

UNDERSTANDING DATA ASSIMILATION

APPLICATIONS TO HIGH-LATITUDE IONOSPHERIC ELECTRODYNAMICS

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What is data assimilation?

Combining Information

prior knowledge of the state of system

 x

empirical or physical models (e.g. physical laws)
complete in space and time

observations

 y

directly measured or retrieved quantities
incomplete in space and time

Bayes Theorem

- Bayesian statistics provides a coherent probabilistic framework for most of DA approaches [e.g., Lorenc, 1986]

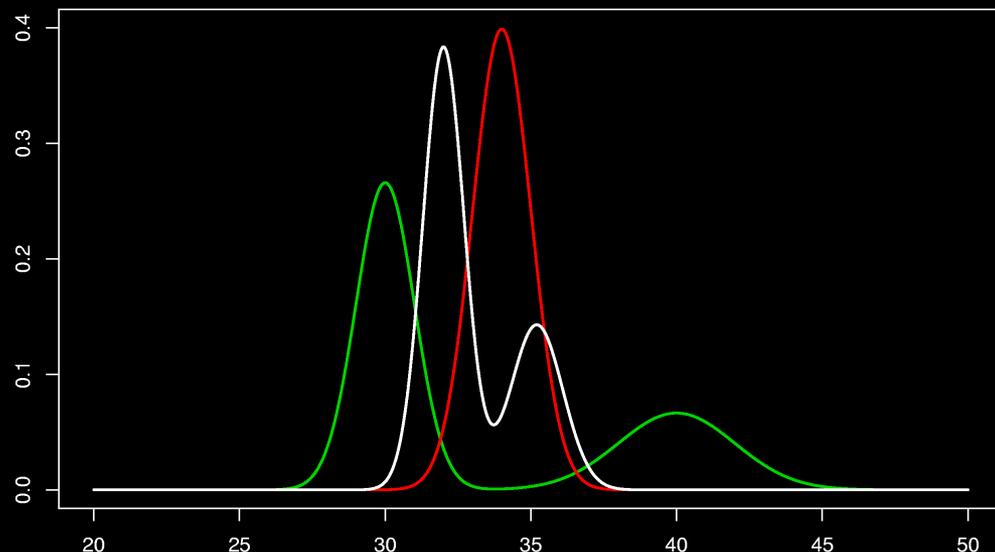
prior $p(\mathbf{x})$

observation likelihood $p(\mathbf{y}|\mathbf{x})$

probability distribution of y when x have a given value

posterior

$$p(\mathbf{x}|\mathbf{y}) \propto p(\mathbf{y}|\mathbf{x})p(\mathbf{x})$$



Bayes Theorem - Bayesian statistics provides a coherent probabilistic framework for most of DA approaches [e.g., Lorenc, 1986]

$$\text{prior} \quad p(\mathbf{x}) \sim \mathcal{N}(\mathbf{x}_b, \mathbf{P}_b) \quad \mathbf{x} = \mathbf{x}_b + \boldsymbol{\epsilon}_b$$

$$\text{observation likelihood} \quad p(\mathbf{y}|\mathbf{x}) \sim \mathcal{N}(\mathbf{H}\mathbf{x}, \mathbf{R}) \quad \mathbf{y} = \mathbf{H}\mathbf{x} + \boldsymbol{\epsilon}_y$$

probability distribution of y when x have a given value

posterior

$$p(\mathbf{x}|\mathbf{y}) \propto p(\mathbf{y}|\mathbf{x})p(\mathbf{x})$$

$$p(\mathbf{x}|\mathbf{y}) \sim \mathcal{N}(\mathbf{x}_a, \mathbf{P}_a) \quad \text{where}$$

$$\mathbf{x}_a = \mathbf{x}_b + \mathbf{K}(\mathbf{y} - \mathbf{H}\mathbf{x}_b)$$

$$\mathbf{P}_a = (\mathbf{I} - \mathbf{K}\mathbf{H})\mathbf{P}_b$$

$$\mathbf{K} = \mathbf{P}_b\mathbf{H}^T (\mathbf{H}\mathbf{P}_b\mathbf{H}^T + \mathbf{R})^{-1}$$

