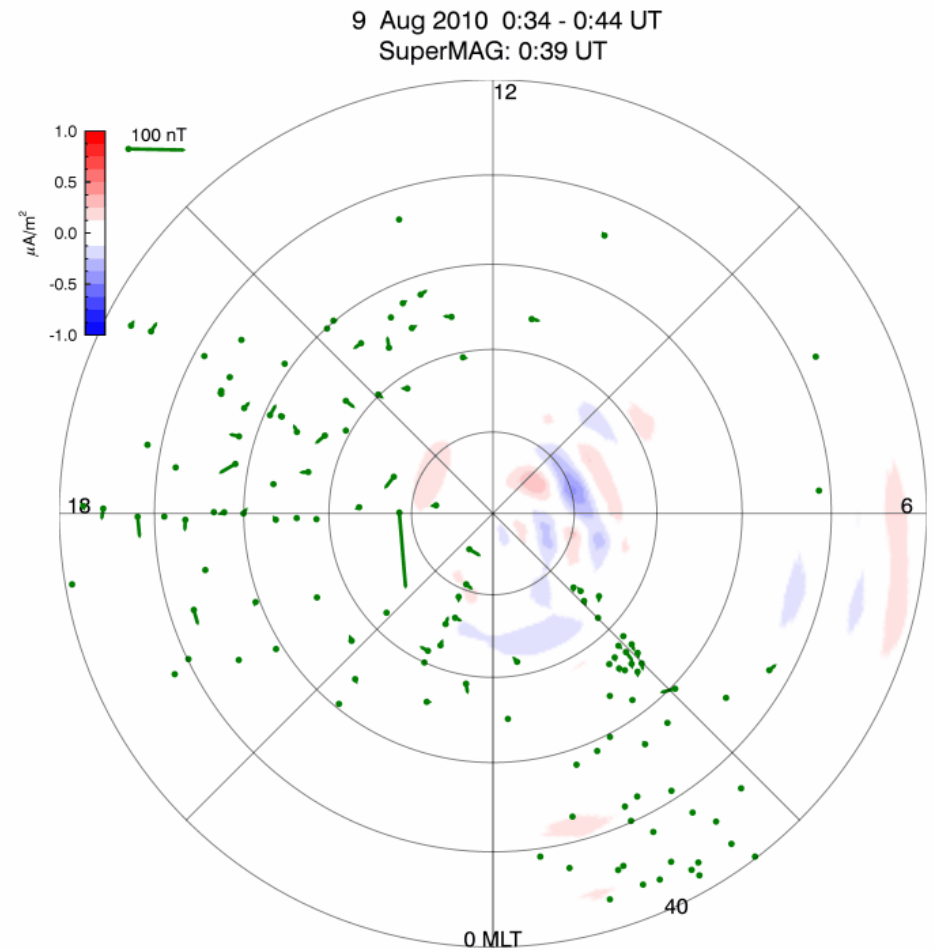
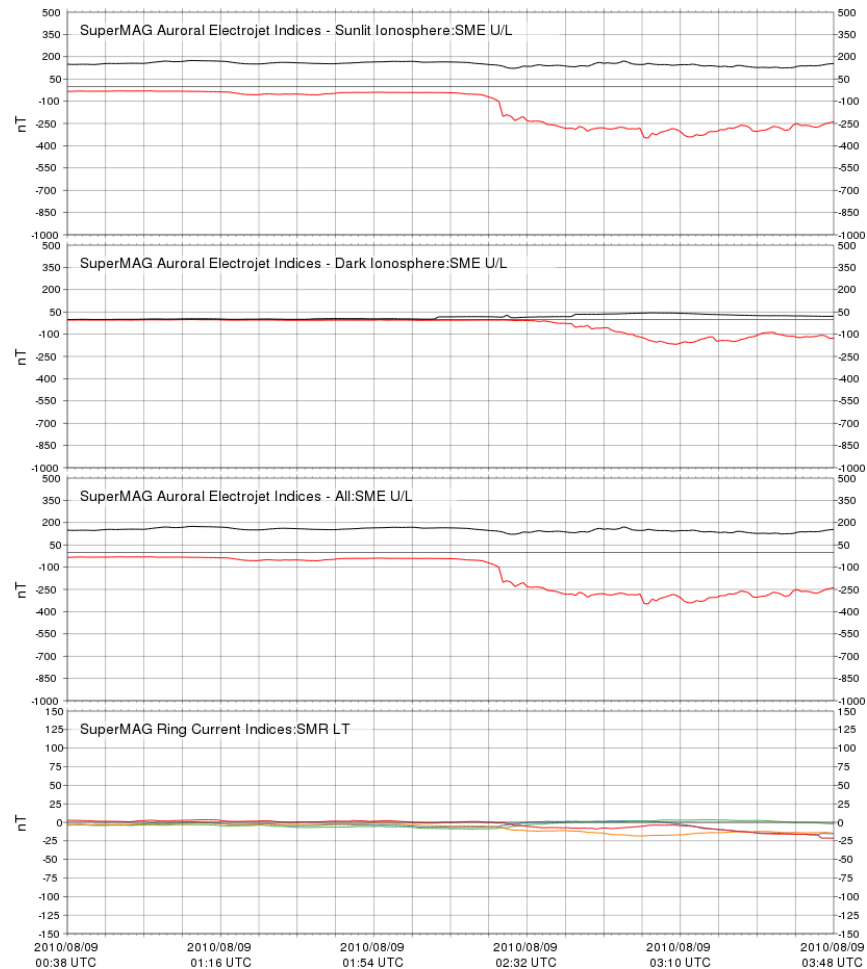
1. How do we derive global solutions from sparse data coverage?
2. What are the limitations of global solutions?
 - Derived parameters
 - Processes/phenomena
3. **The holy grail of M-I physics: Global, continuous and complete electrodynamic solutions.**



