



Figure 1: OH IR (0.9-1.7μm) all-sky airglow imager.

Analyzing Atmospheric Gravity Waves Over Antarctica and Visualizing Machine Learning Data

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Antarctic Gravity Wave Instrument Network (ANGWIN)

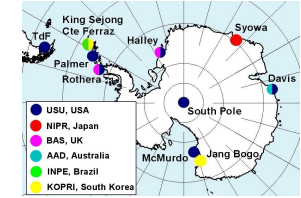


Figure 2: ANGWIN imager network map.

Introduction

Gravity Waves are buoyancy waves that propagate in the atmosphere [Matsuda et al., 2014]

- Mostly generated by tropospheric weather,
- Can vertically propagate above 100 km altitude,
- Affect the temperature structure of the atmosphere,
- Drive pole-to-pole circulation.

ANGWIN (Fig. 1 & 2)

- An international collaboration, investigates the upper atmosphere dynamics over a continent-size region, uses a network of all-sky imagers.

- Large data sets (~1M images per winter) → bottle neck.

Method

Use LightGBM Models to identify “clean” windows (Fig. 3)

- 2 hours of “clean” data,
- 3 minutes or less between each “clean” data point.

Compare window identification methods

- Manually identified windows vs. computationally identified,
- Window length, OH power (Fig. 6).

Algorithm used:

- Light Gradient Boosted Machine (LightGBM) [Ke et al., 2017],
- Fast but requires unique models for each station.
- Inspire by ML model used to sort Themis Aurora all sky imager data [Clausen et al., 2018]: “Clean” (0), “Obscured” (1).

Research goals:

- Compare validated Halley models’ findings,
- Compare short period gravity waves power over different Antarctic stations.

Compare filtered vs unfiltered computationally found windows

- Subtracted phase velocity spectrums (Fig. 5).

Process FFT spectrum analysis to study atmospheric gravity waves [Matsuda et al., 2014]

- Performed on “clean”, processed windows (Fig. 4),
- Generates gravity wave phase velocity spectrums.

Differences between windows

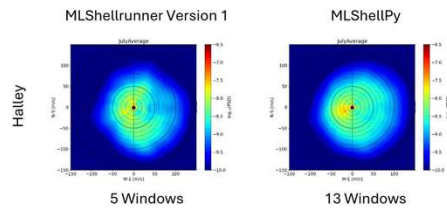


Figure 4: Monthly power spectrums processed with the clean windows found by MLShellrunner v1 (left) vs found by MLShellPy (right). The number and length of windows change across identification methods which affect monthly average phase velocity spectrums.

Image Processing

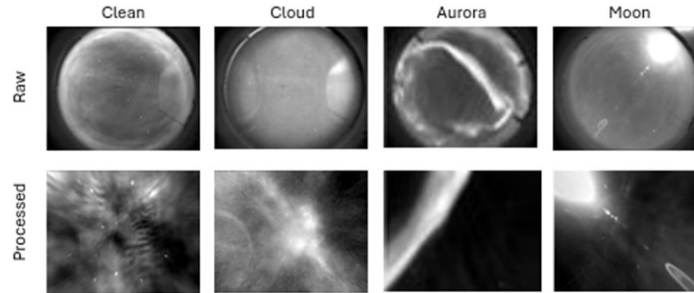


Figure 3: “Clean” windows are defined as free of excessive cloud, aurora, moon, or twilight contamination.

Subtracted phase velocity spectrums

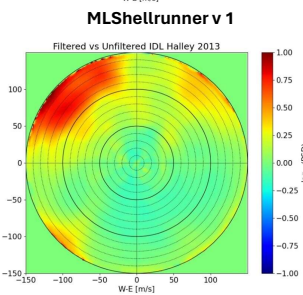
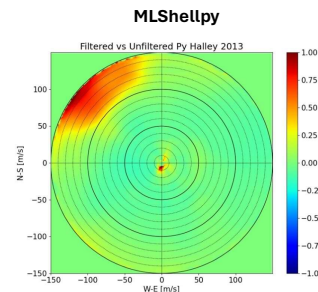


Figure 5: Difference between the monthly averaged phase velocity spectrums generated using manually verified “clean” windows and those using all windows found.

Results

Window selection method [Fig. 5]

- Windows flagged by MLShellPy contain less error around the edges than MLShellrunner Version 1, but the centers remain comparable.

Average power and window length [Fig. 6]

- Average power measured at Davis is approximately 4.6x larger than Halley’s and 4.8x larger than McMurdo’s,

- Station with the longest windows: Halley. Station with the most windows: McMurdo.

Phase Velocity Spectrum [Fig. 7]

- Power increases over the course of the winter for all the stations and directionality is very similar for McMurdo and Davis (~SW) during most of the winter. It varies for Halley from W to E, which was unexpected.

Window length and power station comparison 2013

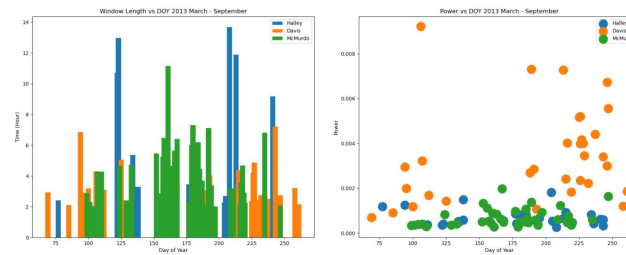


Figure 6 Comparison of average power and length of window between the Halley, Davis, and McMurdo stations. Windows gathered using MLShellrunner Version 1.

Phase velocity spectrum station comparison

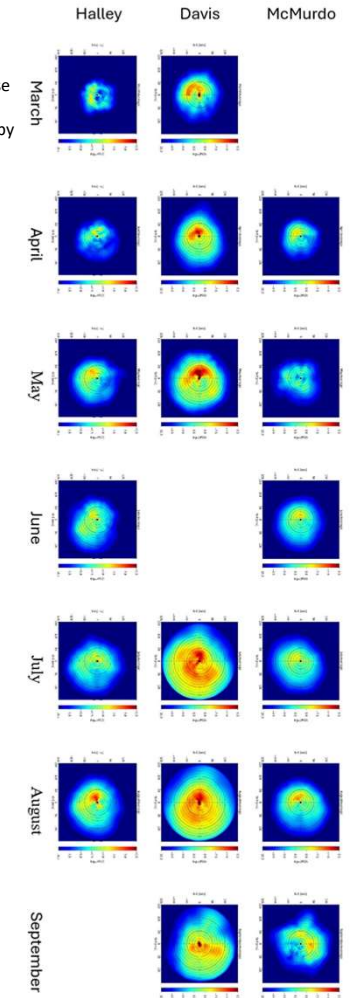


Figure 7: Monthly averaged phase velocity spectrums from Halley, Davis, and McMurdo generated by manually verified “clean” windows found by MLShellrunner Version 1 for an entire season.

References and Acknowledgments

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Conclusion

- Machine learning in ASI cleaning removes the bottle neck created by the large data set.
- Machine-identified windows and manually identified windows shows similar results.
- The number of clean windows correctly identified by the Halley model comparable to that of Davis and McMurdo.
- More “clean” windows may be found using MLShellPy window flagging algorithm as opposed to the original MLShellrunner version 1 algorithm.