What is covariance? – two variables case

Bayes theorem

$$p(\mathbf{x}|\mathbf{y}) \propto p(\mathbf{y}|\mathbf{x})p(\mathbf{x})$$

prior

$$p(\mathbf{x}) \sim \mathcal{N}(\mathbf{x}_b, \mathbf{P}_b)$$

$$\mathbf{x}_b = \begin{pmatrix} 2.3 & 2.5 \end{pmatrix}$$

$$\mathbf{P}_b = \begin{pmatrix} 0.225 & 0.05 \\ 0.05 & 0.15 \end{pmatrix}$$

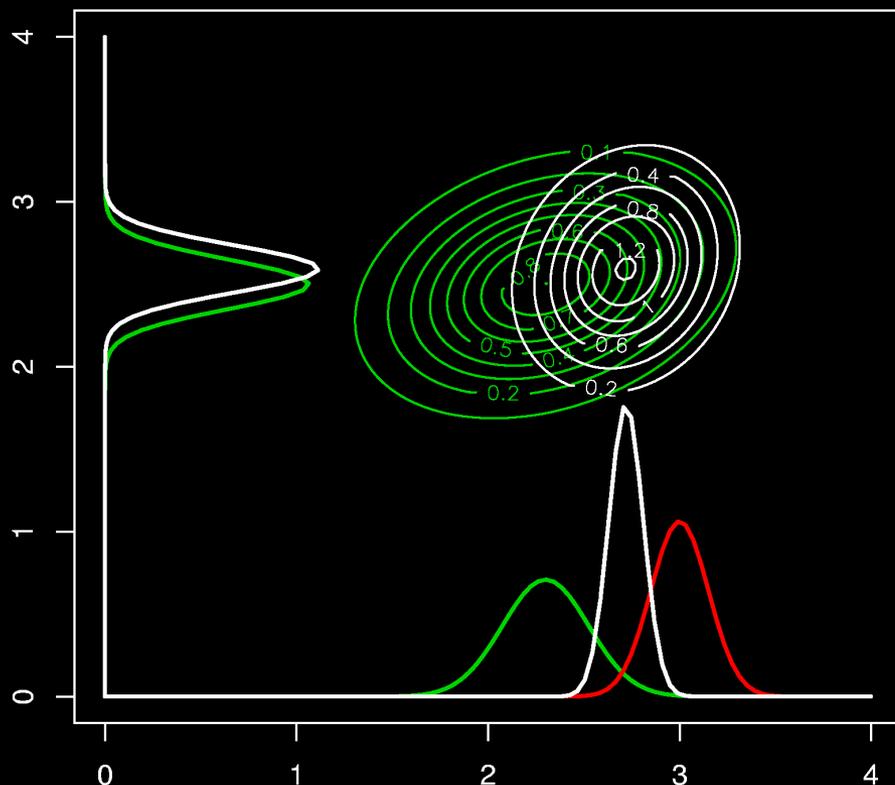
observation-likelihood

$$p(\mathbf{y}|\mathbf{x}) \sim \mathcal{N}(\mathbf{H}\mathbf{x}, \mathbf{R})$$

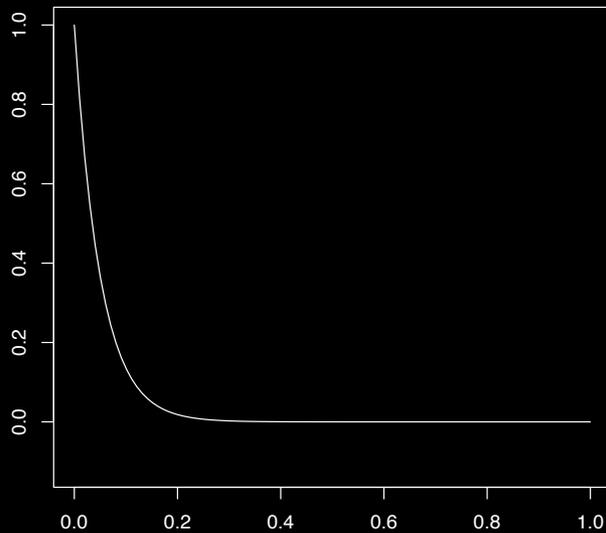
$$\mathbf{H} = \begin{pmatrix} 1 & 0 \end{pmatrix}$$

x_1 : *observed*

x_2 : *unobserved*

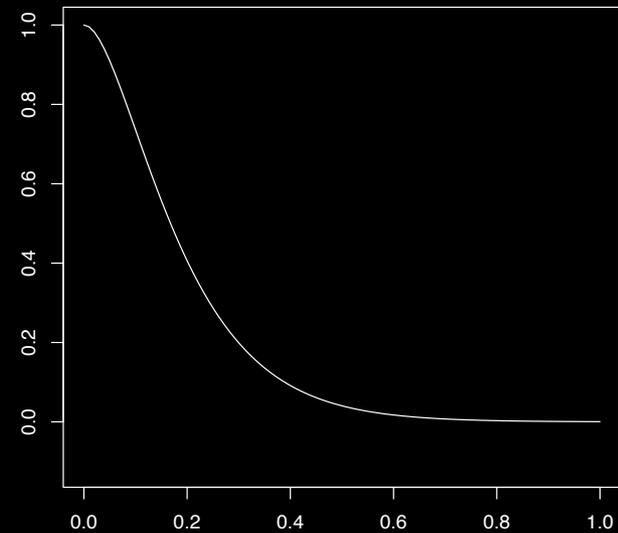


What is covariance? – in spatial sense



lag distance

$$\mathbf{P}_1(\mu = 0.5, \gamma = 0.05)$$

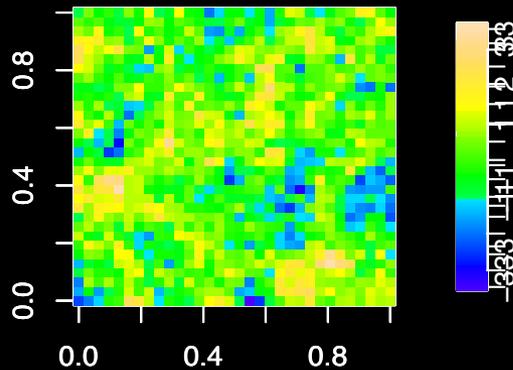


lag distance

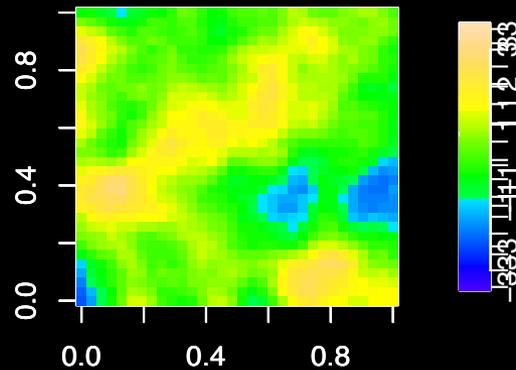
$$\mathbf{P}_2(\mu = 1.5, \gamma = 0.1)$$