AMPERE-SuperMAG

AMPERE-SuperMAG substorm. - Non-storm conditions.

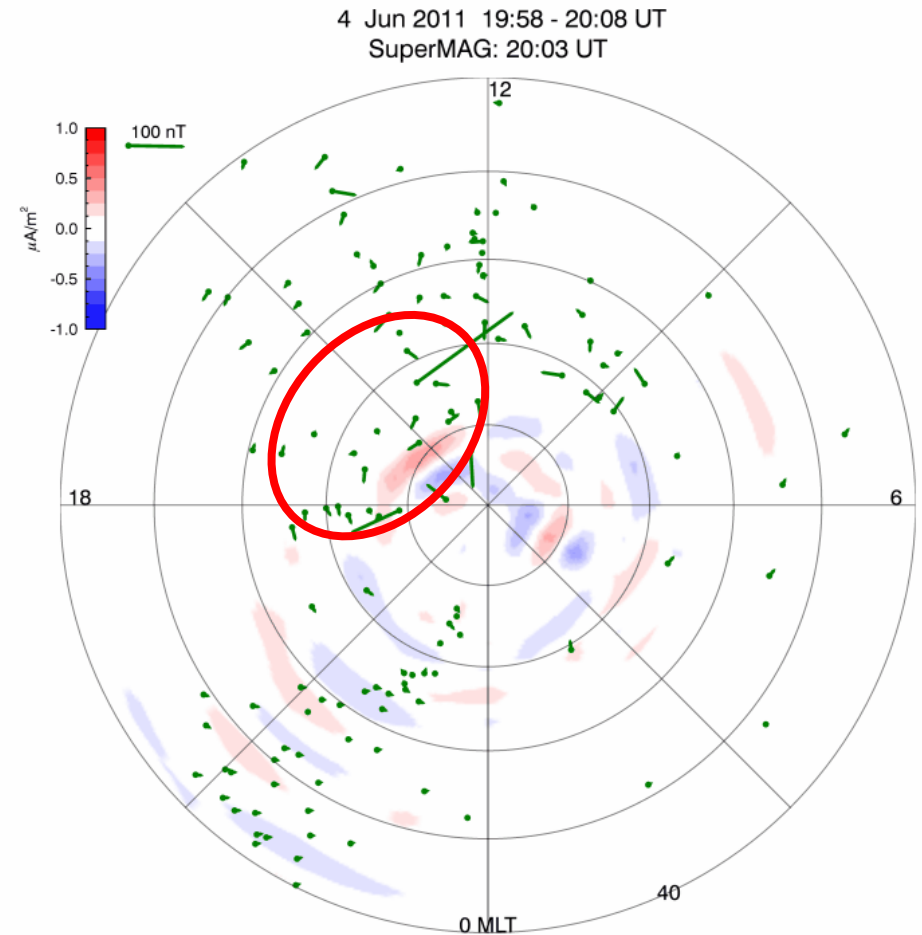
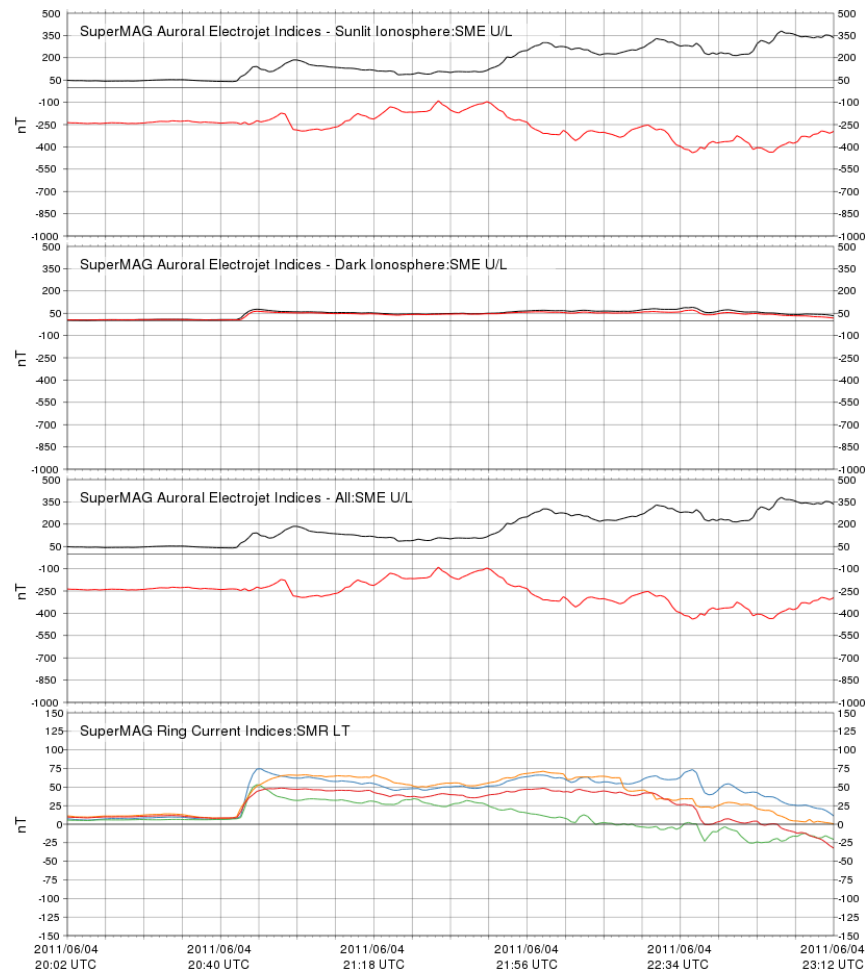
Special thanks to Cameron Olson (JHU/APL, Augsburg College)



AMPERE-SuperMAG

AMPERE-SuperMAG substorm. - Storm conditions.

