. Introduction

- > The lonosphere-Thermosphere is a strongly driven dissipative system^[6].
- Solar and geomagnetic inputs to the I-T system are not fully observed and are not fully captured in physics-based models. This uncertainty in the model forcing can introduce significant errors^[6].
- \succ We examine a data assimilation approach that estimates corrections to the $F_{10.7}$ and Kp input parameters, with the aim of improved agreement between multiple model outputs and data sources.

2. Methods

- This study employs the Iterative Driver Estimation and Assimilation (IDEA)^[9] scheme, shown to the right. IDEA tests perturbations above and below an initial daily F_{107} value and 3 most recent 3hourly Kp values, then estimates the values that reduce model-data root-mean-square error (RMSE) the most.
- This technique provides sufficient time for the updated forcing to the model, without influence model's selfbreaking the consistent physics.
- We assimilate the logarithm of mass densities derived from the accelerometer aboard the ESA GOCE mission^[2] into the WAM-IPE^[1,8] and TIEGCM^[5] models.
- The evaluated time period is March 12-23, 2013, which includes the arrival of a geomagnetic storm on March 17 at roughly 0530 UTC.
- Assimilative and free-running model outputs are compared with the assimilated neutral data as well as the CEDAR Madrigal Database GNSS vertical TEC data^[3].





Performance Evaluation of a Data Assimilation Method Estimating the External Forcing of the I-T System

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3. Results Forcing Parameters **WAM-IPE** Neutral Density RMSE Mass RMSE Neutral Density ত 20 ab I TEC RMSE Assimilated) C WAM-IPE TEC RMSE Vertical (Not A

4. Findings & Discussion

a Even without data assimilation, both models give very accurate thermosphere mass densities in the quiet period before this particular geomagnetic storm, with RMSE values below 10%. **IDEA** reduces the mass density RMS errors for nearly all times with WAM-IPE, and under geomagnetic disturbances with TIEGCM. The mass density RMSE of TIEGCM during quiet conditions is largely unchanged. C The ionosphere TEC RMSE during quiet conditions shows negligible change with both models and fluctuates above and below the free-run values during disturbed conditions. This is likely because the forcing adjustments are made only to optimize the neutral mass density. **O** Deficiencies in cooling following storm conditions^[7] likely prompt IDEA to dramatically reduce the energy input of TIEGCM during the storm recovery. While this reduces the density error, the TEC RMSE increases significantly. Thermosphere mass density at a constant altitude varies both with the motion of pressure surfaces and with changes in composition due to vertical winds^[4]. Accelerometer density data alone does not contain information that allows the data assimilation engine to distinguish between these two mechanisms and adjust the model forcing accordingly. Adding data that contains composition information may increase the effectiveness of the data assimilation technique.

Start t_o:=0 hr t₁:=24 hr Run I-T Model Variations $(t_0 -> t_1)$ Solve Least Squares Eqns.: **Update Forcing** Converged? t₀:=t₀+3 hr t₁:=t₁+3 hr RMSE = $\left|\sum_{i}^{N} (model_{i} - data_{i})^{2}\right|$





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