What is covariance? – in spatial sense

$$\mathbf{x}_1 \sim \mathcal{N}(0, \mathbf{P}_1)$$



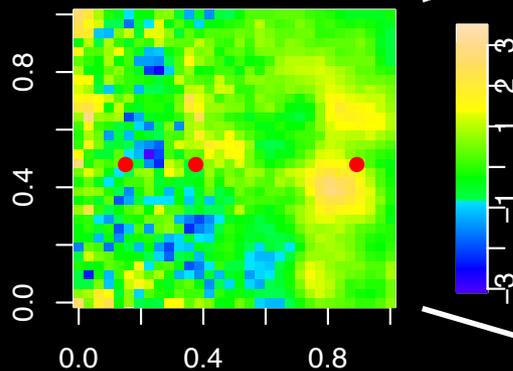
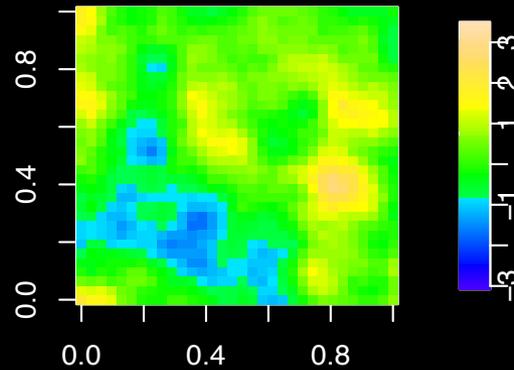
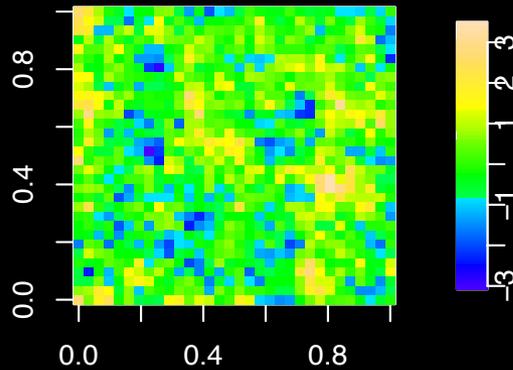
$$\mathbf{x}_2 \sim \mathcal{N}(0, \mathbf{P}_2)$$



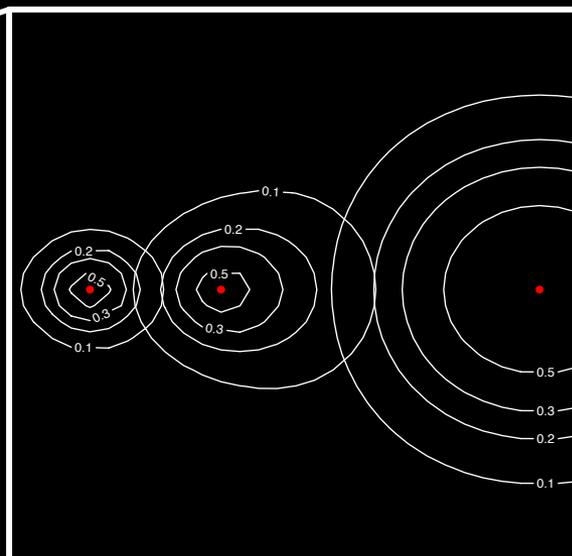
What is covariance? – in spatial sense

$$\mathbf{x}_1 \sim \mathcal{N}(0, \mathbf{P}_1)$$

$$\mathbf{x}_2 \sim \mathcal{N}(0, \mathbf{P}_2)$$



2-D Correlation Function



Assimilative Mapping of Ionospheric Electrodynamics

[Richmond and Kamide, 1988]