Special thanks to Cameron Olson (JHU/APL, Augsburg College)



Magnetosphere-Ionosphere-Atmosphere-Coupling Project (MIAC)

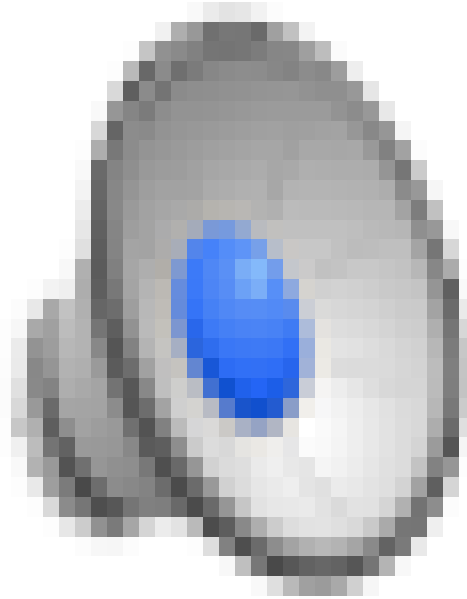
Challenges:

Difference in temporal resolution of datasets

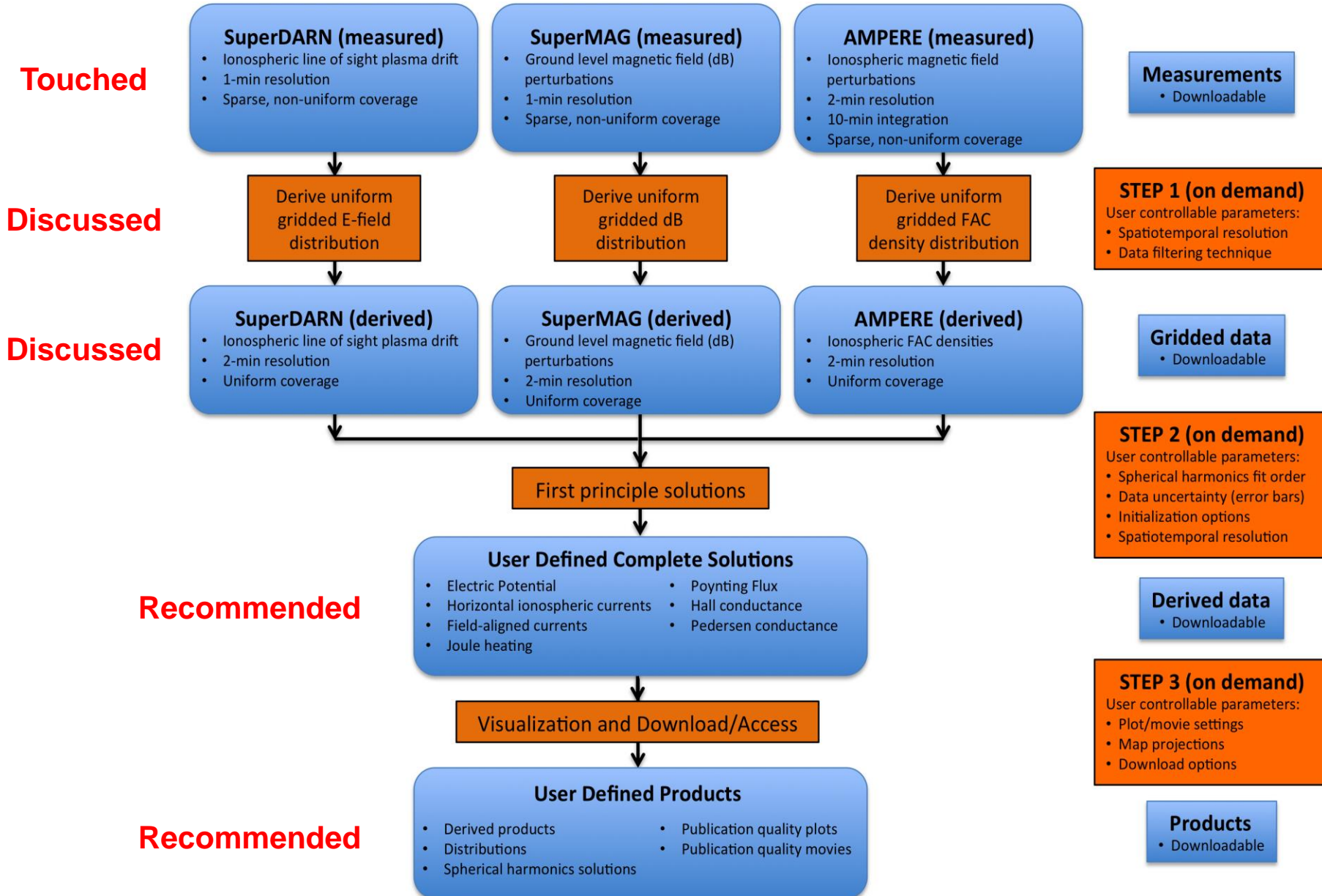
Non uniform spatial coverage

Measurement uncertainties and errors

Technique of deriving parameters from measurements



Magnetosphere-Ionosphere-Atmosphere-Coupling Project (MIAC)



Global, continuous and complete solutions: What have we learned?