Inverse procedure to infer maps of

$$\vec{E}, \Phi, \vec{I}_{\perp}, \vec{J}_{\parallel}, \Delta\vec{B}$$

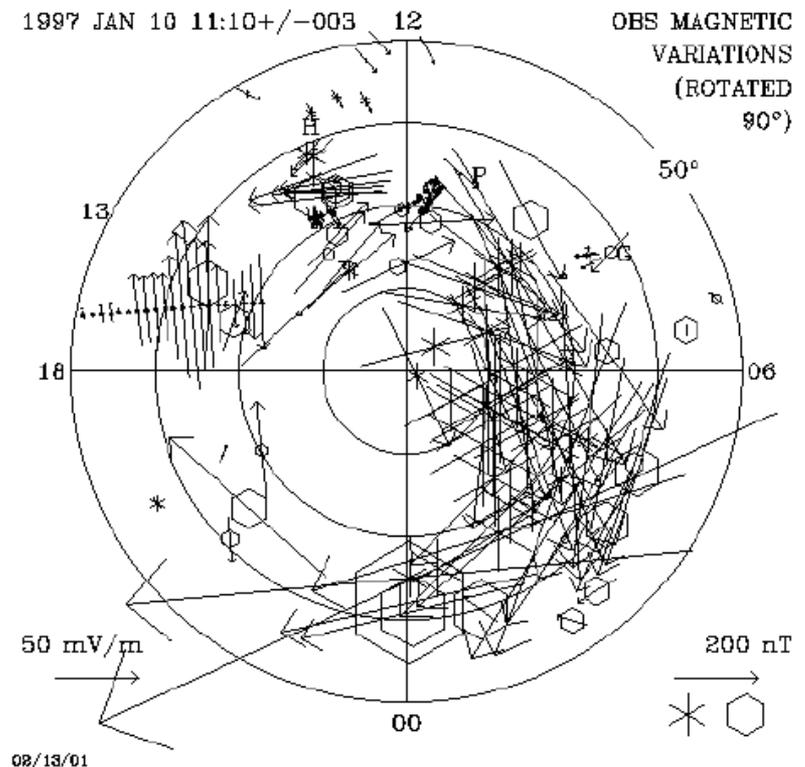
From observations of

\vec{E} IS or HF radar, Satellites

\vec{I}_{\perp} IS radar

\vec{J}_{\parallel} Satellite or ground-based magnetometers

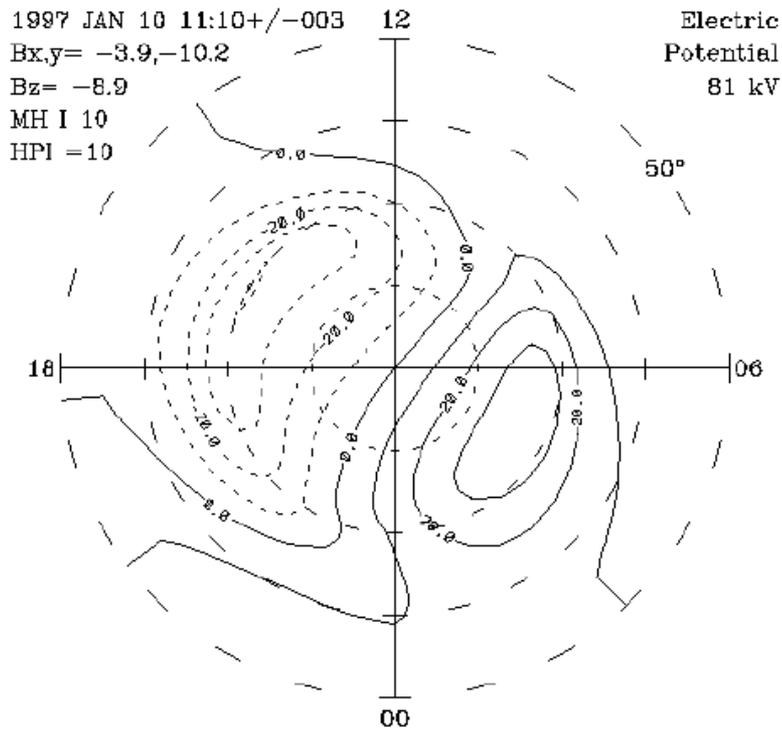
$\Delta\vec{B}$



Assimilative Mapping of Ionospheric Electrodynamics

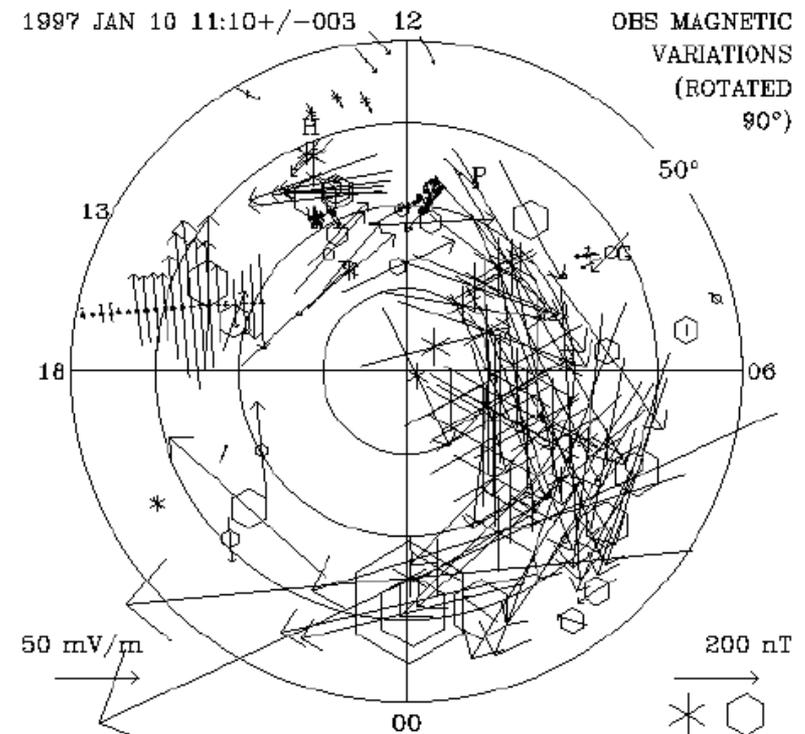
[Richmond and Kamide, 1988]

prior



02/13/01 (MODEL)
 CONTOUR PLOT -40.000 TO 30.000 INCREMENT OF 10.000 PLOTS, 31 7.1412

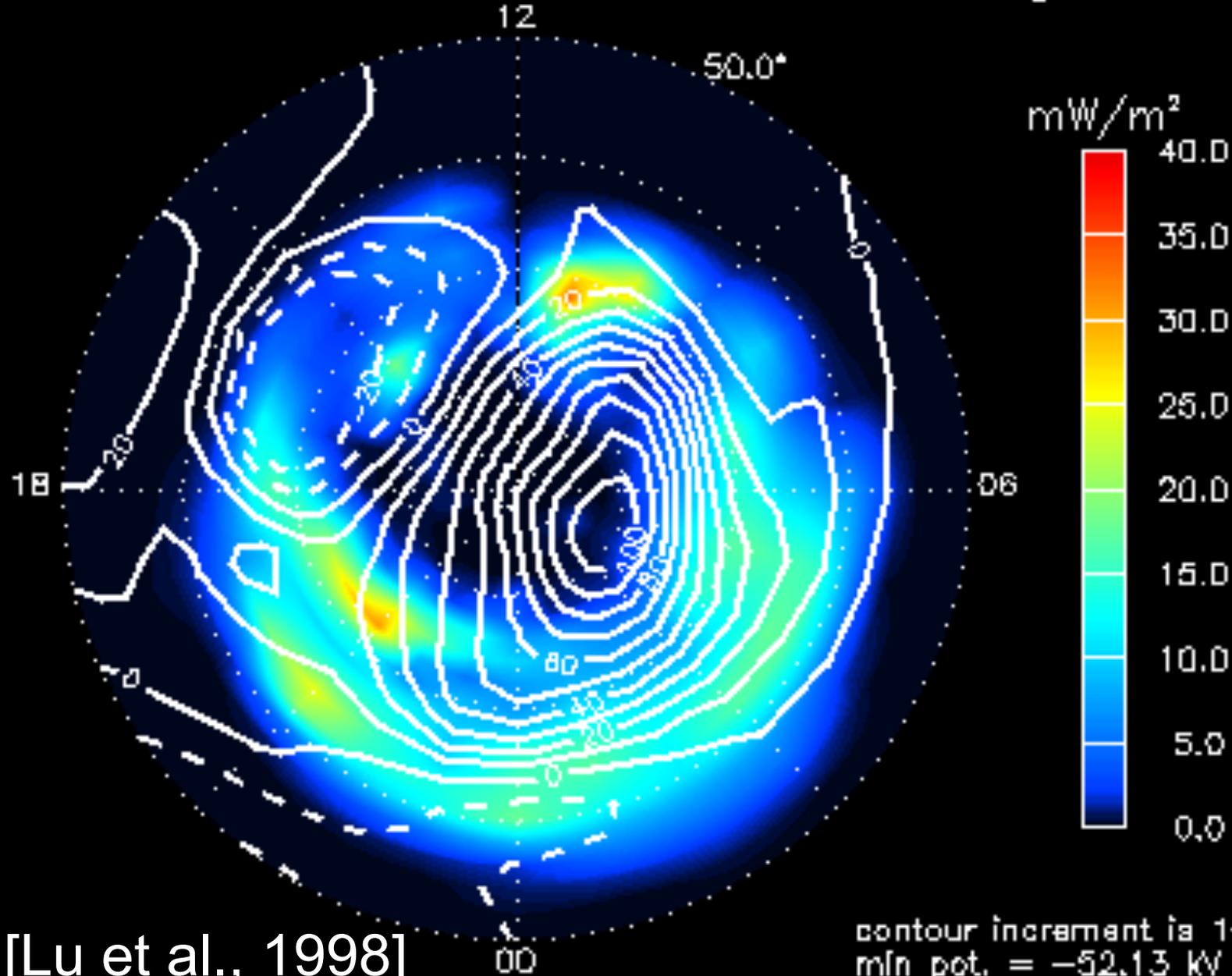
observations



02/13/01

Energy Flux (NH) with contours of Electric Potential

data averaged over ± 3 mins

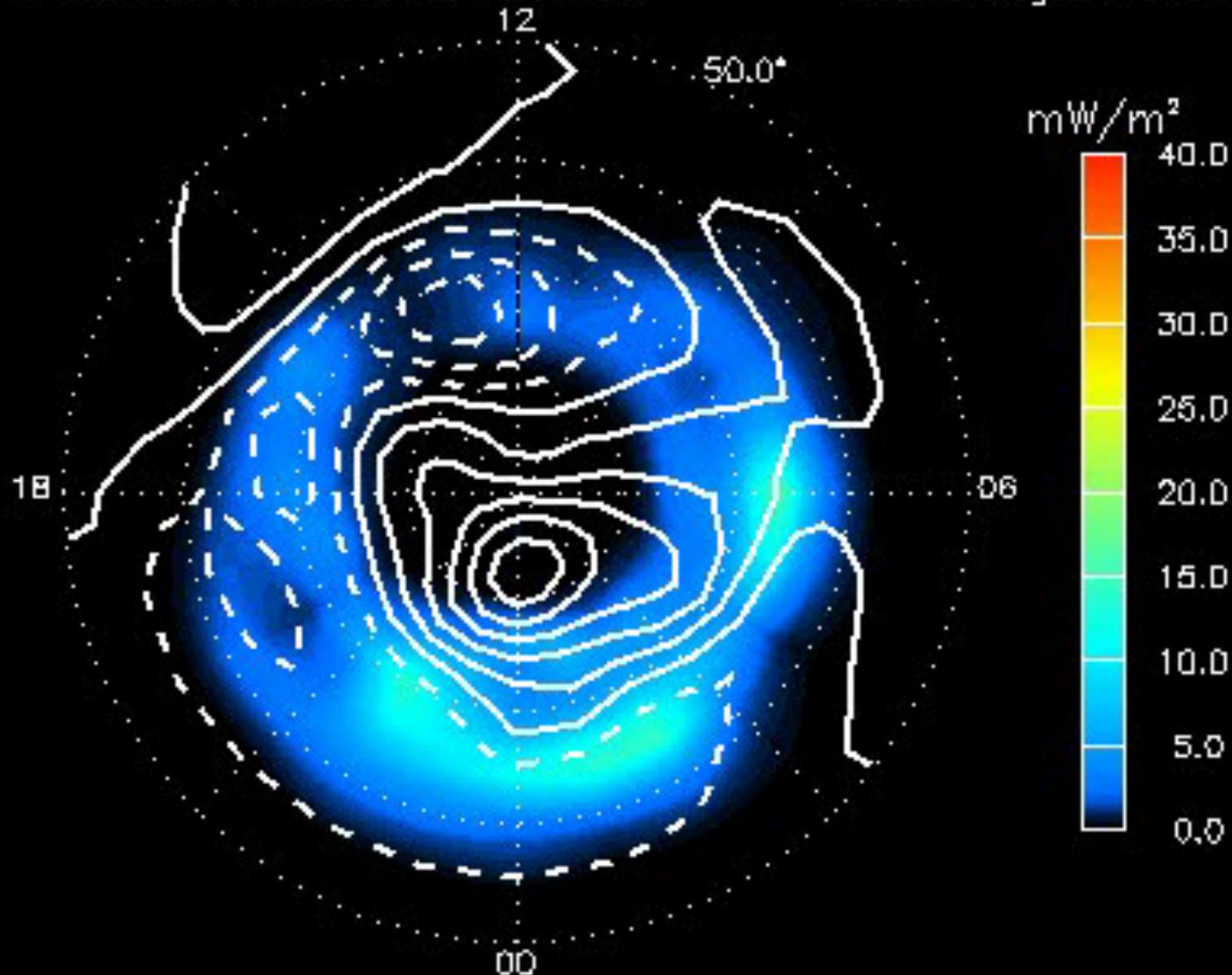


[Lu et al., 1998]

contour increment is 10.0 kV
min pot. = -52.13 kV
max pot. = 107.28 kV

Energy Flux (NH)
with contours of Electric Potential

97:01:10 07:00 UTC
data averaged over ± 3 mins



contour increment is 10.0 kV

AMIE – relationship among electromagnetic variables

Inverse procedure to infer maps of

$$\vec{E}, \Phi, \vec{I}_{\perp}, \vec{J}_{\parallel}, \Delta\vec{B}$$

From observations of

$$\vec{E} \quad \text{IS or HF radar, Satellites}$$

$$\vec{I}_{\perp} \quad \text{IS radar}$$

$$\vec{J}_{\parallel} \quad \text{Satellite or ground-based magnetometers}$$

$$\Delta\vec{B}$$

linear relationship (for a given $\underline{\underline{\Sigma}}$)

$$F(\vec{E}) = \Phi, \vec{I}_{\perp}, \vec{J}_{\parallel}, \Delta\vec{B}$$

$$\vec{E} = -\nabla\Phi$$

$$\vec{I}_{\perp} = \underline{\underline{\Sigma}} \cdot \vec{E}$$

$$\vec{J}_{\parallel} = \nabla \cdot \vec{I}_{\perp}$$

$$\vec{I}_{\perp}, \vec{J}_{\parallel} \longleftrightarrow \Delta\vec{B}$$