Conclusions:

- **SuperMAG-SuperDARN-AMPERE allow complete-continuous-global first-principle solutions but:**
 - **measurements have inherent limitations**
 - **parameters derived from measurements use fundamental assumptions**
 - **difference in temporal resolution**
 - **difference in spatial coverage**
- The solutions will not (generally) allow studies of small to meso-scale processes.**

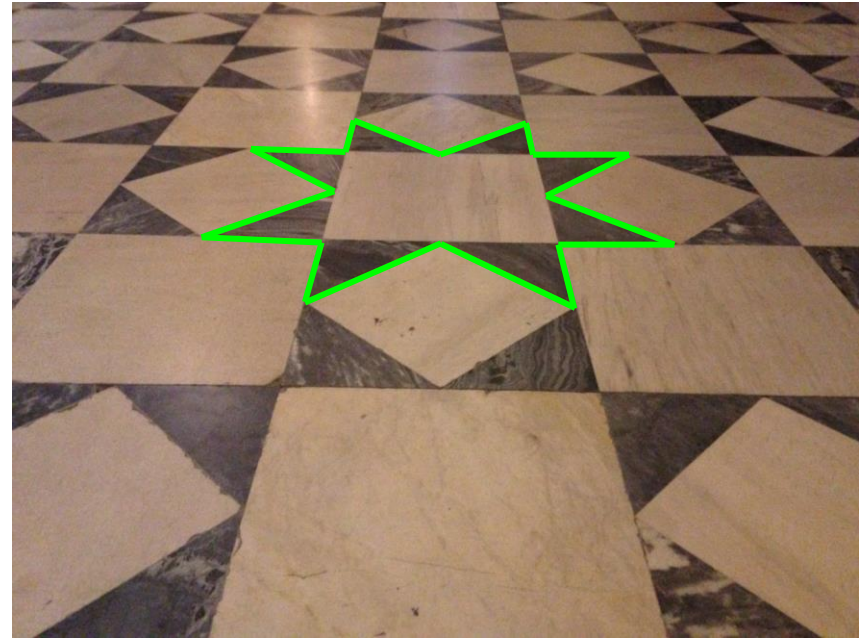
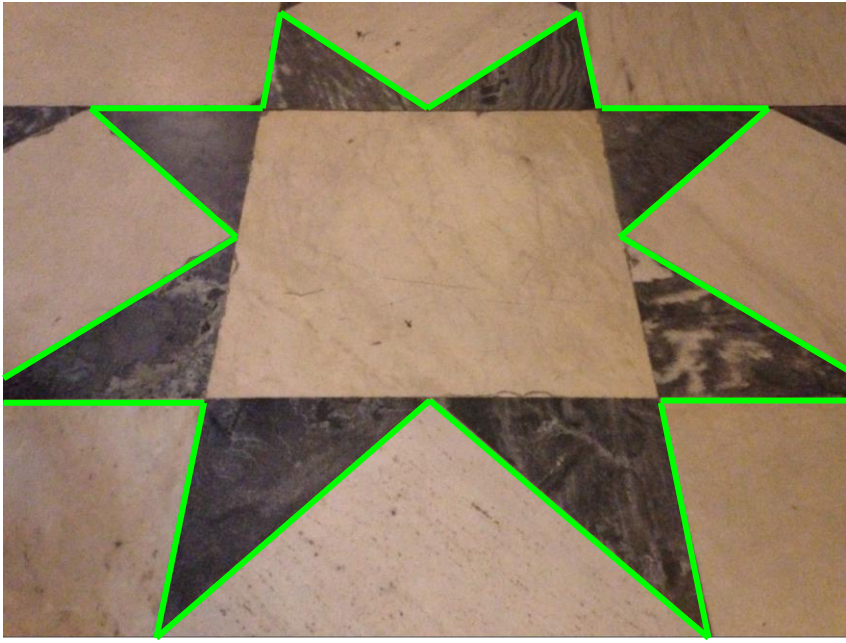
Recommendations:

- **Comprehensive objective validation of solutions is essential.**

Outline

1. How do we derive global solutions from sparse data coverage?
2. What are the limitations of the global solutions?
Derived parameters
Processes/phenomena
3. The holy grail of M-I physics: Global, continuous and complete electrodynamic solutions.
4. Bonus slide. 😊

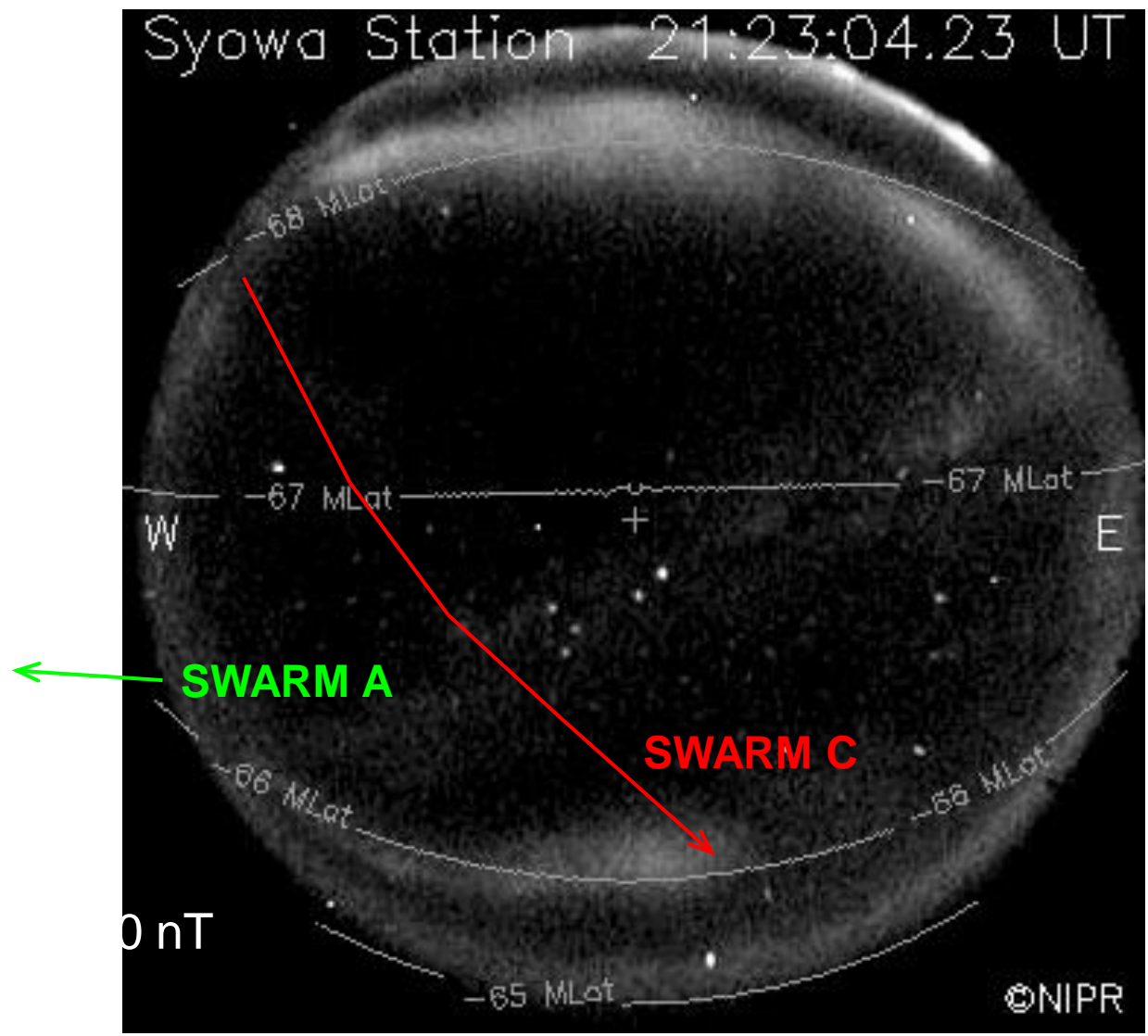
Drawing Conclusions From Local/Sparse Observations