Biot-Savart's law

AMIE – basis functions as forward operator

functional analysis

$$\Phi = \Psi \mathbf{x}$$

Ψ : spherical harmonics

\mathbf{x} : coefficients

$$\vec{E} = -\nabla \Psi \mathbf{x}$$

forward operator

$$\mathbf{y} = \mathbf{H} \mathbf{x}$$

$$= F(-\nabla \Psi) \mathbf{x}$$

linear relationship (for a given $\underline{\underline{\Sigma}}$)

$$F(\vec{E}) = \Phi, \vec{I}_{\perp}, \vec{J}_{\parallel}, \Delta \vec{B}$$

$$\vec{E} = -\nabla \Phi$$

$$\vec{I}_{\perp} = \underline{\underline{\Sigma}} \cdot \vec{E}$$

$$\vec{J}_{\parallel} = \nabla \cdot \vec{I}_{\perp}$$

$$\vec{I}_{\perp}, \vec{J}_{\parallel} \longleftrightarrow \Delta \vec{B}$$

Biot-Savart's law

Ideas to improve AMIE: Adaptive covariance

$$\mathbf{x}_a = \mathbf{x}_b + \mathbf{K}(\mathbf{y} - \mathbf{H}\mathbf{x}_b)$$

$$\mathbf{K} = \mathbf{P}_b(\alpha)\mathbf{H}^T (\mathbf{H}\mathbf{P}_b(\alpha)\mathbf{H}^T + \mathbf{R})^{-1}$$

Maximum likelihood Method [Dee 1995, Matsuo et al., 2005]

$$\mathbf{d} = \mathbf{y} - \mathbf{H}\mathbf{x}_b$$

$$\mathbf{d} \sim \mathcal{N}(0, \mathbf{S})$$

$$\text{where } \mathbf{S}(\alpha) = \mathbf{R} + \mathbf{H}\mathbf{P}_b(\alpha)\mathbf{H}^T$$

Find alpha that maximizes the following pdf

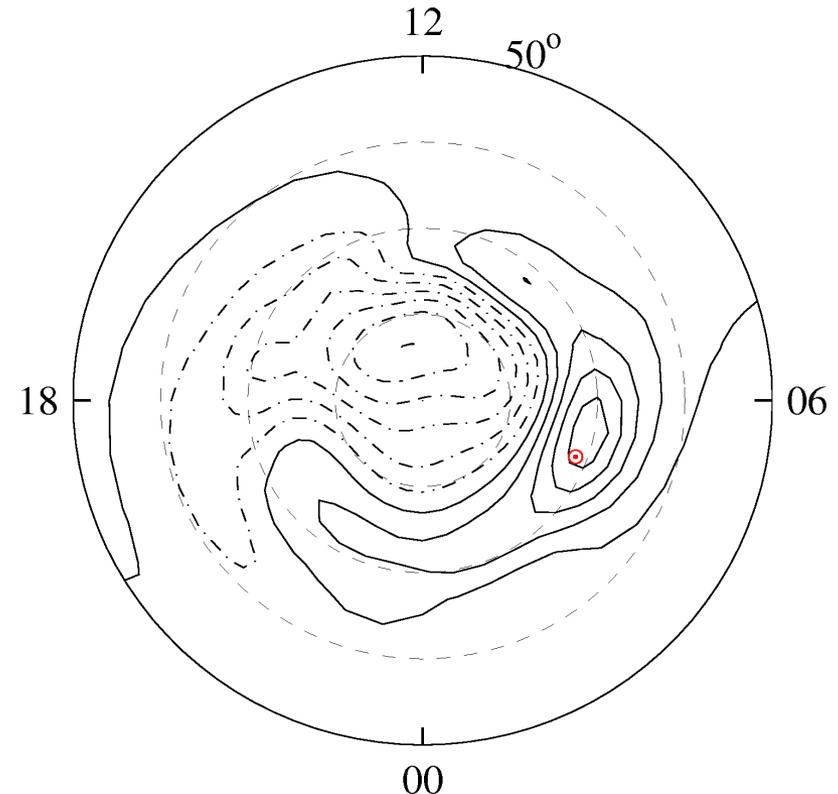
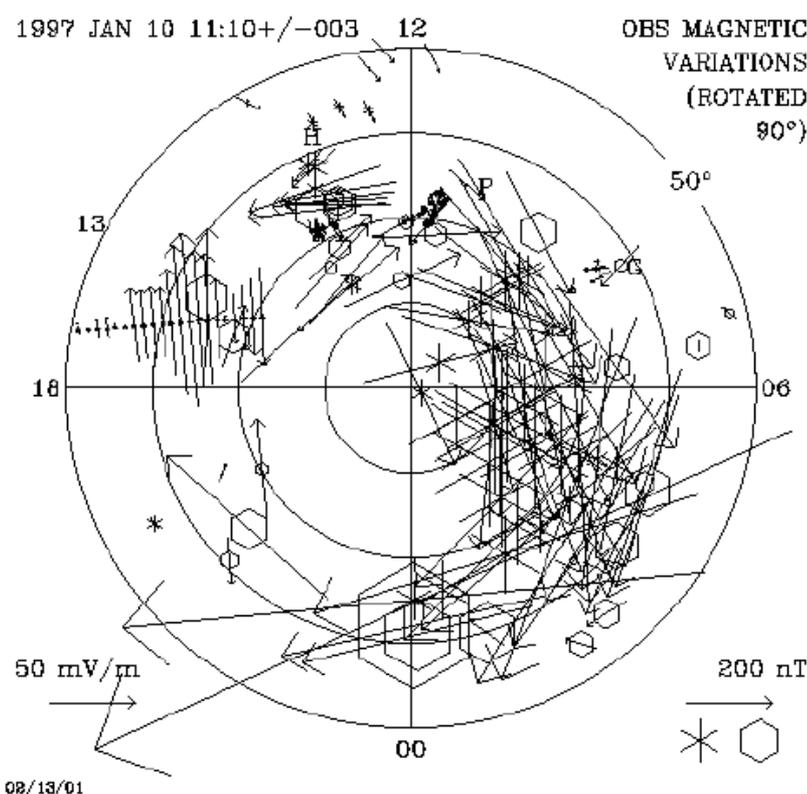
$$p(\mathbf{d}|\alpha) = \frac{1}{\sqrt{2\pi}^{\mathcal{J}} \sqrt{\det \mathbf{S}(\alpha)}} \exp \left[-\frac{\mathbf{d}^T \mathbf{S}^{-1}(\alpha) \mathbf{d}}{2} \right]$$

Ideas to improve AMIE: Adaptive covariance

$$\mathbf{x}_a = \mathbf{x}_b + \mathbf{K}(\mathbf{y} - \mathbf{H}\mathbf{x}_b)$$

$$\mathbf{K} = \underline{\mathbf{P}_b(\alpha)} \mathbf{H}^T (\mathbf{H} \mathbf{P}_b(\alpha) \mathbf{H}^T + \mathbf{R})^{-1}$$