Backup

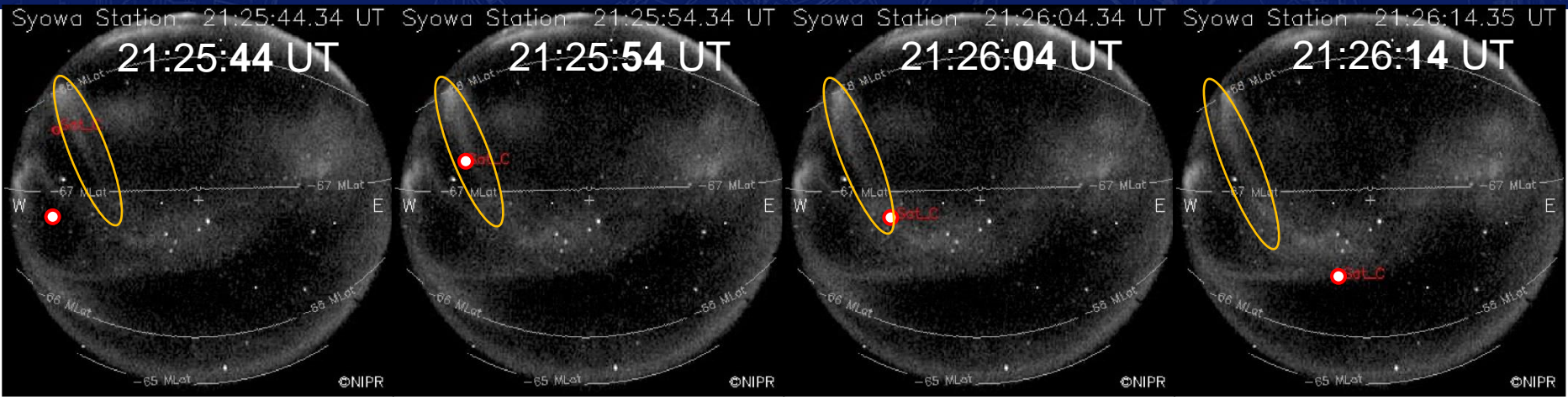
Calculating Birkeland Currents using ESA Swarm

Example on 3 May 2014



Calculating Birkeland Currents using ESA Swarm

Example on 3 May 2014



SWARM-C(MLT: 22:20)

Curlometer and single-SC results differs because FACs are structured along the SWARM orbit.