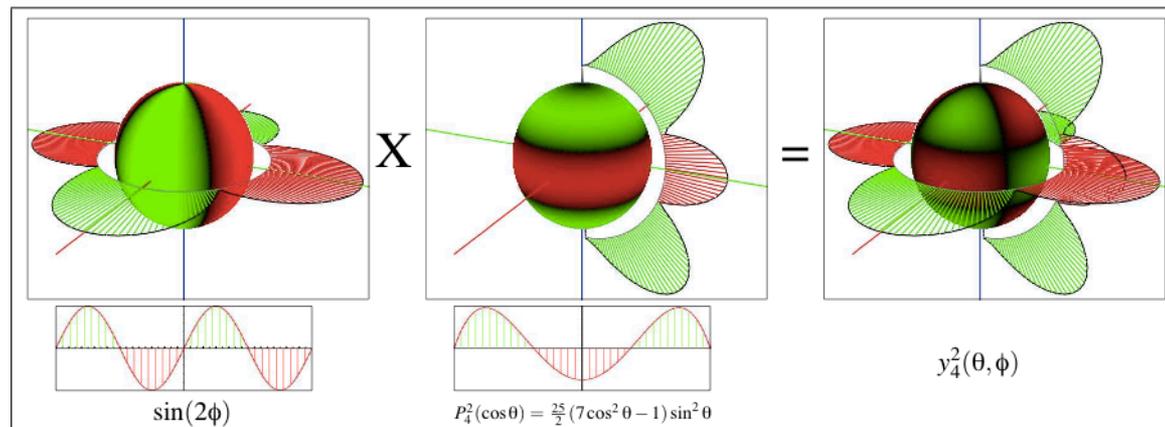
For given observations



Ideas to improve AMIE: Multi-resolution basis functions

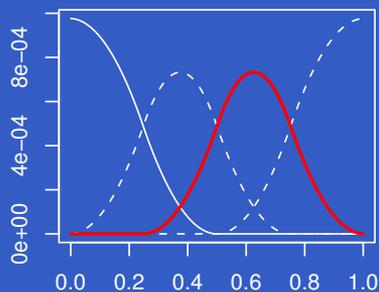
Spherical Harmonics

$$Y_l^m(\theta, \phi) = N_l^{|m|} P_l^{|m|}(\cos \theta) (\cos(m\phi) + i \sin(m\phi))$$

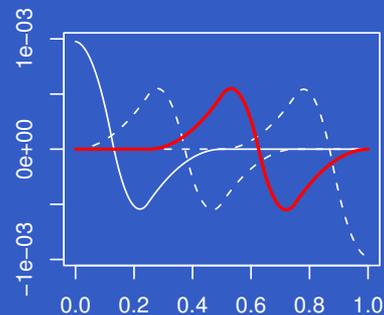


Wavelets

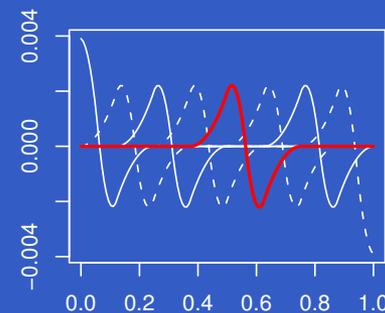
Father wavelet (scaling) functions



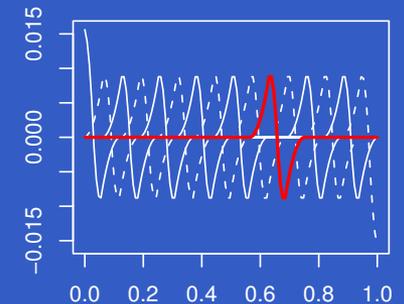
Mother wavelet functions



Mother wavelet functions



Mother wavelet functions



Ideas to improve AMIE: what to minimize $\Delta\mathbf{B}$ or \mathbf{E}

How to take advantage of new space-based observations?

Inverse procedure to infer maps of

$$\vec{E}, \Phi, \vec{I}_{\perp}, \vec{J}_{\parallel}, \Delta\vec{B}$$

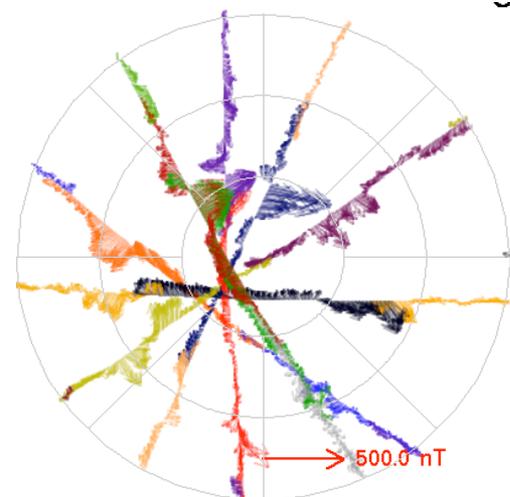
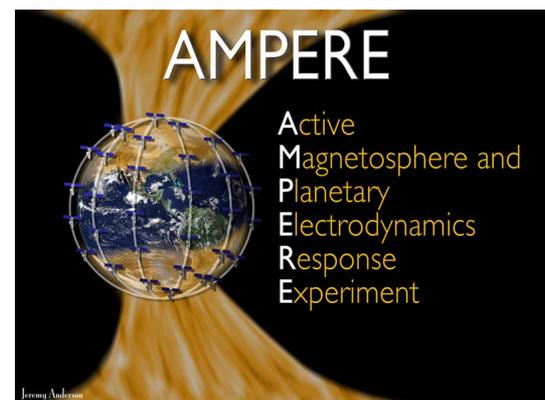
From observations of

\vec{E} IS or HF radar, Satellites

\vec{I}_{\perp} IS radar

\vec{J}_{\parallel} Satellite or ground-based magnetometers

$\Delta\vec{B}$



Summary

- Bayesian statistics as an overarching framework for many of DA methods
- Assumptions: Gaussian distribution, Linear H...
- Role of Covariance in spatial interpolation

- Applications to high-latitude electrodynamics (AMIE)
- Functional analysis of \mathbf{E} , Φ , \mathbf{I} , \mathbf{J} , $\Delta\mathbf{B}$
- Kalman update of spherical harmonics coefficients
- Current issues
 - Resolution: global function ->> compactly supported functions
 - New space-based magnetometer observations ->> \mathbf{E} or $\Delta\mathbf{B}$
 - Improve conductance models
 - Adaptive Covariance